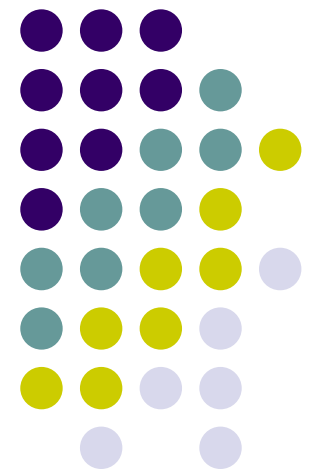


# PhD Training in Statistics

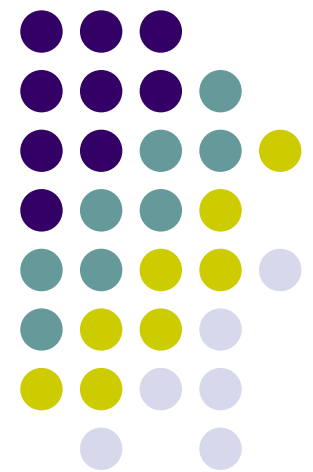
G.Wilquet

1. **Recall on probability**
2. **Special distributions**
3. **Recall on statistics**
4. **Sampling distributions**
5. **Hypothesis tests**
6. **Estimation**
7. **Maximum likelihood**
8. **Least squares**
9. **Confidence levels in pathological cases**
10. **Monte-Carlo simulation**



# I– Recall of general notions of probability theory

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# Basic axioms of the theory of probability



1/  $0 \leq P(x) \leq 1$       if  $x$  certainly true:  $P(x) = 1$   
if  $x$  certainly false:  $P(x) = 0$

2/ **Addition and exclusion**

$$P(x \cup y) = P(x) + P(y) - P(x \cap y)$$

if  $x$  and  $y$  are exclusif:  $P(x \cap y) = 0$

$$P(x \cup y) = P(x) + P(y)$$

3/ **Multiplication and independence**

$$P(x \cap y) = P(x) \times P(y | x) = P(y) \times P(x | y)$$

if  $x$  and  $y$  are independent:  $P(x | y) = P(x)$

$$P(y | x) = P(y)$$

$$P(x \cap y) = P(x) \times P(y)$$

# Density Probability Function (PDF)

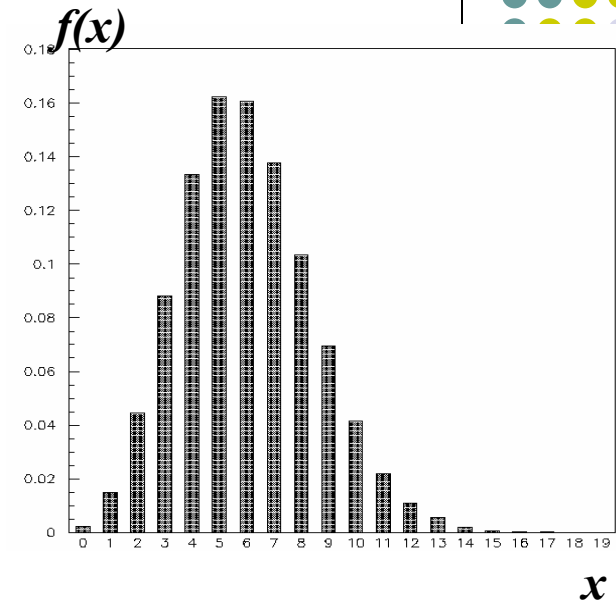


## Discrete variable

- $k$  possible values  $x_1, x_2, \dots, x_k$  for  $x$
- $p_i, i = 1, k$  the probability of occurrence of  $x_i$

$$f(x_i) = p_i \quad \sum_{i=1}^k p_i = 1$$

$$P(x_i \leq x < x_j) = \sum_{k=1}^j p_j$$

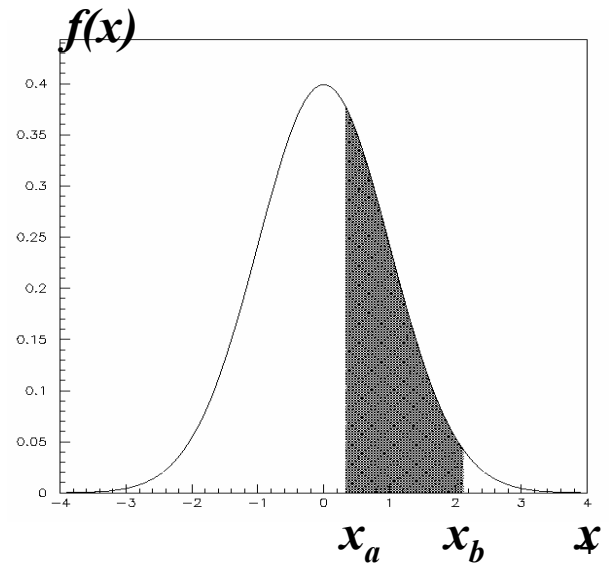


## Continuous variable

$$f(x_i) = \lim_{\Delta x \rightarrow 0} P(x_i \leq x < x_i + \Delta x) / \Delta x$$

$$f(x_i) dx = P([x_i, x_i + dx]) \quad \int_{-\infty}^{\infty} f(x) dx = 1$$

$$P(x_a \leq x < x_b) = \int_{x_a}^{x_b} f(x) dx$$



# Change of variable – conservation of probability



- $f(x)$

bijection  $y = y(x)$

$f'(y)$  ?

- Conservation of probability:

$$f(x) dx = f'(y) dy$$

$$f'(y) = f(x) \left| \frac{dx}{dy} \right|$$

- $n$  variables

$$f'(y_1, y_2, \dots, y_n) = |J| f(x_1, x_2, \dots, x_n)$$
$$J_{ij} = \frac{\partial x_i}{\partial y_j}$$

# Distribution Function

## Discrete variable

$$F(x_i) = \sum_{j=1}^i f(x_j) = \sum_{j=1}^i p_j \quad i = 1, n$$

## Continuous variable

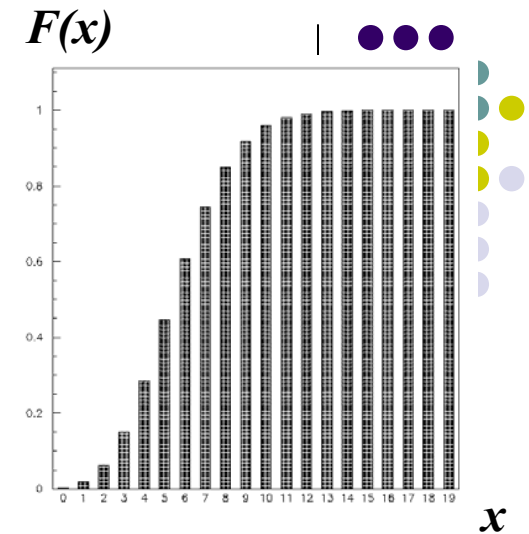
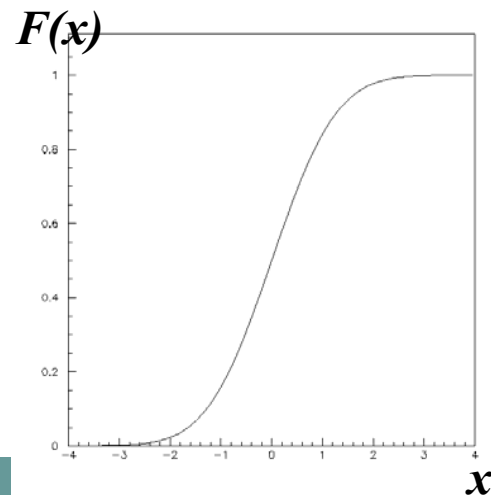
$$F(x) = \int_{-\infty}^x f(y) dy$$

$$dF(x) = f(x) dx$$

PDF of  $F(x)$  is uniform on  $[0,1]$

$$F(x) = \int_x^{\infty} f(y) dy \quad \text{or} \quad dF(x) = f(x) dx$$

$$PDF(F(x)) = f(x) \left| \frac{dx}{dF(x)} \right| = \frac{f(x) dx}{f(x) dx} \equiv 1$$



# Moments – Characteristic function



## Non-centred moments

$$\mu_k = E[x^k] = \int_{-\infty}^{\infty} x^k f(x) dx$$

$$\text{mean } \mu_1 = \mu = \int_{-\infty}^{\infty} x f(x) dx$$

## Centred moments

$$m_k = E[(x - \mu)^k] = \int_{-\infty}^{\infty} (x - \mu)^k f(x) dx$$

$$\text{variance } m_2 = \sigma^2 = \int_{-\infty}^{\infty} (x - \mu)^2 f(x) dx$$

$$\text{standard deviation : } \sigma = \sqrt{\sigma^2}$$

## Characteristic Function

Fourier transform of the PDF  
Expendable as a series of the moments

$$\phi(t) = \int_{-\infty}^{\infty} e^{itx} f(x) dx = \sum_{k=0}^{\infty} \frac{\mu_k (it)^k}{k!}$$

# Equivalence between $f(x)$ , $F(x)$ , $\phi(t)$ and $\mu_k$



**Equivalent information are provided by**

**density probability function**  $f(x)$

**distribution function**  $F(x)$   $f(x) = d_x F(x)$

**caractéristique function**  $\phi(t)$   $f(x) = \frac{1}{2\pi} \int_{-\infty}^{\infty} e^{-itx} \phi(t) dt$

**non-null moment**  $\mu_k$   $f(x) = \frac{1}{2\pi} \int_{-\infty}^{\infty} e^{-itx} \sum_{k=0}^{\infty} \frac{\mu_k (it)^k}{k!} dt$



## Join PDF of several variables – dependence and correlation



$$f(x_1, x_2, \dots, x_n) dx_1 dx_2 \dots dx_n = f(\underline{x}) d\underline{x} = P([\underline{x}, \underline{x} + d\underline{x}])$$

normalisation  $\int_{\Omega} f(\underline{x}) d\underline{x} = 1$

means  $\mu_i = E[x_i]$

variances  $\sigma_i^2 = E[(x_i - \mu_i)^2]$

covariances  $\sigma_{ij} = E[(x_i - \mu_i)(x_j - \mu_j)] = E[x_i \cdot x_j] - E[x_i] E[x_j]$

correlation coefficient

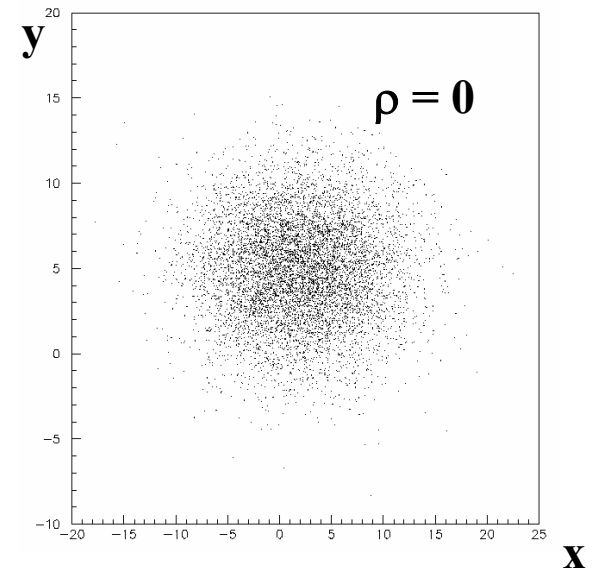
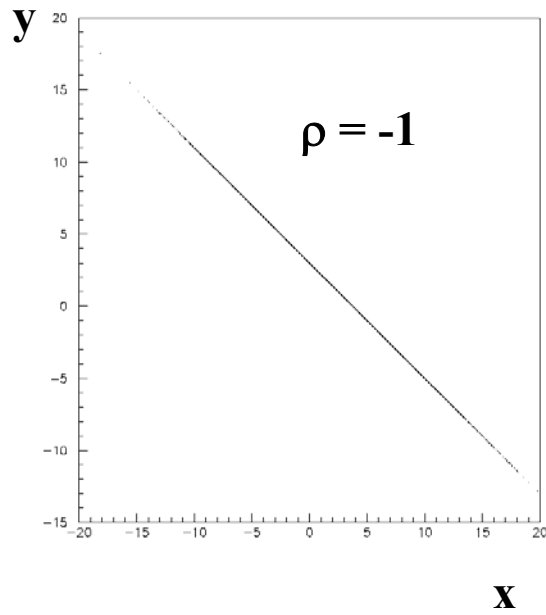
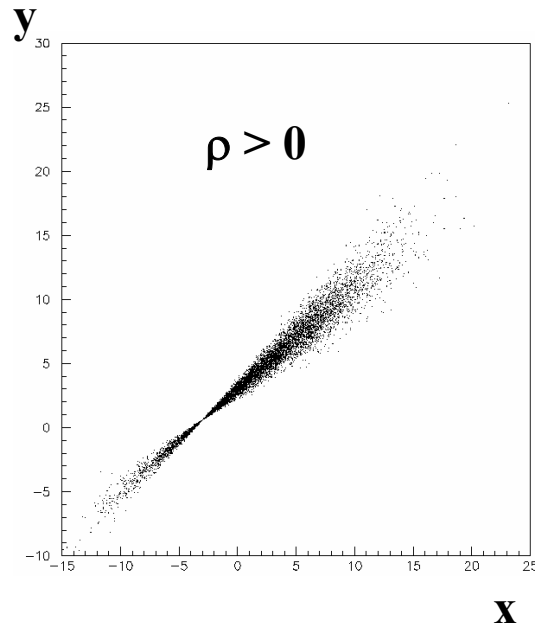
$$\rho_{ij} = \frac{\sigma_{ij}}{\sigma_i \sigma_j} = \frac{E[(x_i - \mu_i)(x_j - \mu_j)]}{\sqrt{E[(x_i - \mu_i)^2] E[(x_j - \mu_j)^2]}}$$

independence between variables  $x_i$  and  $x_j$

factorisation  $f(\underline{x}) = f_i(x_i, \dots, x_{k \neq j}) \cdot f_j(x_j, \dots, x_{k \neq i})$

$$\Rightarrow E[x_i \cdot x_j] = E[x_i] E[x_j] \Rightarrow \sigma_{ij} = \rho = 0$$

# Correlation coefficient



# Marginal and conditional PDF of several variables



- **Marginal : projections of  $f(x_1, x_2)$  on  $x_1$  and  $x_2$**

$$h_1(x_1) = \int_{-\infty}^{\infty} f(x_1, x_2) dx_2 \quad \text{and} \quad h_2(x_2) = \int_{-\infty}^{\infty} f(x_1, x_2) dx_1$$

if  $x_1$  and  $x_2$  are independent:  $f(x_1, x_2) = f_1(x_1) f_2(x_2) \Rightarrow h_i(x_i) \equiv f(x_i)$

- **Conditional : PDF of  $x_1$  for a given value  $x_2 = x_2^0$  and conversaly**

$$g_1(x_1 | x_2 = x_2^0) = \frac{f(x_1, x_2^0)}{h_2(x_2^0)} \quad \text{and} \quad g_2(x_2 | x_1 = x_1^0) = \frac{f(x_1^0, x_2)}{h_1(x_1^0)}$$

- **if  $x_1$  and  $x_2$  are independent :  $f(x_1, x_2) = f_1(x_1) f_2(x_2)$  et  $h_i(x_i) \equiv f_i(x_i)$**

$$\Rightarrow g_1(x_1 | x_2 = x_2^0) \equiv f_1(x_1) \equiv h_1(x_1)$$

$$\Rightarrow g_2(x_2 | x_1 = x_1^0) \equiv f_2(x_2) \equiv h_2(x_2)$$

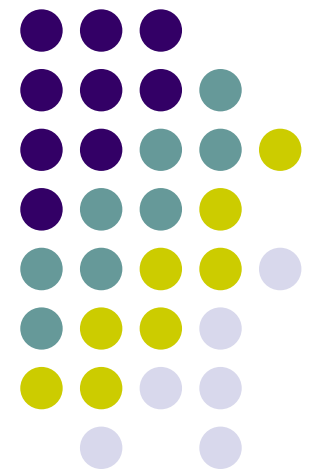
# II – Special Distributions

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**Bernoulli process: binomial et multinomial**

**Poisson process: Poisson, exponential**

**Gauss process: gaussian or normal**



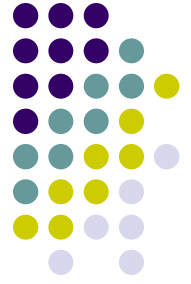
# Bernoulli process

## Multinomial PDF

- $k$  possible results
- Result  $i$  occurs with a probability  $p_i$   $\sum_{i=1}^k p_i = 1$
- Probability to observe  $\underline{r} = r_1, r_2, \dots, r_k$  results of type 1, 2, ...,  $k$  on a total of  $n = \sum_{i=1}^k r_i$  trials

$$f(\underline{r} | \underline{p}, n) = \frac{n!}{\prod_{i=1}^k r_i!} \prod_{i=1}^k p_i^{r_i}$$

- Mean  $\mu_i = n p_i$
- Variance  $\sigma_i^2 = n p_i (1 - p_i)$
- Covariance  $\sigma_{ij} = -n p_i p_j$



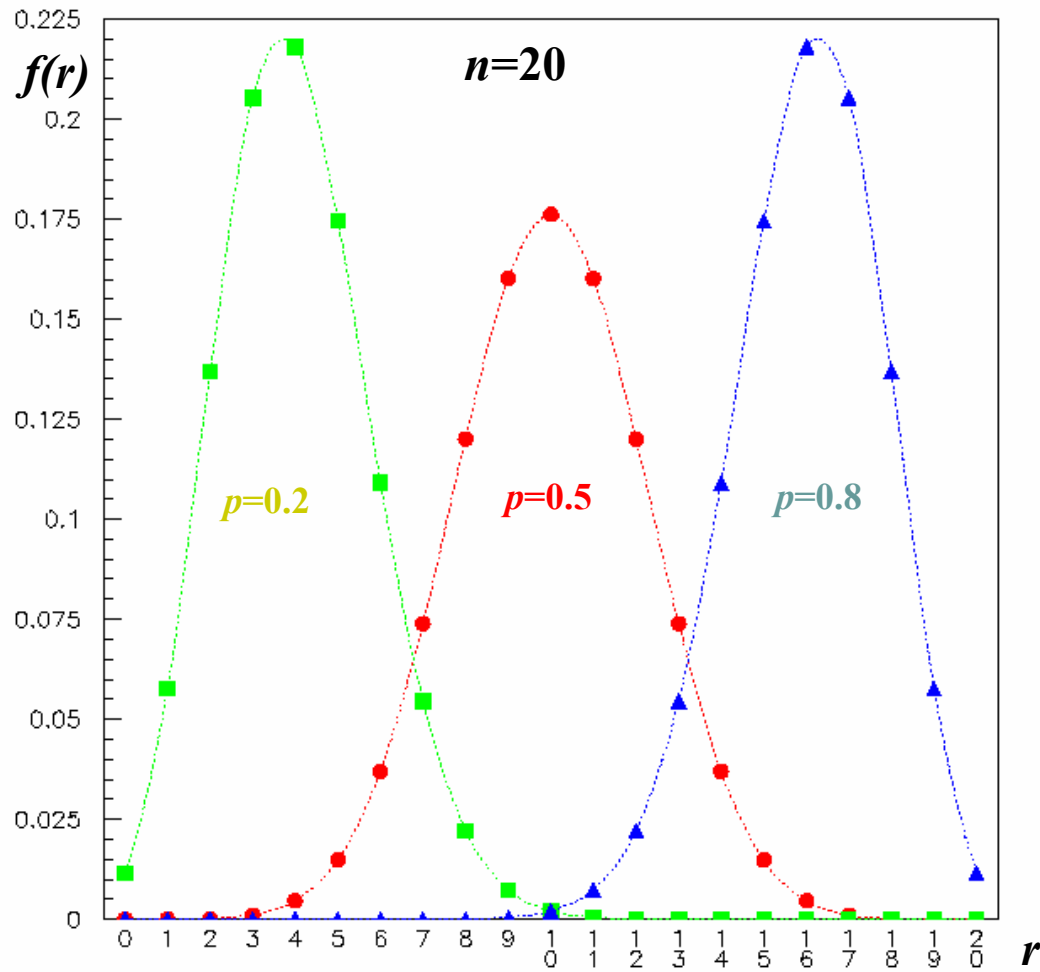
## Binomial PDF

- Probability to observe  $r_1 = r$  successes that have probability  $p_1 = p$  and  $r_2 = n - r$  failures that have probability  $p_2 = 1 - p$

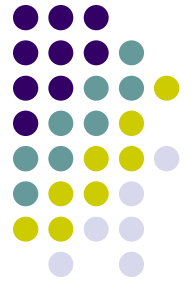
$$f(r | p, n) = \frac{n!}{r! (n-r)!} p^r (1-p)^{n-r}$$

- $\rho = -1$

# Binomial PDF



# Poisson process



## Defining properties of the Poisson PDF

Process occurs or not on a small interval  $\Delta x$  : 0 or 1 success

$$P_1([x, x + \Delta x]) = \Delta x / \beta$$

$$P_0([x, x + \Delta x]) = 1 - \Delta x / \beta$$

- do not depend on  $x$

$\beta$  mean interval between two successes

$1/\beta$  density of succes per unitinterval

## Poisson PDF as the limit of the binomial PDF

$$n \rightarrow \infty$$

$$p \rightarrow 0$$

$$np \rightarrow \mu \text{ finate}$$

$$\lim_{n \rightarrow \infty} n! = \sqrt{2\pi n} n^n e^{-n}$$

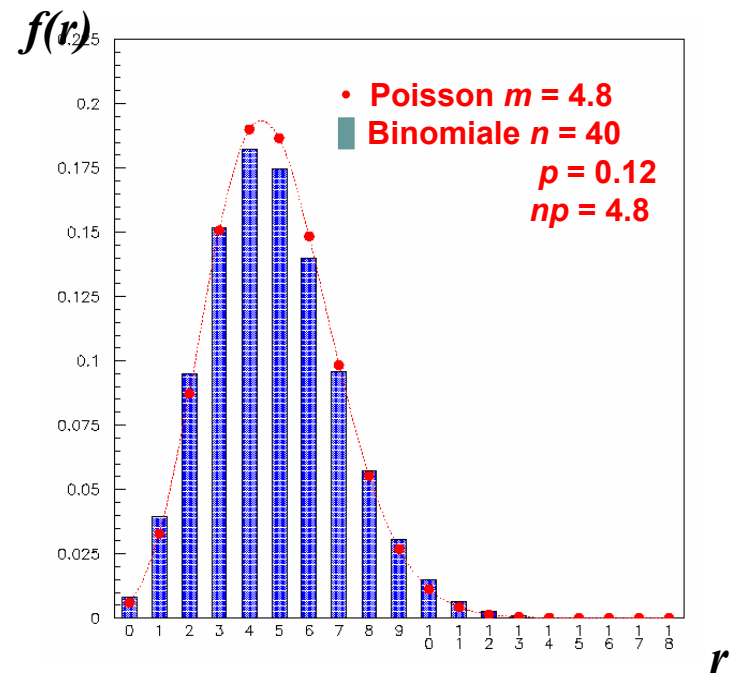
# Poisson Distribution



- Probability of occurrence of  $r$  (integer) successes on an interval  $x$  given a mean number of successes  $\mu$  (real)  $\mu = \frac{x}{\beta}$

$$f(r | \mu) = \frac{1}{r!} \mu^r e^{-\mu}$$

- Mean  $\mu$
- Variance  $\sigma^2 = \lim_{p \rightarrow 0} np(1 - p) = np = \mu$





# Poisson Distribution : demonstration of the PDF



$$P_0(\Delta x) = 1 - P_1(\Delta x) = 1 - \frac{\Delta x}{\beta}$$

$$P_0(x + \Delta x) = P_0(x) \times P_0(\Delta x) = P_0(x) - \frac{\Delta x}{\beta} P_0(x)$$

$$\frac{P_0(x + \Delta x) - P_0(x)}{\Delta x} = -\frac{1}{\beta} P_0(x)$$

$$\left. \begin{array}{l} \frac{dP_0(x)}{dx} = -\frac{1}{\beta} P_0(x) \\ P_0(0) = 1 \end{array} \right\} \rightarrow P_0(x) = e^{-x/\beta}$$

$$P_r(x + \Delta x) = P_{r-1}(x) \times P_1(\Delta x) + P_r(x) \times P_0(\Delta x) = P_{r-1}(x) \frac{\Delta x}{\beta} + P_r(x) \left(1 - \frac{\Delta x}{\beta}\right)$$

$$\frac{P_r(x + \Delta x) - P_r(x)}{\Delta x} = -\frac{1}{\beta} (P_r(x) - P_{r-1}(x))$$

$$\left. \begin{array}{l} \frac{dP_r(x)}{dx} = -\frac{1}{\beta} (P_r(x) - P_{r-1}(x)) \\ P_0(x) = e^{-x/\beta} \end{array} \right\} \rightarrow P_r(x) = \frac{1}{r!} \left(\frac{x}{\beta}\right)^r e^{-x/\beta}$$

$$P_r(x) = f(r | \mu) = \frac{1}{r!} \mu^r e^{-\mu} \quad \text{avec } \mu = \frac{x}{\beta}$$

# Exponential Distribution



Poissonian process

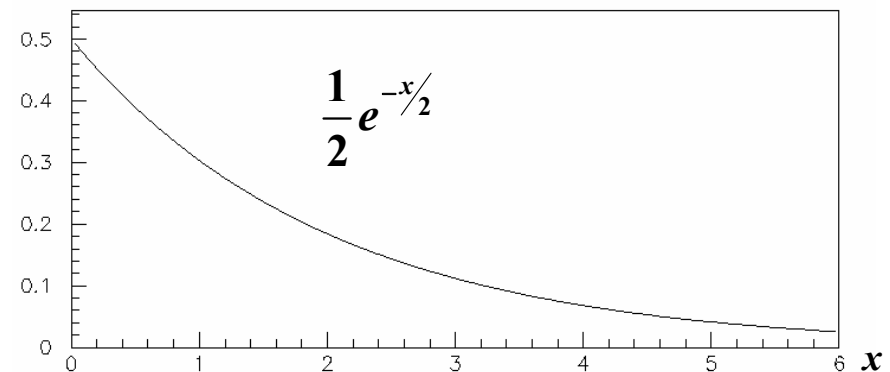
$\beta$  = average interval between two successes

Probability of a first succès on interval  $[x, x + dx]$ .

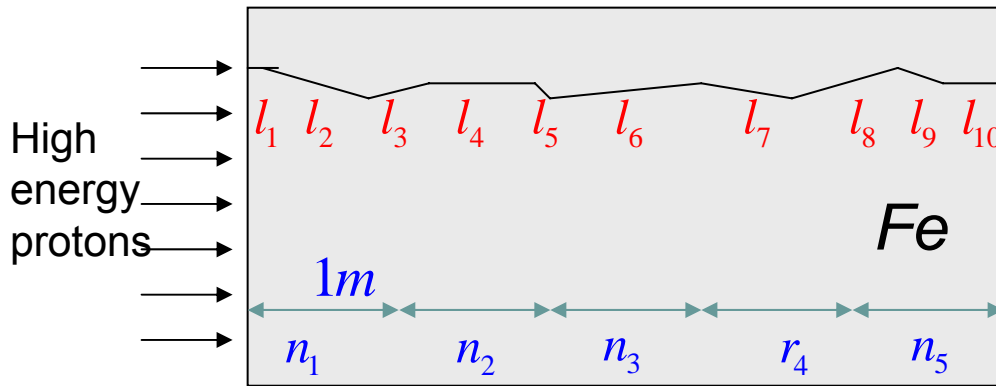
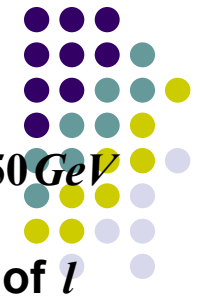
$$P_0([0, x]) \times P_1([x, x + dx]) = \frac{1}{0!} \left(\frac{x}{\beta}\right)^0 e^{-x/\beta} \times \frac{dx}{\beta} = \frac{1}{\beta} e^{-x/\beta} dx$$

$$f(x|\beta) = \frac{1}{\beta} e^{-x/\beta}$$

- Mean  $\mu = \beta$
- Variance  $\sigma^2 = \beta^2$



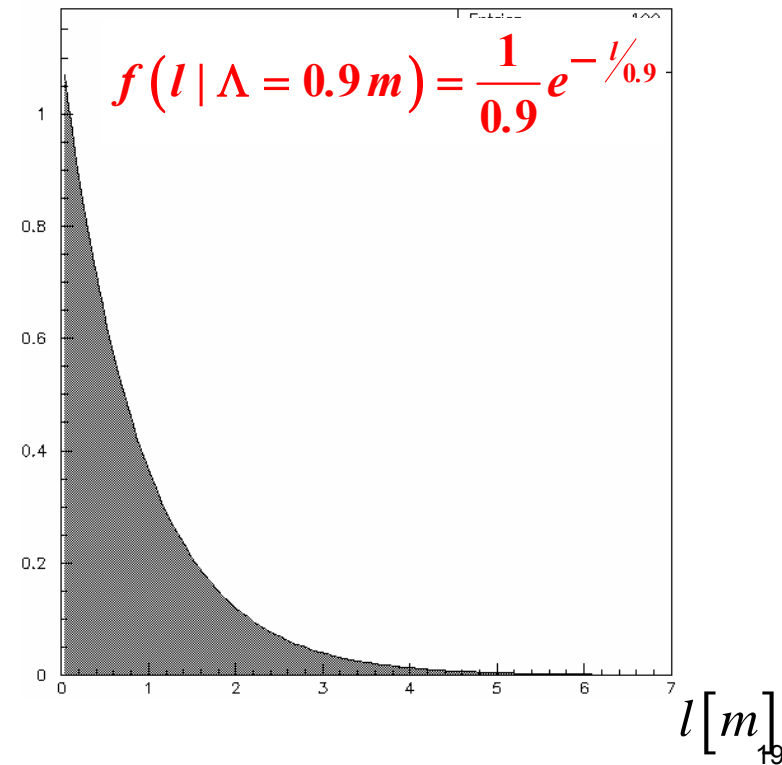
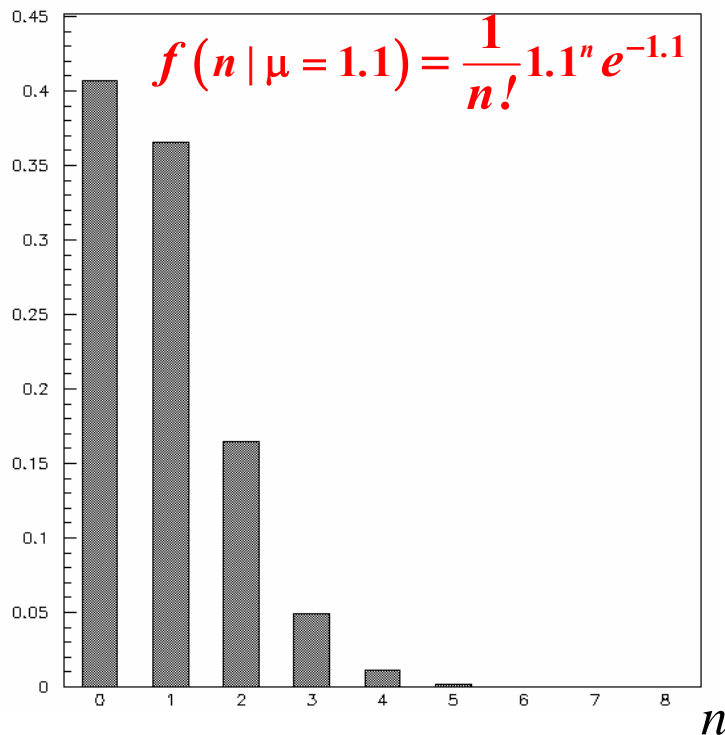
# Example of relation between exponential and Poisson PDF



$$\sigma_{pFe}^{elast} \approx 0.110 \cdot 10^{24} \text{ cm}^2 \text{ for } E \geq 50 \text{ GeV}$$

$$\Lambda = \frac{A_{Fe}}{\sigma_{pFe}^{elast} N_A \rho_{Fe}} \approx 0.9 \text{ m} : \text{mean of } \underline{l}$$

$$\mu = \frac{1 \text{ m}}{0.9 \text{ m}} \approx 1.1 : \text{mean of } \underline{n}$$



## Convolutions of Poisson and Binomial PDF



$r_1$  and  $r_2$  : independent from Poisson PDF of means  $\mu_1$  and  $\mu_2. \Rightarrow$

$r_1 + r_2$  : Poisson PDF of mean  $\mu_1 + \mu_2.$

$r$  : binomial PDF of success probability  $p$  and number of trials  $n.$

$n$  : Poisson PDF of mean  $\mu. \Rightarrow$

$r$  : Poisson PDF of mean  $p\mu.$

## Convolution example



Plastic scintillator strip of thickness  $0.1 \text{ mm}$  seen by a photosensor  
and crossed by a MIP

Mean photon emission :  $\mu_\gamma = 200$

Distance to photocathode :  $l = 1 \text{ m}$

Scintillator absorption length :  $\lambda = 0.5 \text{ m}$

Photocathode efficiency :  $QE = 0.2$

PDF of  $n_\gamma$  at emission: Poisson of mean  $\mu_\gamma = 200$

Fraction of photons reaching the photocathode  $p_\lambda = \int_1^\infty \frac{1}{0.5} e^{-x/0.5} dx = 0.14$

PDF of  $n_\gamma$  at photocathode input: Poisson of mean  $p_\lambda \times \mu_\gamma = 0.14 \times 200 = 28$

PDF of  $n_e$  at photocathode output: Poisson of mean  $QE \times p_\lambda \times \mu_\gamma = 0.14 \times 200 \times 0.2 = 5.6$

Efficiency = probability to observe at least 1  $e$

$$\varepsilon = 1 - P(0 | 5.6) = 1 - e^{-5.6} = 0.996$$

# Gauss Process



- **Central place in statistics.**
- **No natural process is sRICTO SENSU gaussian.**
- **Many PDF asymptotically tend towards a gaussian or normal PDF at the limit of large samples.**
- **Sums and means of large samples asymptotically follow a gaussian PDF (Central limit theorem).**

# Normal or gaussian PDF

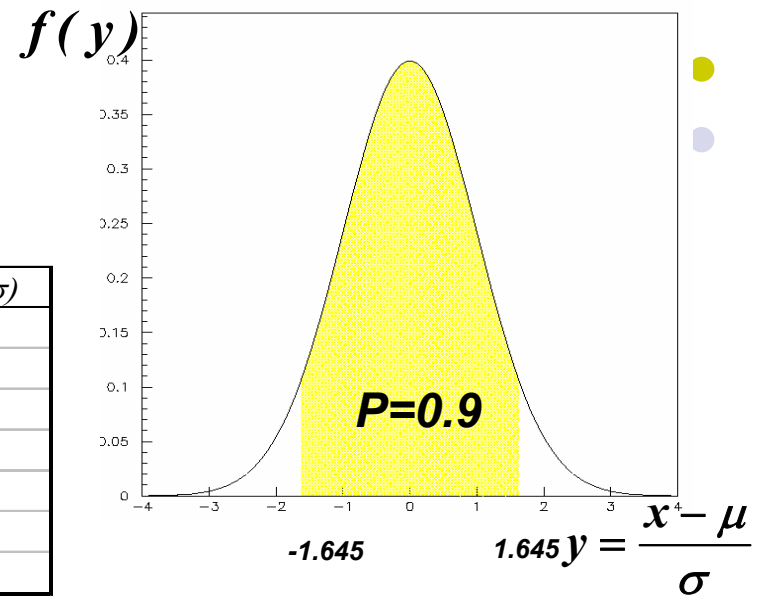
$$f(x|\mu, \sigma^2) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{1}{2} \frac{(x-\mu)^2}{\sigma^2}} = N(\mu, \sigma^2)$$

## Standard normal PDF

$$y = \frac{x - \mu}{\sigma}$$

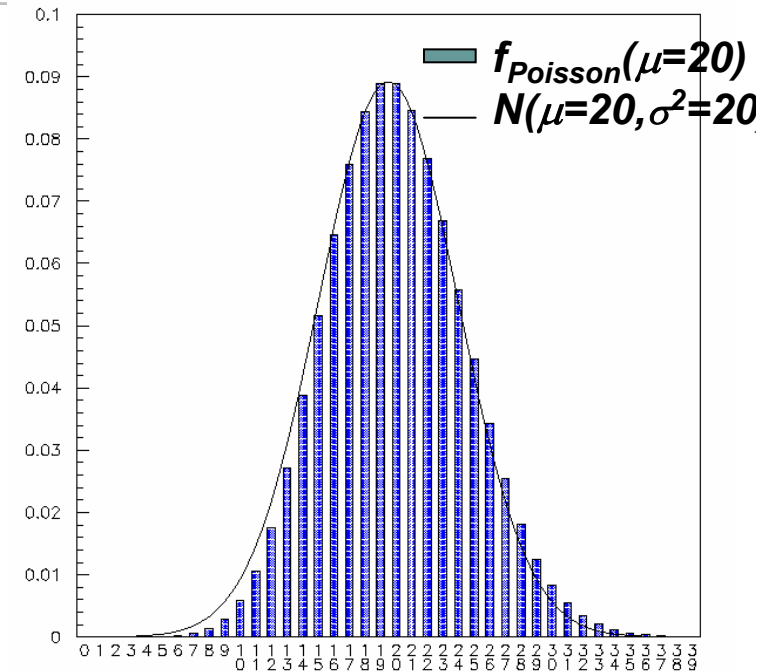
$$f(y|0,1) = \frac{1}{\sqrt{2\pi}} e^{-\frac{1}{2}y^2} = N(0,1)$$

$n$	$P(\mu - n\sigma < x < \mu + n\sigma)$
1	0.683
1.645	0.900
1.960	0.950
2	0.955
2.576	0.990
3	0.997
3.29	0.999



## Normal PDF as a limit the Poisson PDF

$$\lim_{\mu \rightarrow \infty} \frac{1}{r!} \mu^r e^{-\mu} = \frac{1}{\sqrt{2\pi\mu}} e^{-\frac{1}{2} \frac{(r-\mu)^2}{\mu}}$$



## Contents of an histogram: from binomial to Poisson to Normal PDF



- $n$  events into dans  $k$  classes
- $n_i$  observed events class  $i = 1, k$
- $p_i$  probability in class  $i$

### Exact PDF : binomial PDF

$n_i$  follows binomial PDF  $f(n_i | n, p_i) \quad \forall i = 1, k$

$$\mu_i = np_i \quad \sigma_i^2 = np_i(1 - p_i)$$

$n = \sum_{i=1}^k n_i$  is conserved

### Many classes : Poisson PDF approximation

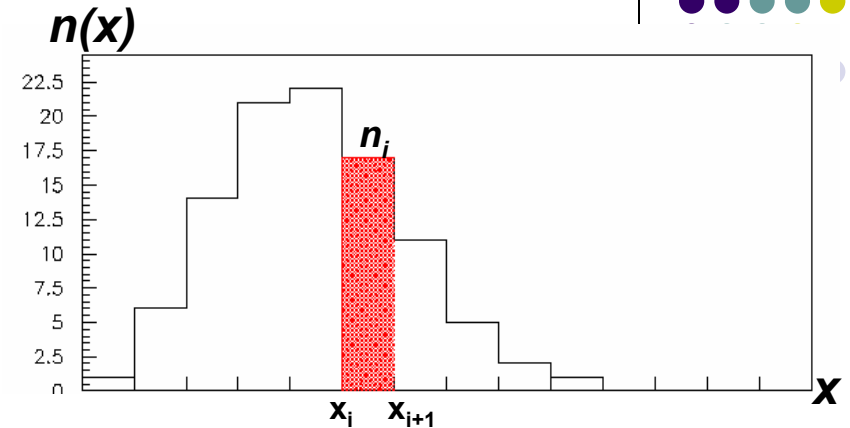
$k$  large  $\Rightarrow p_i \ll 1 \quad \forall i = 1, k$

$$\Rightarrow \sigma_i^2 = np_i(1 - p_i) \approx np_i \quad \forall i = 1, k$$

PDF of  $n_i \Rightarrow$  Poisson PDF  $f(n_i | \mu_i)$

$n \neq \sum_{i=1}^k n_i$  is not conserved

30/11/2006



### Many classes and events per class : Normal PDF approximation

$n_i \gg 1 \Rightarrow \forall i = 1, k$

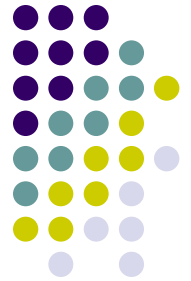
PDF of  $n_i \Rightarrow N(n_i | \mu_i)$

$n \neq \sum_{i=1}^k n_i$  is not conserved

In practice :  $n_i > 20 \Rightarrow \forall i = 1, k$



# Binormal and Multi-Normal Distributions



## Independent variables

$$f(x_1, x_2) = \frac{1}{2\pi\sqrt{\sigma_1^2\sigma_2^2}} e^{-\frac{1}{2}\left(\frac{(x_1-\mu_1)^2}{\sigma_1^2} + \frac{(x_2-\mu_2)^2}{\sigma_2^2}\right)}$$

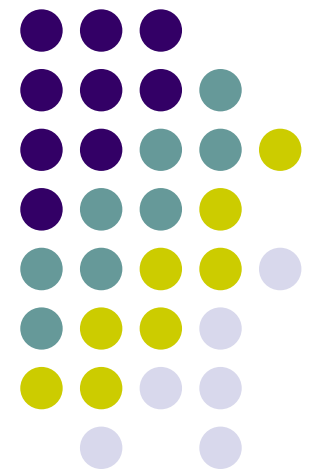
$$f(\underline{x}) = \frac{1}{(2\pi)^{\frac{n}{2}} \prod_{i=1}^n \sigma_i} e^{-\frac{1}{2} \sum_{i=1}^n \frac{(x_i - \mu_i)^2}{\sigma_i^2}} \quad \underline{x} = (x_1, \dots, x_n)$$

## Correlated variables

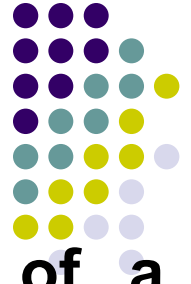
$$f(x_1, x_2) = \frac{1}{\sqrt{1-\rho^2}} \frac{1}{2\pi\sqrt{\sigma_1^2\sigma_2^2}} e^{-\frac{1}{2(1-\rho^2)}\left(\frac{(x_1-\mu_1)^2}{\sigma_1^2} + \frac{(x_2-\mu_2)^2}{\sigma_2^2} - 2\rho\frac{(x_1-\mu_1)(x_2-\mu_2)}{\sigma_1\sigma_2}\right)}$$

# III – Recall of general notions de statistics

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# Sampling



PDF  $f(x)$  defines the probability for each value of a population to occur.

Unbiased experiment = random sample of  $n$  observations  $(x_1, x_2, \dots, x_n)$  differing from the population only by statistical fluctuations due to its limited size

For the experiment to make sense, if the sample is biased, either the bias can be corrected for or it is small enough to be neglected.

# Concepts of statistic and estimator



**A statistic** : a random variables that depends only on the sample of observations and known parameters

**An estimator** : a statistic the value of which provides an estimation  $\hat{\theta}$  of a parametre  $\theta$  of unknown true value  $\theta_0$  .

**A non-bias estimator** :  $E[\hat{\theta}] = \theta_0$

**A coherent estimator** :  $\lim_{n \rightarrow \infty} \hat{\theta} = \theta_0$

**Invariance of the solution ; non propagation of the non-biasness :**

$$\text{If } \tau = \tau(\theta) \Rightarrow \hat{\tau} = \tau(\hat{\theta})$$

$$\text{If } E[\hat{\theta}] = \theta_0 \Rightarrow E[\hat{\tau}] = E[\tau(\hat{\theta})] \neq \tau(E[\hat{\theta}]) = \tau(\theta_0) = \tau_0$$

$\Rightarrow E[\hat{\tau}] \neq \tau_0$  in general

# Estimation of the mean and the variance of a sample



- Mean  $\hat{\mu} = \bar{x} = \frac{1}{n} \sum_{i=1}^n x_i$

**Non-biased estimator** :  $E[\bar{x}] = E\left[\frac{1}{n} \sum_{i=1}^n x_i\right] = \frac{1}{n} \sum_{i=1}^n E[x_i] = \mu$

**Coherent estimator** :  $\lim_{n \rightarrow \infty} \bar{x} = \mu$

intuitively  $\sigma_{\bar{x}}^2 = \frac{\sigma^2}{n}$

- Variance -  $\mu$  known

$$\hat{\sigma}^2 = S^2 = \frac{1}{n} \sum_{i=1}^n (x_i - \mu)^2$$

**Non biased estimator** :  $E[S^2] = \sigma^2$

- Variance -  $\mu$  unknown

$$\hat{\sigma}^2 = s^2 = \frac{1}{n-1} \sum_{i=1}^n (x_i - \bar{x})^2$$

**Non biased estimator** :  $E[s^2] = \sigma^2$

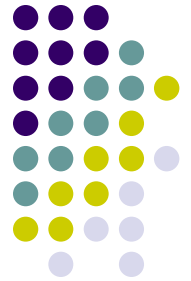
Intuitively : 1 degree of freedom used to compute  $\bar{x}$

**Coherent estimators** :  $\lim_{n \rightarrow \infty} S^2, s^2 = \sigma^2$

Intuitively :  $\sigma_{\sigma^2}^2 = \frac{(m_4 - \sigma^4)}{n} + \frac{2\sigma^4}{(n-1)n}$

**Note** :  $(\bar{x}, S^2)$  and  $(\bar{x}, s^2)$  are pairs of independent variables

# Size of the statistical fluctuations



## Inequality of Bienaymé - Chebyshev

For any PDF  $P(x \notin [\mu - \lambda\sigma, \mu + \lambda\sigma]) \leq \frac{1}{\lambda^2}$

## The Law of Large Numbers

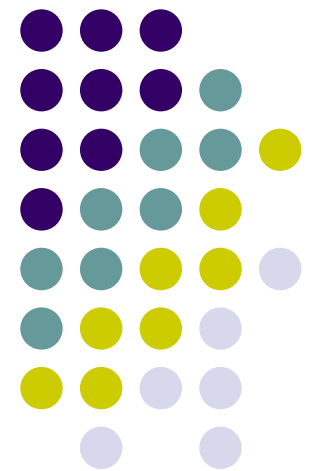
Application of Bienaymé-Chebyshev to the estimated mean of  $\bar{x}$  of a sample

$$\sigma_{\bar{x}}^2 = \frac{\sigma^2}{n}$$

$$P(|\bar{x} - \mu| \geq \lambda\sigma) = P(|\bar{x} - \mu| \geq \lambda\sqrt{n}\sigma_{\bar{x}}) \leq \frac{1}{n\lambda^2} \quad \Rightarrow \quad P(|\bar{x} - \mu| \geq \varepsilon) = \frac{\sigma^2}{n\varepsilon^2}$$

# IV – Sampling Distributions

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## The central role of the Normal Distribution: The Central Limit Theorem



$\underline{x} = (x_1, x_2, \dots, x_n)$  a set of independent random variables from any PDF provided  
means  $(\mu_1, \mu_2, \dots, \mu_n)$   
variances  $(\sigma_1^2, \sigma_2^2, \dots, \sigma_n^2)$  } are defined

$$X = \sum_{i=1}^n x_i \quad \Rightarrow \quad \mu_X = \sum_{i=1}^n \mu_i \quad \text{et} \quad \sigma_X^2 = \sum_{i=1}^n \sigma_i^2$$

If  $n \rightarrow \infty$ ,  $X = \sum_{i=1}^n x_i$  distributed following  $N\left(\sum_{i=1}^n \mu_i, \sum_{i=1}^n \sigma_i^2\right)$

$\underline{x} = (x_1, x_2, \dots, x_n)$  a set of independent random variables from the same PDF provided  
mean  $\mu$   
variance  $\sigma^2$  } are defined

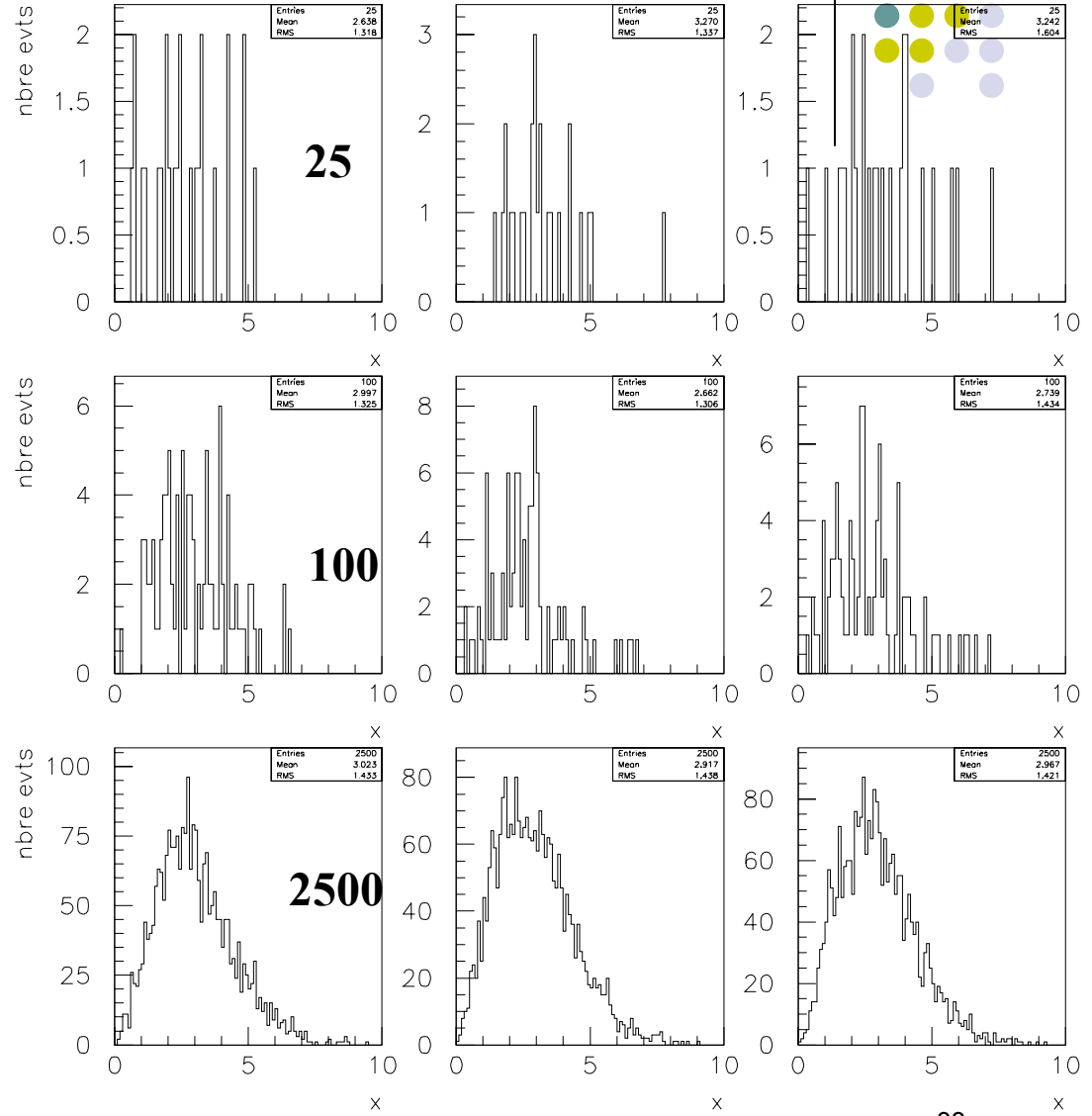
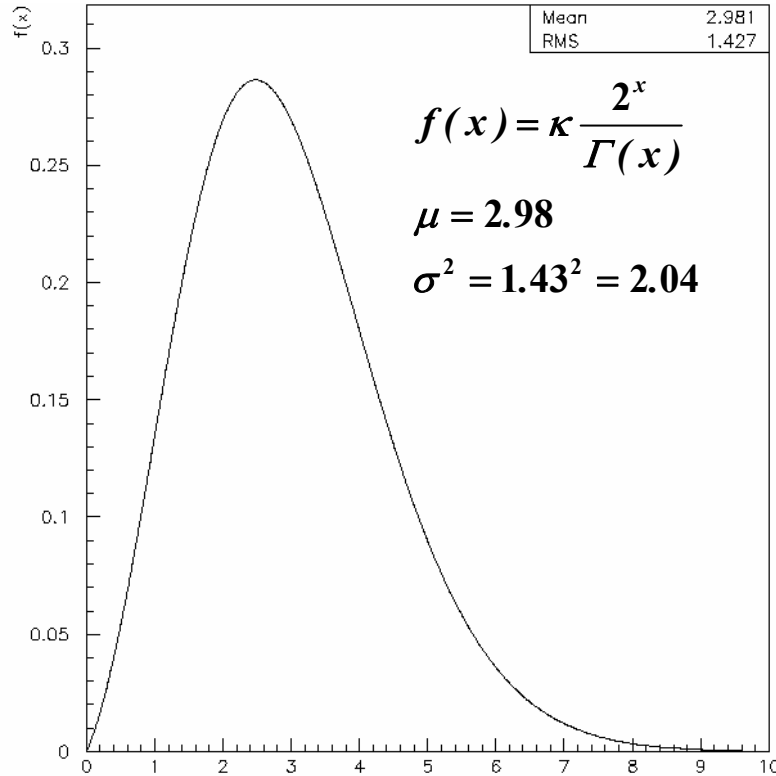
If  $n \rightarrow \infty$ ,  $\bar{x} = \frac{1}{n} \sum_{i=1}^n x_i$  distributed following  $N\left(\mu, \frac{\sigma^2}{n}\right)$

If  $n \rightarrow \infty$ ,  $\frac{\bar{x} - \mu}{\sigma/\sqrt{n}}$  distributed following  $N(0,1)$



# Central Limit Theorem: example (1)

3 samples of each size



**Extraction (par simulation) of**  
**10000 samples de 25 events**  
**10000 samples de 100 events**  
**10000 samples de 2500 events**

# Central Limit Theorem: example (2)



Distributions of the means of the 10000 samples of each of the 3 sample sizes

$$n = 25$$

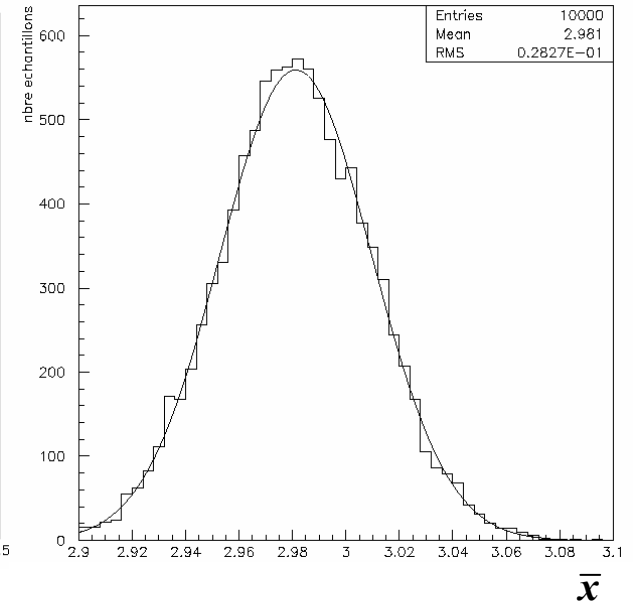
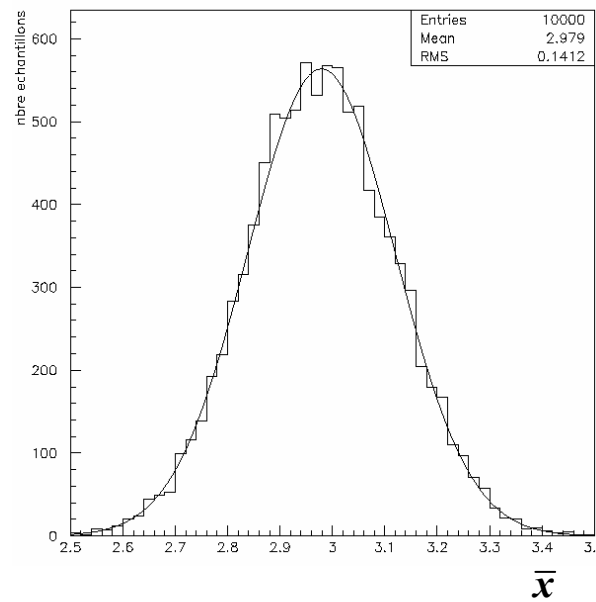
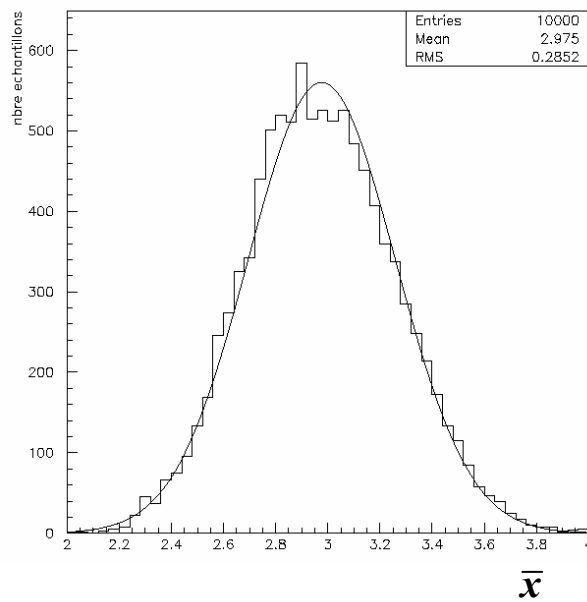
$$\frac{\sigma = 2.04}{\sqrt{25}} = 0.28$$

$$n = 100$$

$$\frac{\sigma = 2.04}{\sqrt{100}} = 0.14$$

$$n = 2500$$

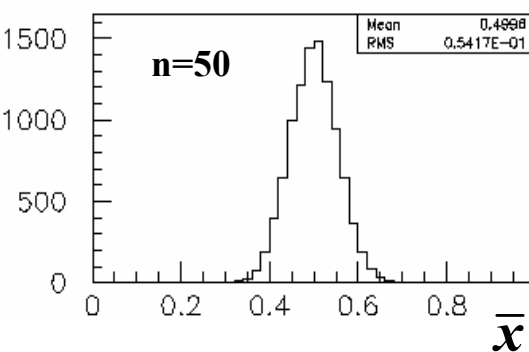
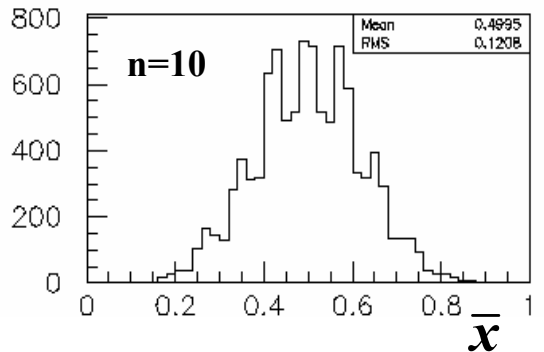
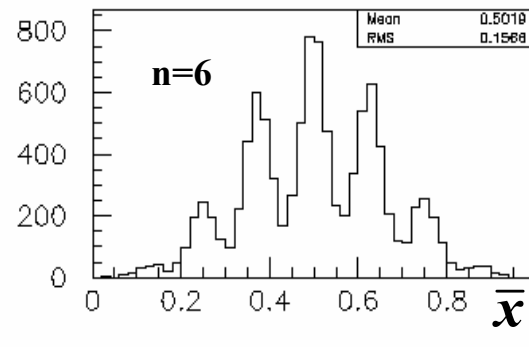
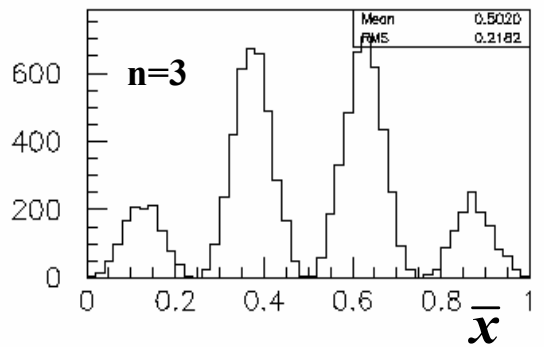
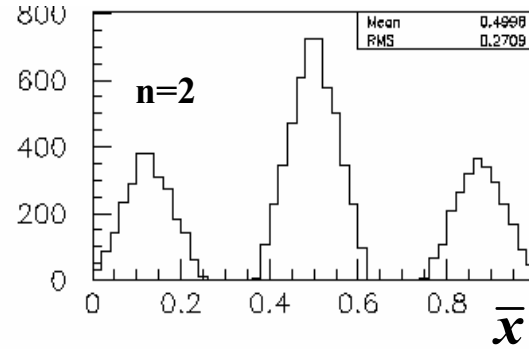
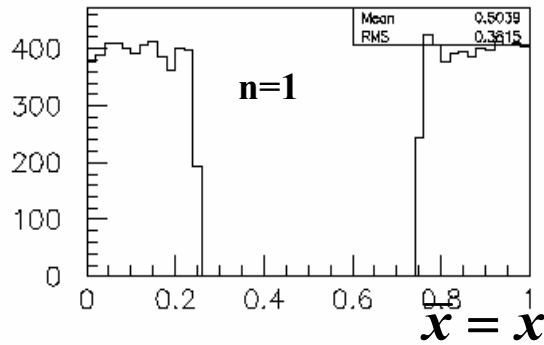
$$\frac{\sigma = 2.04}{\sqrt{2500}} = 0.028$$



# Central Limit Theorem: example (3)



$f(x)$ : uniform on  $[0, 1/4]$  and  $[3/4, 1]$



# Central Limit theorem and the Standard Error



The measurements of a distance of  $3 \text{ km}$  obtained by reporting 10 000 times a  $30 \text{ cm}$  ruler are distributed approximately normally with a standard deviation of  $\sim\sqrt{10\,000} \times 1\text{mm} = 1 \text{ m}$

The Standard Error on a measurement is the standard deviation of the approximate normal distribution along which an hypothetical large number of measurements would distribute around the true value.

The concept of Standard Error applies only if the final measurement is the convolution of a rather large number of rather independent measurements.

# Errors Propagation



## One variable

Knowing the measured values  $\hat{x}$  of  $x$  and the standard errors  $\sigma$   
 what is the error on  $\hat{y} = y(\hat{x})$  ?

Unknown true values :  $x_0$  and  $y_0 = y(x_0)$

First order Taylor series development around  $y_0$

$$y(\underline{x}) = y_0 + \sum_{i=1}^n (x_i - x_{i,0}) \left. \frac{\partial y}{\partial x_i} \right|_{\underline{x}=\underline{x}_0} + \dots = \sum_{i=1}^n x_i \left. \frac{\partial y}{\partial x_i} \right|_{\underline{x}=\underline{x}_0} + \text{Cste}$$

$$\Rightarrow \sigma_y^2 = \sum_{i=1}^n \left( \left. \frac{\partial y}{\partial x_i} \right|_{\underline{x}=\underline{x}_0} \right)^2 \sigma_i^2 \text{ and as } \underline{x}_0 \text{ is unknown, approximation by } \hat{x} \Rightarrow$$

$$\sigma_y^2 = \sum_{i=1}^n \left( \left. \frac{\partial y}{\partial x_i} \right|_{\underline{x}=\hat{x}} \right)^2 \sigma_i^2$$

## Several variables

$n$  variables directly accessible to measurement  $\underline{x} = (x_1, x_2, \dots, x_n)$

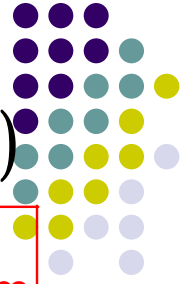
$m$  variables  $\underline{y} = (y_1, y_2, \dots, y_m)$  measured through relations  $\underline{y} = \underline{y}(\underline{x})$

$$\sigma_{y_{kl}} = \sum_{i=1}^n \sum_{j=1}^n \left. \frac{\partial y_k}{\partial x_i} \right|_{\underline{x}=\hat{x}} \left. \frac{\partial y_l}{\partial x_j} \right|_{\underline{x}=\hat{x}} \sigma_{x_{ij}}$$

$k, l = 1, m$

where  $\sigma_{ii} = \sigma_i^2$

# $\chi^2$ Distribution



$n$  independent variables  $\underline{x} = (x_1, \dots, x_n)$  distributed following  $N(\mu_i, \sigma_i^2)$

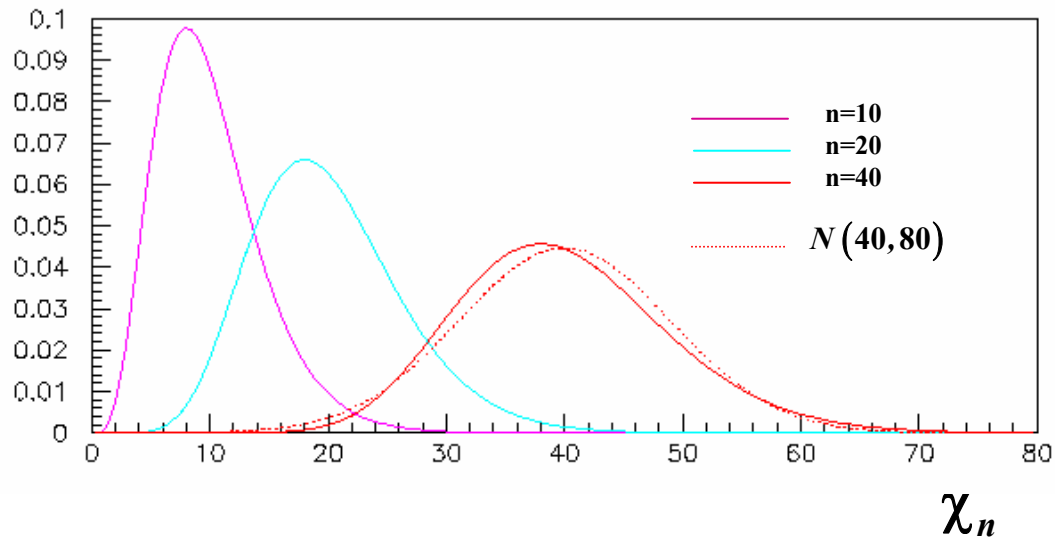
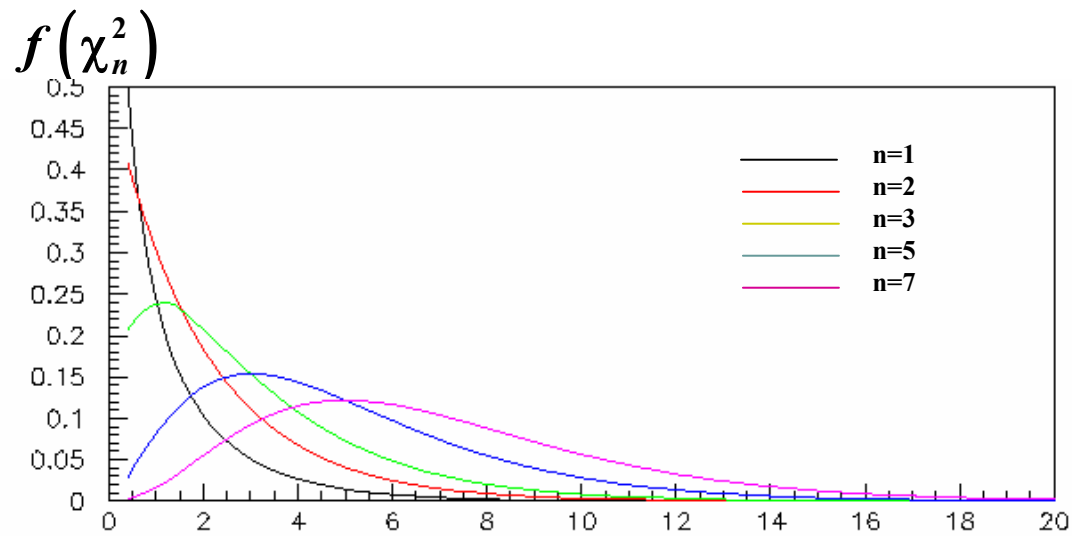
$$X^2 = \sum_{i=1}^n \frac{(x_i - \mu_i)^2}{\sigma_i^2} \text{ follows a } \chi_n^2 \text{ distribution with } n \text{ degrees of freedom}$$

$X^2$  measures the sum of the square distance between point  $\underline{x}$  and its expectation value  $\underline{\mu}$  in a  $n$ -dimension space, using  $\underline{\sigma}$  as unit length.

$$f(X^2 | n) = \frac{1}{2^{n/2} \Gamma(n/2)} (X^2)^{n/2-1} e^{-X^2/2}$$

PDF:  $\mu = n$   
 $\sigma^2 = 2n$

# $\chi^2$ Distribution: shape of PDF and normal asymptotic convergence



$$\lim_{n \rightarrow \infty} f(\chi_n^2) = N(n, 2n)$$

# Statistics following a $\chi^2$ distribution



$\underline{x} = (x_1, \dots, x_n)$  independent and follow  $(\mu, \sigma^2)$

$$\sum_{i=1}^n \left( \frac{x_i - \mu}{\sigma} \right)^2 \text{ follows a } \chi_n^2$$

$$S^2 = \frac{1}{n} \sum_{i=1}^n (x_i - \mu)^2$$

$$\Rightarrow \boxed{n \frac{S^2}{\sigma^2} \text{ follows a } \chi_n^2}$$

$$\sum_{i=1}^n \left( \frac{x_i - \bar{x}}{\sigma} \right)^2 \text{ follows a } \chi_{n-1}^2$$

$$s^2 = \frac{1}{n-1} \sum_{i=1}^n (x_i - \bar{x})^2$$

$$\Rightarrow \boxed{(n-1) \frac{s^2}{\sigma^2} \text{ follows a } \chi_{n-1}^2}$$



# Student $t$ Distribution : small samples



- Given -  $x$  distributed following a  $N(0,1)$ 
  - $u$  distributed following a  $\chi_n^2$
  - $x$  and  $u$  independent

$t_n = \frac{x}{\sqrt{u/n}}$  follows a Student  $t$  distribution with  $n$  degrees of freedom

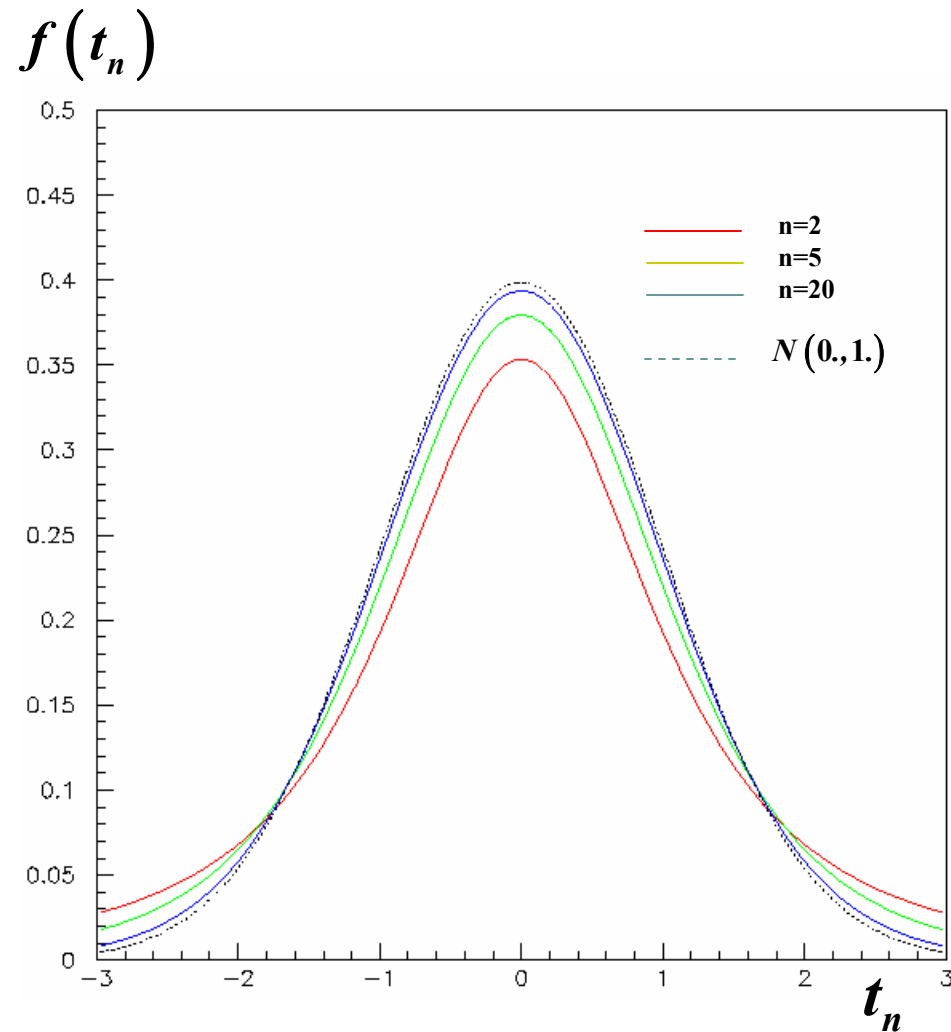
$$f(t_n | n) = \frac{\Gamma\left(\frac{n+1}{2}\right)}{\sqrt{\pi n} \Gamma\left(\frac{n}{2}\right)} \frac{1}{\left(1 + t_n^2\right)^{\frac{n+1}{2}}}$$

$\mu = 0$

$\sigma^2 = \frac{n}{n-2}$  si  $n > 2$

PDF :

## $t$ Distribution: shape of PDF and normal asymptotic convergence



limit for  $n \rightarrow \infty$

$$\lim_{n \rightarrow \infty} (t_n) = N(0,1)$$

# Statistics following a $t$ distribution



$\underline{x} = (x_1, \dots, x_n)$  independent and follow  $N(\mu, \sigma^2)$

$$\bar{x} = \frac{1}{n} \sum_{i=1}^n x_i \quad \text{and} \quad \frac{\bar{x} - \mu}{\sigma/\sqrt{n}} \text{ distributed following } N(0,1)$$

$$S^2 = \frac{1}{n} \sum_{i=1}^n (x_i - \mu)^2 \quad \text{and} \quad n \frac{S^2}{\sigma^2} \text{ distributed following } \chi_n^2$$

$$\frac{\frac{\bar{x} - \mu}{\sigma/\sqrt{n}}}{\sqrt{\frac{n \frac{S^2}{\sigma^2}}{n}}} = \frac{\bar{x} - \mu}{S/\sqrt{n}} \text{ follows } t_n \quad \frac{\bar{x} - \mu}{\sigma/\sqrt{n}} \text{ follows } N(0,1)$$

$$s^2 = \frac{1}{n-1} \sum_{i=1}^n (x_i - \bar{x})^2 \quad \text{and} \quad (n-1) \frac{s^2}{\sigma^2} \text{ distributed following } \chi_{n-1}^2$$

$$\frac{\frac{\bar{x} - \mu}{\sigma/\sqrt{n}}}{\sqrt{\frac{(n-1) \frac{s^2}{\sigma^2}}{(n-1)}}} = \frac{\bar{x} - \mu}{s/\sqrt{n}} \text{ follows } t_{n-1} \quad \frac{\bar{x} - \mu}{\sigma/\sqrt{n}} \text{ follows } N(0,1)$$

$$\lim_{n \rightarrow \infty} \frac{\bar{x} - \mu}{s/\sqrt{n}}, \frac{\bar{x} - \mu}{S/\sqrt{n}} = \frac{\bar{x} - \mu}{\sigma/\sqrt{n}} \quad \Leftrightarrow \quad \lim_{n \rightarrow \infty} f(t_n) = N(0,1)$$

# Cauchy or $t_1$ Student and Breit-Wigner distributions

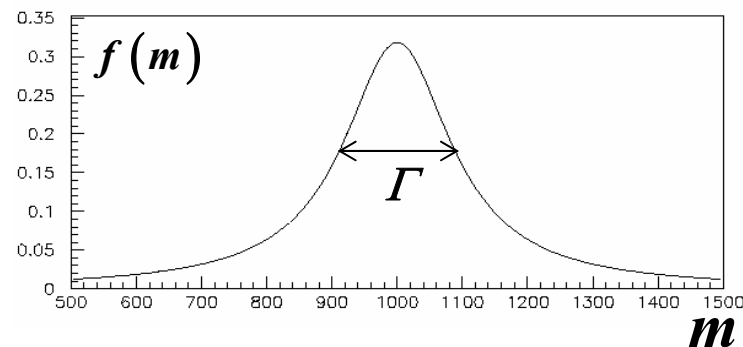
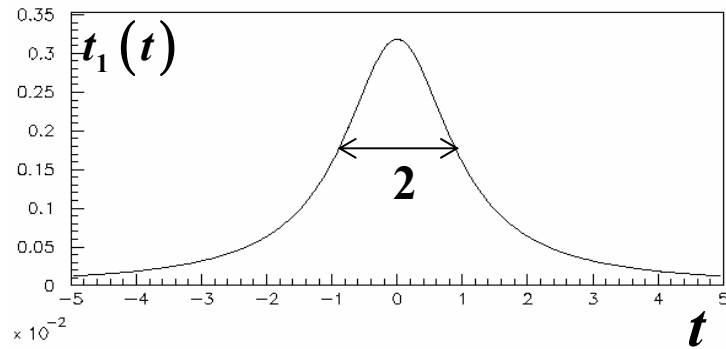


## Cauchy or Student $t_1$ Distribution

$$f(t_1) = \frac{1}{\pi(1+t_1^2)}$$

$$\int_{-\infty}^{\infty} t_1^2(t_1) dt = \infty$$

$\Rightarrow$   $\left\{ \begin{array}{l} \sigma^2 \text{ undefined} \\ \text{central limit theorem not applicable} \\ \text{full width at half maximum FWHM} = 2 \end{array} \right.$



## Breit-Wigner Distribution

$$\Gamma = \frac{\hbar}{\tau} = \text{intrinsic particle mass width.}$$

Strong interaction :  $\tau \approx 10^{-23} s \Rightarrow \Gamma \approx 100 \text{ MeV}$

Change of variable  $m = m_0 + t_1 \cdot \Gamma/2$

$$f(m) = \frac{\Gamma/2}{\pi} \frac{1}{(m - m_0)^2 + (\Gamma/2)^2} \quad \Gamma = \text{FWHM}$$

Mass distribution of a spin 0 particle

# Fisher-Snedecor F Distribution



- $u_1, u_2$  distributed following  $\chi_{n_1}^2, \chi_{n_2}^2$
- $u_1$  and  $u_2$  independent

$F_{n_1, n_2} = \frac{u_1/n_1}{u_2/n_2}$  follows a Fisher distribution with  $n_1, n_2$  degrees of freedom

$$f(F_{n_1, n_2} | n_1, n_2) = \frac{\Gamma\left(\frac{n_1 + n_2}{2}\right)}{\Gamma\left(\frac{n_1}{2}\right)\Gamma\left(\frac{n_2}{2}\right)} \left(\frac{n_1}{n_2}\right)^{\frac{n_1}{2}} \times \frac{F_{n_1, n_2}^{\frac{n_1}{2} - 1}}{\left(1 + \frac{1}{n_2} F_{n_1, n_2}\right)^{\frac{n_1 + n_2}{2}}}$$

PDF:

$$\mu = \frac{n_2}{n_2 - 2} \text{ si } n_2 > 2$$
$$\sigma^2 = \frac{2n_2^2 (n_1 + n_2 - 2)}{n_1 (n_2 - 2)^2 (n_2 - 4)} \text{ si } n_2 > 4$$

$$\lim_{n_2 \rightarrow \infty} f(n_1 F_{n_1, n_2}) = f(\chi_{n_1}^2)$$

$$\lim_{n_1, n_2 \rightarrow \infty} f(F_{n_1, n_2}) = N(0, 1)$$

# Statistics following an $F$ distribution



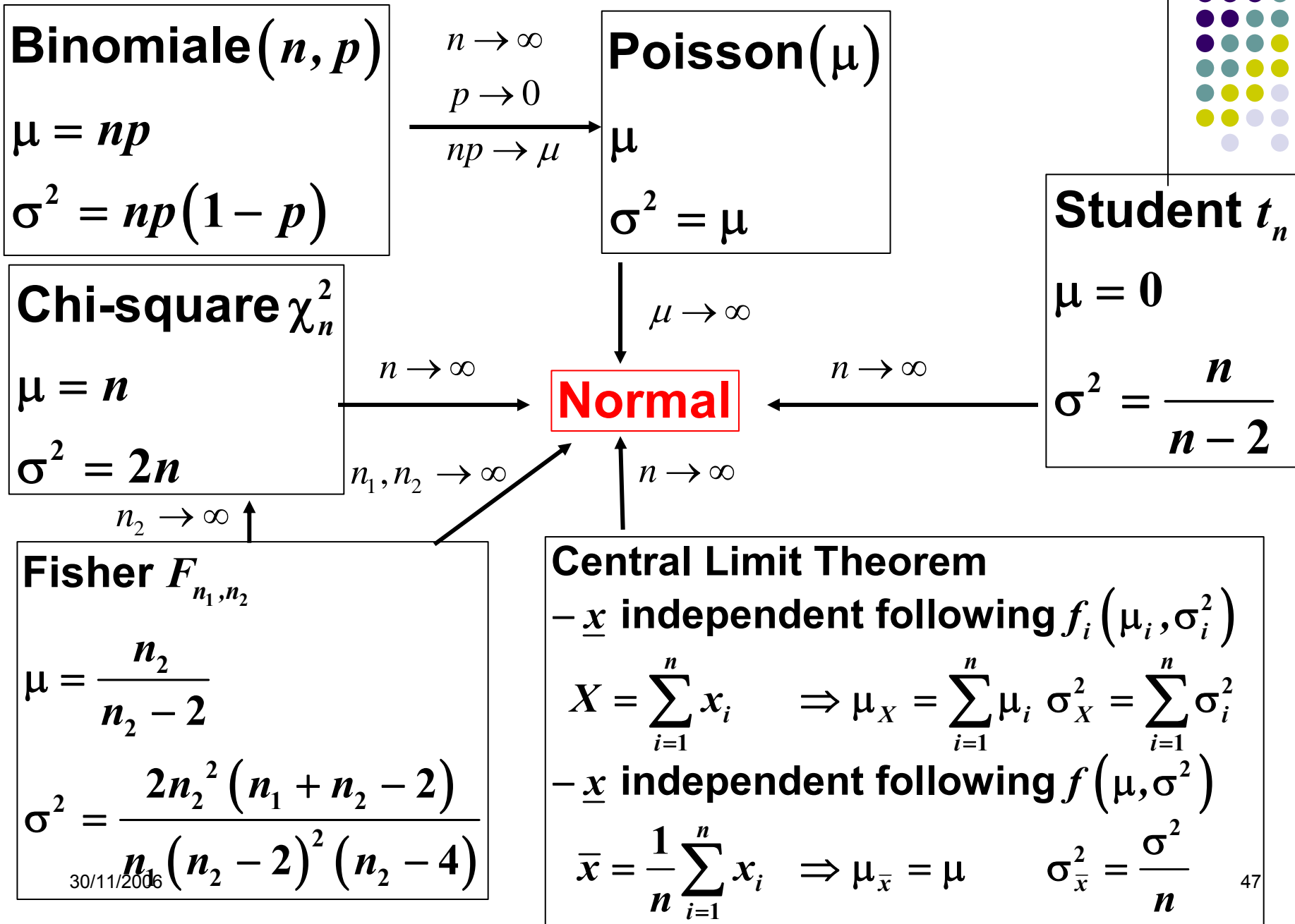
$\underline{x} = (x_1, \dots, x_n)$  independent and follow  $N(\mu_x, \sigma_x^2)$

$\underline{y} = (y_1, \dots, y_m)$  independent and follow  $N(\mu_y, \sigma_y^2)$

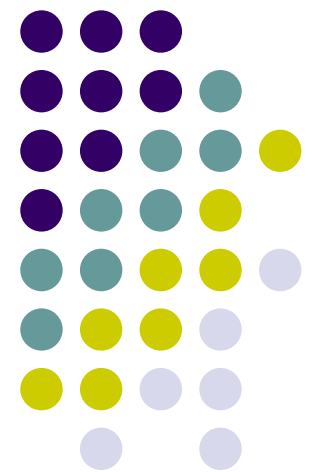
$\frac{S_x^2 / \sigma_x^2}{S_y^2 / \sigma_y^2}$  follows a  $F_{nm}$

$\frac{s_x^2 / \sigma_x^2}{s_y^2 / \sigma_y^2}$  follows a  $F_{(n-1)(m-1)}$

# Central role of the Normal Distribution



# V – Hypothesis Tests





# Principle



Decide if the hypothesis  $H_0$ , the **null** or **tested hypothesis**, that an observation (value of a parameter, distribution of a variable) is compatible with a reference (expectation from a model, existing observation) is true while accepting to reject the hypothesis though it is true (commit a **type I error**) with an a priori probability  $\alpha$ , the significance or level of significance of the test.

The test only makes sense if there exists an **alternative hypothesis  $H_1$**  with a non null probability to occur. The most trivial form of  $H_1$  is that  $H_0$  is false

If  $H_1$  is fully specified, the probability  $\beta$  to accept  $H_0$  though  $H_1$  is true (commit a **type II error**) can be computed. The best test maximises the **power  $1-\beta$**  of the test.

If  $H_1$  is not fully specified,  $\beta$  cannot be computed but it is often possible to define the test that maximises  $1-\beta$ .

## Definitions – Best critical zone



**Parametric test:** test the value of a parameter

**Non-parametric test:** test the shape of a distribution

**Simple hypothesis:** fully specified

**Composite hypothesis:** partly specified or unspecified

**Best critical region  $R_\alpha$  :** domain of rejection of values of the parameter that maximise the power of the test.

If PDF  $f_0$  defines  $H_0$  :

$$\alpha = \int_{R_\alpha} f_0(x) dx$$

$$1 - \beta = \int_{R_\alpha} f_1(x) dx \text{ is maximal}$$

**Acceptance region  $A_\alpha = W - R_\alpha$  :** complement of the critical region

## Best critical region $R_\alpha$ : Neyman-Pearson Lemma

One measurement :

$$\alpha = \int_{R_\alpha} f_0(x) dx$$

$$1 - \beta = \int_{R_\alpha} f_1(x) dx = \int_{R_\alpha} \frac{f_1(x)}{f_0(x)} f_0(x) dx = \left\langle \frac{f_1(x)}{f_0(x)} \right\rangle_{H_0 \text{ true}}$$

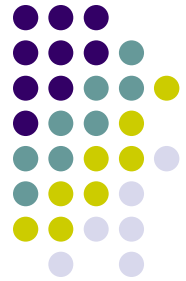
$$R_\alpha \subset \begin{cases} f_0(x) = 0 \\ \frac{f_1(x)}{f_0(x)} > k_\alpha \end{cases}$$

$n$  measurements : critical region difficult to get

$$\alpha = \int_{R_\alpha} \prod_{i=1}^n f_0(x_i) dx \Rightarrow \quad n\text{-dimensional integral}$$

$$R_\alpha \subset \begin{cases} f_0(x) = 0 \\ \frac{\prod_{i=1}^n f_1(x_i)}{\prod_{i=1}^n f_0(x_i)} > k_\alpha \end{cases}$$

$n$  large : use  $\bar{x} = \frac{\sum_{i=1}^n x_i}{n}$  instead of  $\underline{x}$  and the Central Limit Theorem



# Test of the mean of a normal distribution



**$H_0$ : sample  $N(\mu = \mu_0, \sigma^2 = \sigma_0^2 \text{ known})$**

**$H_1$ :  $\mu \neq \mu_0$  : composite hypothesis**

If  $H_0$  true:

$$z = \frac{\bar{x} - \mu_0}{\sigma_0 / \sqrt{n}} \text{ follows a } N(0,1)$$

$R_\alpha$ : domain of large values of  $|z| > r_{\alpha/2}$

$$\rightarrow \alpha/2 = \int_{-\infty}^{-r_{\alpha/2}} N(z | 0,1) dz = \int_{r_{\alpha/2}}^{\infty} N(z | 0,1) dz$$

**$H_0$ : sample  $N(\mu = \mu_0, \sigma^2 \text{ unknown})$**

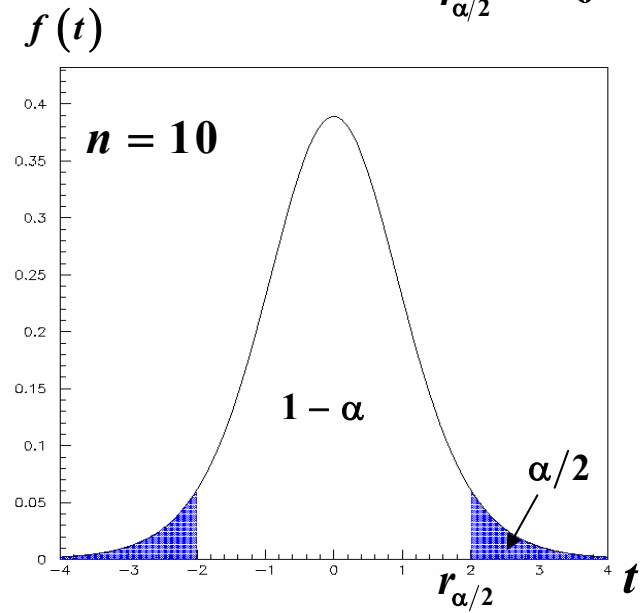
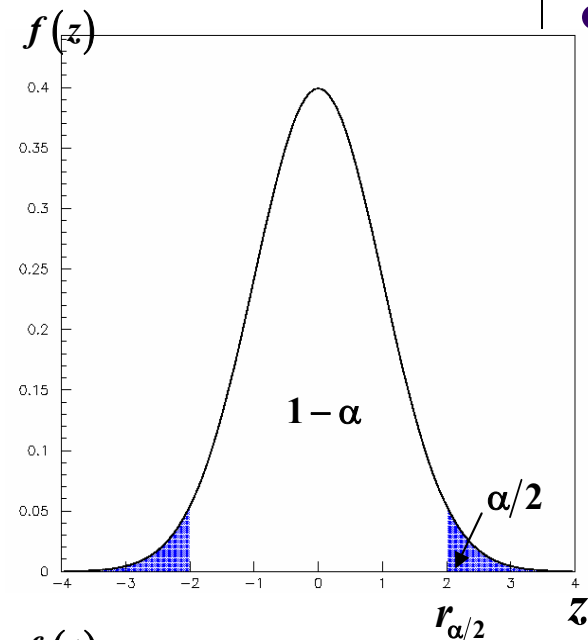
**$H_1$ :  $\mu \neq \mu_0$  : composite hypothesis**

$$t = \frac{\bar{x} - \mu_0}{s / \sqrt{n}} \text{ follows a Student } t_{n-1}$$

$$s^2 = \frac{1}{n-1} \sum_{i=1}^n (x_i - \bar{x})^2$$

$R_\alpha$ : domain of large values of  $|t| > r_{\alpha/2}$

$$\rightarrow \alpha/2 = \int_{-\infty}^{-r_{\alpha/2}} f(t_{n-1}) dt = \int_{r_{\alpha/2}}^{\infty} f(t_{n-1}) dt$$



## Test of the means of two normal distributions of known variances



$$\bar{x} = \frac{1}{n} \sum_{i=1}^n x_i: \text{sample of size } n \text{ from } N(\mu_x, \sigma_x^2)$$

$$\bar{y} = \frac{1}{m} \sum_{i=1}^m y_i \text{ sample of size } m \text{ from } N(\mu_y, \sigma_y^2)$$

$$H_0: \mu_x = \mu_y \quad - \quad \sigma_x^2 \text{ and } \sigma_y^2 \text{ known}$$

$$H_1: \mu_x \neq \mu_y \rightarrow \text{composite hypothesis}$$

$$\text{If } H_0: (\bar{x} - \bar{y}) \text{ follows } N(\mu_x - \mu_y = 0, \sigma_x^2/n + \sigma_y^2/m)$$

$$z = \frac{\bar{x} - \bar{y}}{\sqrt{\sigma_x^2/n + \sigma_y^2/m}} \text{ follows } N(0,1)$$

$$R_\alpha: \text{domain of large values of } |z| > r_{\alpha/2}$$

$$\rightarrow \alpha/2 = \int_{-\infty}^{-r_{\alpha/2}} N(z | 0,1) dz = \int_{r_{\alpha/2}}^{\infty} N(z | 0,1) dz$$

## Test of the means of two normal distributions of unknown equal variances



$$\bar{x} = \frac{1}{n} \sum_{i=1}^n x_i: \text{ sample of size } n \text{ from } N(\mu_x, \sigma_x^2)$$

$$\bar{y} = \frac{1}{m} \sum_{i=1}^m y_i \text{ sample of size } m \text{ from } N(\mu_y, \sigma_y^2)$$

$$H_0: \mu_x = \mu_y \quad - \quad \sigma_x^2 = \sigma_y^2 = \sigma_0^2 \text{ unknown}$$

sensible if similar experimental procedures

$$H_1: \mu_x \neq \mu_y \rightarrow \text{composite hypothesis}$$

If  $H_0$ :  $z = \frac{\bar{x} - \bar{y}}{\sqrt{\sigma_0^2/n + \sigma_0^2/m}}$  follows  $N(0,1)$

$(n-1)s_x^2/\sigma_0^2$  et  $(m-1)s_y^2/\sigma_0^2$  follows  $\chi_{n-1}^2$  et  $\chi_{m-1}^2$

$\rightarrow (n-1)s_x^2/\sigma_0^2 + (m-1)s_y^2/\sigma_0^2$  follows  $\chi_{n+m-2}^2$

$$t = \frac{\frac{\bar{x} - \bar{y}}{\sqrt{\sigma_0^2/n + \sigma_0^2/m}}}{\sqrt{\frac{(n-1)s_x^2/\sigma_0^2 + (m-1)s_y^2/\sigma_0^2}{n+m-2}}} = \frac{\bar{x} - \bar{y}}{\sqrt{\frac{((n-1)s_x^2 + (m-1)s_y^2)(n+m)}{nm(n+m-2)}}} \text{ follows } t_{n+m-2}$$

## Test of the means of two normal distributions of unknown variance



$$\begin{aligned} H_0: \mu_x = \mu_y & \quad - \quad \sigma_x^2, \sigma_y^2 \text{ unknown} \\ H_1: \mu_x \neq \mu_y & \quad \rightarrow \text{composite hypothesis} \end{aligned}$$

$$t = \frac{\frac{\bar{x} - \bar{y}}{\sqrt{\sigma_x^2/n + \sigma_y^2/m}}}{\sqrt{\frac{(n-1)s_x^2/\sigma_x^2 + (m-1)s_y^2/\sigma_y^2}{n+m-2}}} \quad \text{follows } t_{n+m-2}$$

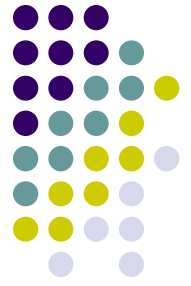
$t$  depends on unknown  $\sigma_x^2$  et  $\sigma_y^2$  and is not a statistic : the PDF of  $t$  is unknown

Approximation  $s_x^2 \approx \sigma_x^2$  et  $s_y^2 \approx \sigma_y^2$

$$z = \frac{\bar{x} - \bar{y}}{\sqrt{s_x^2/n + s_y^2/m}} \quad \text{follows } N(0,1)$$

The larger  $n, m$  the better the approximation

# Non-parametric tests



Theoretical model for the PDF of  $x : f_0(x)$

Set of  $n$  observations  $\underline{x} = (x_1, x_2, \dots, x_n)$

$H_0$ :  $\underline{x}$  is a sample extracted from population of PDF  $f_0(x)$

$H_1$ :  $H_0$  false

Variant : the model also predicts the size of the sample

Set of  $n$  observations  $\underline{x} = (x_1, x_2, \dots, x_n)$

Set of  $m$  observations  $\underline{y} = (y_1, y_2, \dots, y_m)$

$H_0$ : sample  $\underline{x}$  and  $\underline{y}$  extracted from the same population

$H_1$ :  $H_0$  false



# Non-parametric Pearson's $\chi^2$ test – partition in exclusive classes



Partition of  $\underline{x}$  into  $N < n$  classes of contents  $n_i, i = 1, N$  with normalisation  $n = \sum_{i=1}^N n_i$

If  $x$  numerical : class  $i$  defined by  $X_i \leq x < X_{i+1}$

**Remember :**

$n_i$  follows a binomial of probability  $p_i$

$\lim_{\substack{p_i \rightarrow 0 \forall i \\ n \rightarrow \infty}} \text{binomial} \rightarrow \text{Poisson}$

$\lim_{n_i \rightarrow \infty \forall i} \text{Poisson} \rightarrow \text{normal}$

$n_i$  follows  $N(np_i, np_i)$

If  $H_0$  true:  $p_i = p_{0i} = \int_{X_i}^{X_{i+1}} f_0(x) dx \quad \forall i = 1, N$

Test statistic  $X^2 = \sum_{i=1}^N \frac{(n_i - np_{0i})^2}{np_i}$  follows  $\chi_{N-1}^2$

Contents of the last class  $n_N = n - \sum_i^{N-1} n_i$

Number of degrees of freedom  $\nu = N - 1$

If  $H_0$  true:  $n_i = n_{0i}$

Test statistic  $X^2 = \sum_{i=1}^N \frac{(n_i - n_{0i})^2}{np_i}$  follows  $\chi_N^2$

Contents of the last class  $\sum_i^N n_i \neq \sum_i^N n_{0i}$

Number of degrees of freedom  $\nu = N$

# Pearson's $\chi^2$ test – critical zone

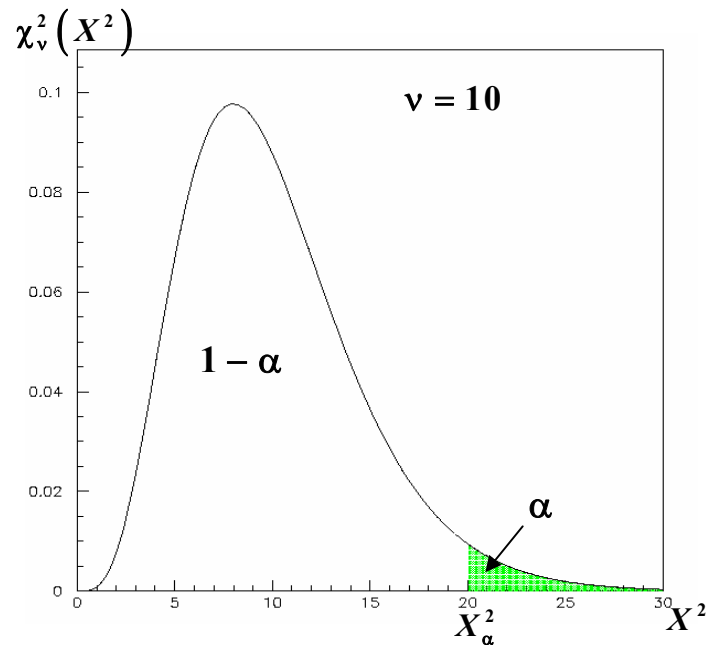


Critical zone  $R_\alpha: X^2 > X_\alpha^2$

$$X_\alpha^2 \Rightarrow \int_{X_\alpha^2}^{\infty} \chi_v^2(X^2) dX^2 = \alpha$$

If  $H_0$  true:  $E[X_\alpha^2] = v \Rightarrow$  small values of  $X^2$  are improbable

small values of  $X^2$  are even less probable if  $H_1$  true



# Pearson's $\chi^2$ test – choice of the classes



**Contradictory requirements unless the sample is very large:**

**binomial  $\rightarrow$  Poisson  $\Rightarrow$  small  $p_i \Rightarrow$  many classes**

**Poisson  $\rightarrow$  normal  $\Rightarrow$  large  $n_i \Rightarrow$  many entries per class**

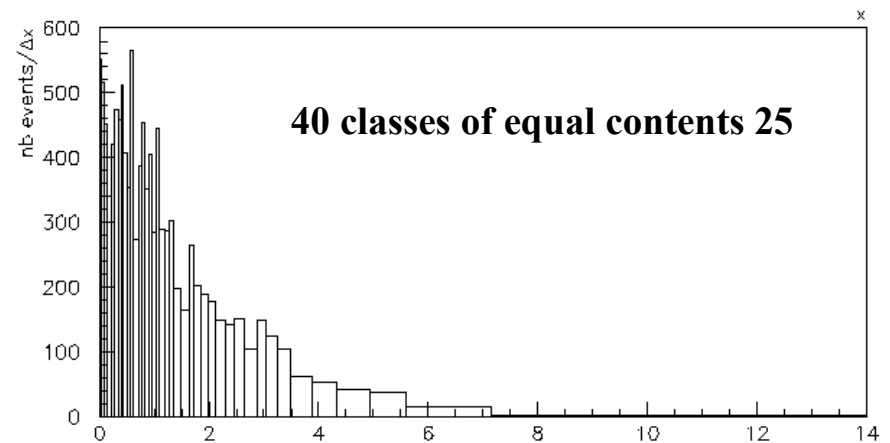
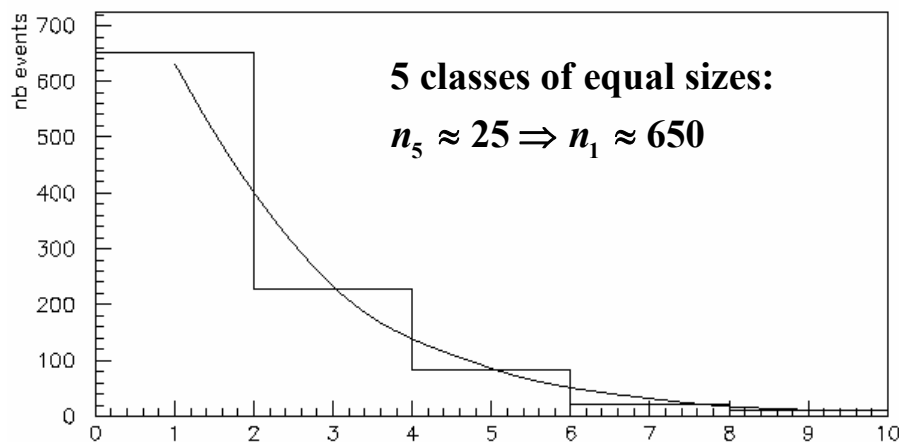
**Loss of information:**

**many entries per class  $\Rightarrow$  large classes**

**Two methods:**

**classes of equal size: simpler**

**classes of large ( $\approx 25$ ) equal content : minimises the loss of information**



# Non-parametric Kolmogorov-Smirnov test



Ordering of  $\underline{x} : x_i \leq x_{i+1} \quad \forall i = 1, n-1$

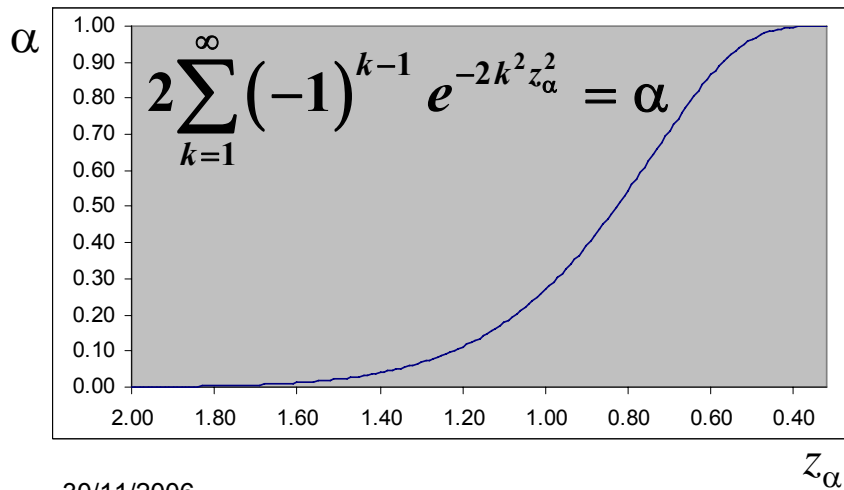
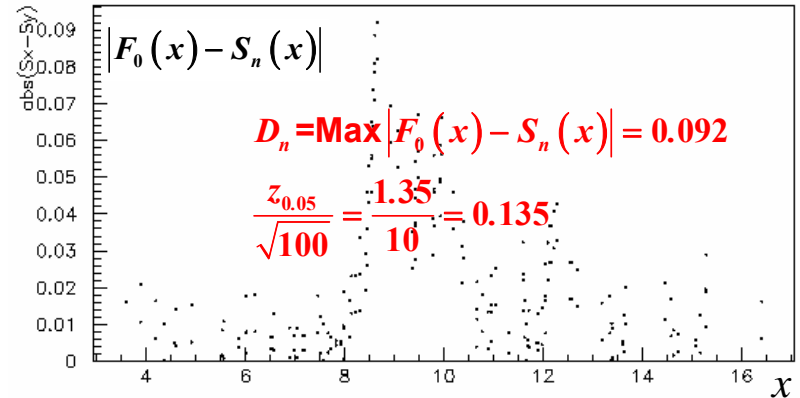
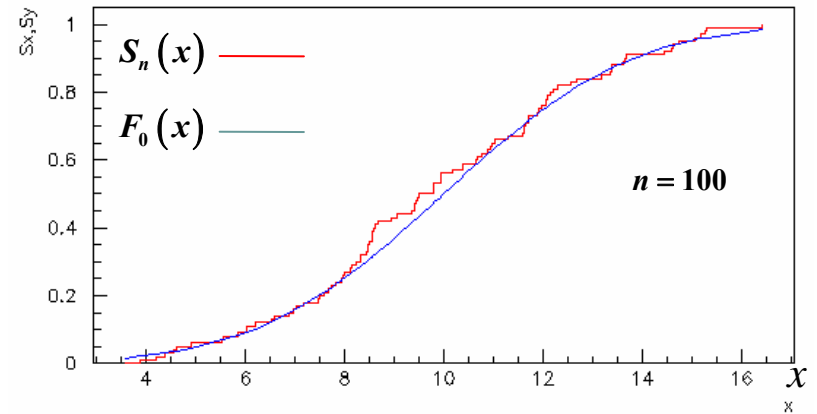
Observed distribution function

$$S_n(x) \begin{cases} 0 & \text{si } x < x_1 \\ \frac{i}{n} & \text{si } x_i \leq x < x_{i+1} \\ 1 & \text{si } x > x_n \end{cases} \quad 0 \leq S_n(x) \leq 1$$

If  $H_0$  true: distribution function is  $F_0(x)$

Test Statistic  $D_n = \text{Max}(|F_0(x) - S_n(x)|)$

Critical zone :  $D_n > d_{n,\alpha} \approx \frac{z_\alpha}{\sqrt{n}}$  for  $n \geq 10$



# Kolmogorov-Smirnov test between two samples



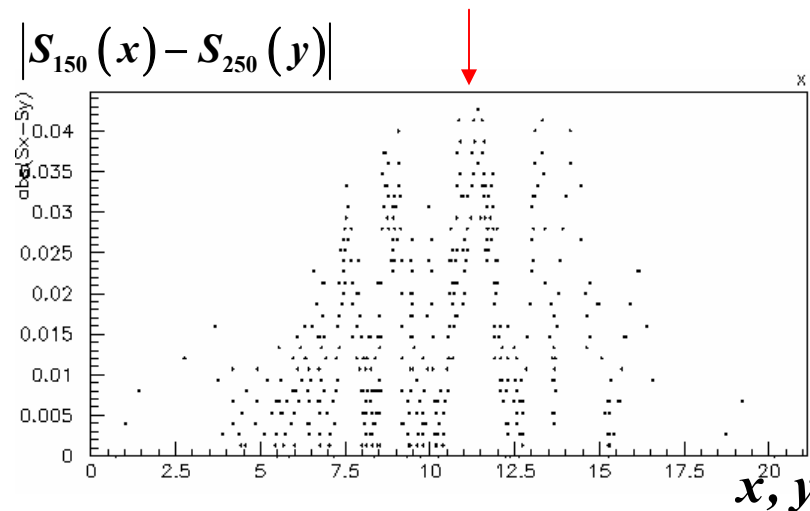
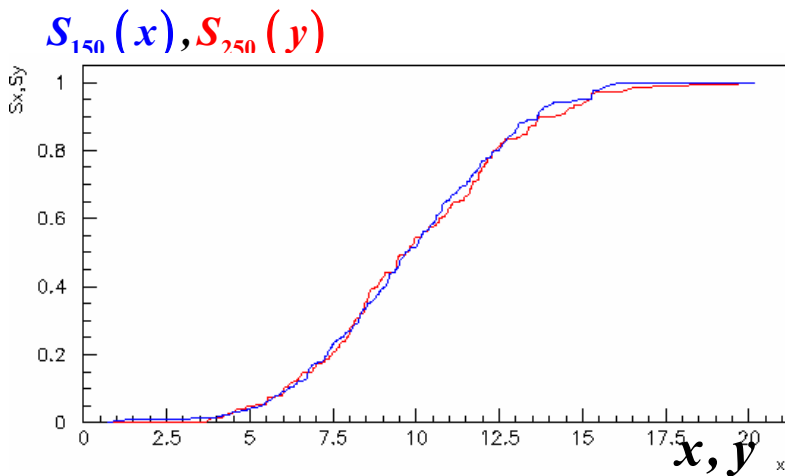
Two measurements samples  $\underline{x} = (x_1, x_2, \dots, x_n)$  and  $\underline{y} = (y_1, y_2, \dots, y_m)$

$H_0$ :  $\underline{x}$  and  $\underline{y}$  are samples of the same population - have the same PDF

$H_1$ :  $H_0$  is false

Test statistics  $D_{m,n} = \text{Max}(|S_n(x) - S_m(y)|)$

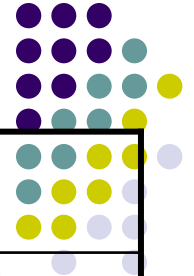
Critical zone  $D_{n,m} \geq d_{\alpha,n,m} = d_{\alpha,n} \sqrt{1 + \frac{n}{m}} = d_{\alpha,m} \sqrt{1 + \frac{m}{n}} \approx z_{\alpha} \sqrt{\frac{1}{n} + \frac{1}{m}}$  for  $n \geq 10$

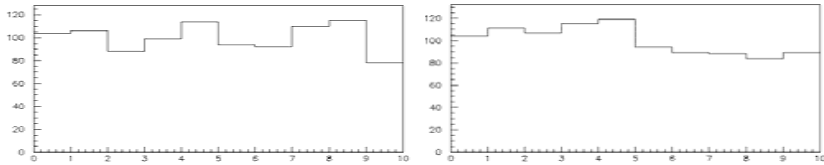


$$D_{150,250} = 0.043$$

$$d_{0.05,150,250} = z_{0.05} \sqrt{\frac{1}{m} + \frac{1}{n}} = 1.35 \sqrt{\frac{1}{150} + \frac{1}{120}} = 0.162 > 0.043$$

# Comparison between the two non-parametric tests



Pearson	Kolmogorov - Smirnov
Strictly exact pour a sample of infinite size	Strictly exact pour a sample of any size.
Partition in class → loss of information	No loss of information
<p>Test not sensitive to the sign of differences</p> 	<p>Test sensitive to the sign differences</p>
<p>Test correct if <math>K</math> parameters of model <math>f_0</math> are estimated by the least square method from the sample under test.</p> <p>The PDF of statistic <math>\chi^2</math> is know:</p> $\chi_n^2 \rightarrow \chi_{n-K}^2$	<p>Test not correct if <math>K</math> parameters of model <math>F_0</math> are estimated from the sample under test.</p> <p>The PDF of statistic <math>D_n</math> is not know.</p>

# Level of significance $\alpha$ and confidence level $C.L.$



## Pearson

$$\alpha = \int_{X_{\alpha}^2}^{\infty} \chi_v^2(x^2) dx^2$$

$$C.L. = \int_{X^2}^{\infty} \chi_v^2(x^2) dx^2$$

$$P(X^2 \leq X_{\alpha}^2) \equiv P(C.L. \geq \alpha)$$

## Kolmogorov-Smirnov

$$\alpha = 2 \sum_{k=1}^{\infty} (-1)^{k-1} e^{-2k^2 z_{\alpha}^2}$$

$$C.L. = 2 \sum_{k=1}^{\infty} (-1)^{k-1} e^{-2k^2 n D_n^2}$$

$$P\left(D_n \leq \frac{z_{\alpha}}{\sqrt{n}}\right) \equiv P(C.L. \geq \alpha)$$

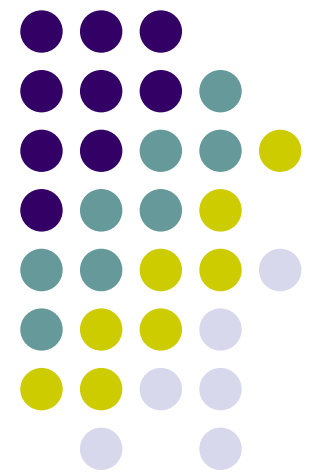
**$C.L.$  provides a straightforward probabilistic information on how well the hypothesis under test is verified**

$$C.L. = 1 - \int_{-\infty}^x f(x) dx = 1 - F(x)$$

**The PDF of  $C.L.$  is uniform on  $[0,1]$  if  $H_0$  is true**

# VI- Estimation

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## Principle of the estimation methods



Random set of measurements  $\underline{x} = (x_1, x_2, \dots, x_n)$  extracted from a population defined by  $f(x | \underline{\theta}_0)$  with  $k$  unknown true parameters  $\underline{\theta}_0 = (\theta_{0,1} \dots \theta_{0,k})$  to be estimated from the sample.

- Point estimations: best estimation set  $\hat{\underline{\theta}}$  of  $\underline{\theta}_0$  given sample  $\underline{x}$
- Variance-covariance matrix estimation  
Confidence level and confidence interval

## Définitions et notations



**True unknown value paramètre of paramter  $\theta$  :  $\theta_0$**

**Statistic:  $t = t(\underline{x}, \theta)$**

**Estimator: statistic the value of which is an estimation of paramètre  $\theta$**

**Estimation: value taken by the estimator for the observed sample  $\underline{x}$**

$$\hat{\theta} = t(\underline{x})$$

**Likelihood: joint ptobability to observe sample  $\underline{x}$  for a given value of  $\theta$**

$$\mathcal{L}(\underline{x} | \theta) = \prod_{i=1}^n f(x_i | \theta)$$

**Likelihood fonction :  $\mathcal{L}(\theta | \underline{x})$  as a fonction of  $\theta$  given the  
observed sample  $\underline{x}$**

## Confidence interval in frequentist view: Neyman belts



Given :

- a measurements sample  $\underline{x} = (x_1, x_2, \dots, x_n)$  from population  $f(x | \theta_0)$
- estimator  $t(\underline{x})$  of  $\theta_0$
- estimation  $\hat{\theta} = t(\underline{x})$  of  $\theta_0$
- $g(t | \theta)$  the PDF to observe  $t$  given  $\theta$

Knowing  $g(t | \theta)$  for all sensible values of  $\theta$ , or at least for the restricted domain of values where the experiment claims sensitivity, is mandatory for the experiment to make sens.

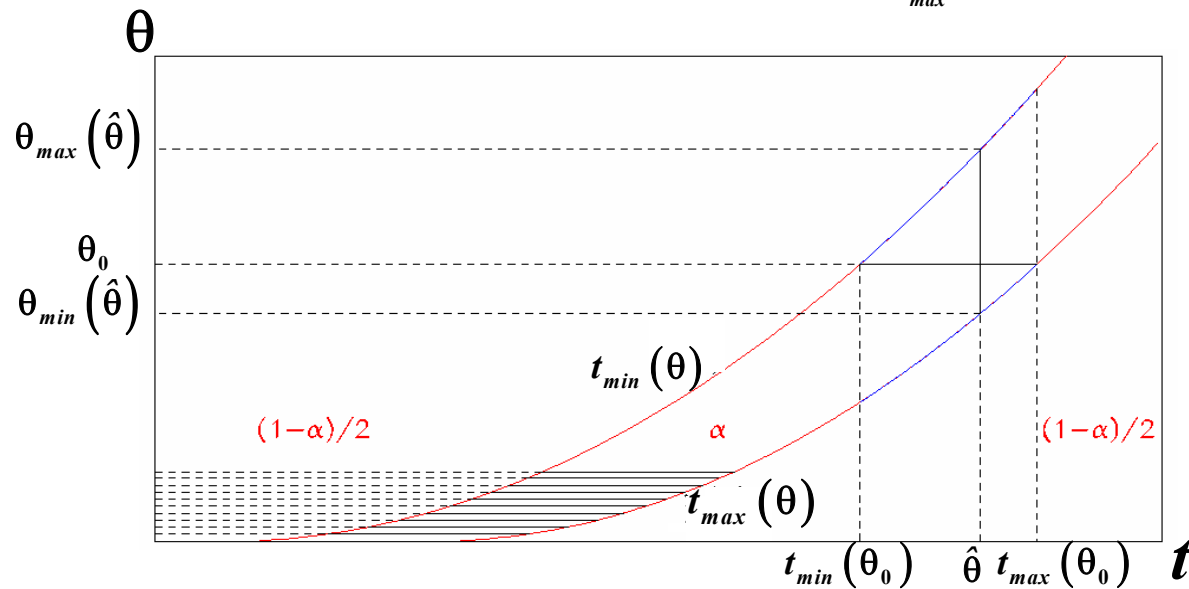
# Confidence interval in frequentist view: Neyman centred belts



Neyman belts associated to a given *C.L.*  $\alpha$

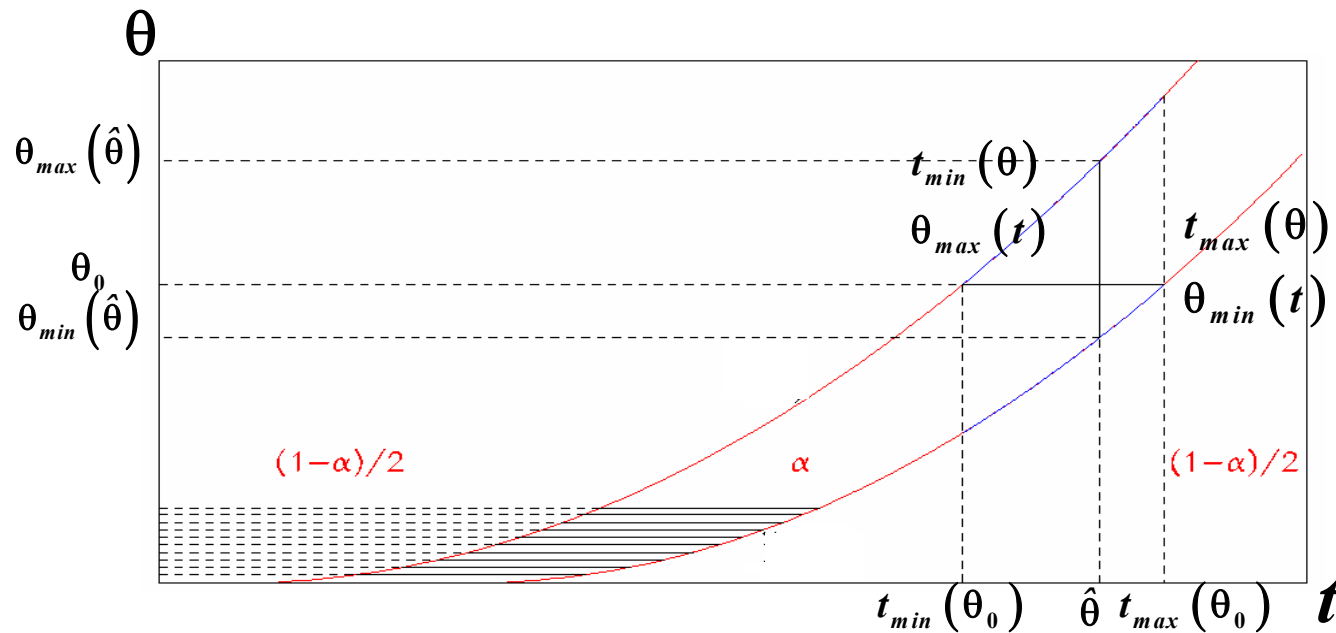
Compute for a finite values of  $\theta$  in the sensible domain  $[\theta_{min}, \theta_{max}]$  contours

$$t_{min}(\theta) \text{ and } t_{max}(\theta) \text{ such that } \int_{-\infty}^{t_{min}} g(t|\theta) dt = \int_{t_{max}}^{\infty} g(t|\theta) dt = \frac{1-\alpha}{2} \Rightarrow \int_{t_{min}}^{t_{max}} g(t|\theta) dt = \alpha$$



$$P(\hat{\theta} \in [t_{min}(\theta_0), t_{max}(\theta_0)]) = \alpha$$

# Confidence interval in frequentist view: correct interpretation



$$t_{b,a}(\theta)$$

$\Rightarrow$

$$\theta_{a,b}(t)$$

$$P(\hat{\theta} \in [t_{min}(\theta_0), t_{max}(\theta_0)]) = \alpha$$

$\Rightarrow$

$$P(\theta_0 \in [\theta_{min}(\hat{\theta}), \theta_{max}(\hat{\theta})]) = \alpha$$

$\hat{\theta}$  is a random variable

$\Rightarrow$

$\theta_0$  is a constant

$t_{min}(\theta_0), t_{max}(\theta_0)$  are unknown constants  $\Rightarrow$

$\theta_{min}(\hat{\theta}), \theta_{max}(\hat{\theta})$  are known random variables

## Confidence interval in frequentist view: correct interpretation

The experiment determines a particular interval  $[\theta_{min}, \theta_{max}]$  of values of  $\theta$  belonging to a large set of intervals that would be obtained by an ensemble of similar experiments such that a fraction  $\alpha$  of these intervals contain (covers) the true value  $\theta_0$ .

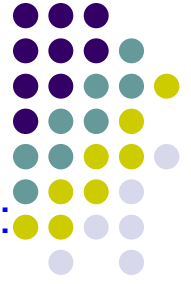


$[\theta_{min}, \theta_{max}]$  = confidence interval at  $C.L. = \alpha$

Statement  $\theta_0 \in [\theta_{min}, \theta_{max}]$  is randomly true  $\alpha\%$  of the times.

Statement  $\theta_0 \notin [\theta_{min}, \theta_{max}]$  is randomly true  $(1-\alpha)\%$  of the times.

## Confidence interval in frequentist view: Neyman upper/lower belts



The Neyman centred belts are constructed with the particular prescription:

$$\int_{-\infty}^{t_{min}} g(t | \theta) dt = \int_{t_{max}}^{\infty} g(t | \theta) dt = \frac{1 - \alpha}{2} \Rightarrow \int_{t_{min}}^{t_{max}} g(t | \theta) dt = \alpha$$

There is an infinite number of prescriptions to construct belts with correct coverage corresponding to *C.L.*  $\alpha$  that lead to different confidence intervals but are all equally correct from the statistical point of view.

The Neyman upper and lower belts are constructed with the particular prescription:

$$\int_{t_{max}}^{+\infty} g(t | \theta) dt = \alpha \qquad \int_{-\infty}^{t_{min}} g(t | \theta) dt = \alpha$$

## Probabilistic or Bayes confidence intervals



The probability to observe a value for an observable  $x$  depends on the value of parameter  $\theta$  of true unknown values  $\theta_0$  with known PDF  $P(x|\theta)$ .

Bayes' theorem states  $P(A|B)P(B) = P(B|A)P(A)$

Application to the particular observed value  $\hat{x}$  :

$P(\theta|\hat{x}) = \frac{P(\hat{x}|\theta)P(\theta)}{P(\hat{x})}$  the posteriory PDF that observation  $\hat{x}$  result from a value of  $\theta$

Bayesian credible interval  $[\theta_1, \theta_2]$  at  $C.L. = \alpha \Rightarrow \int_{\theta_1}^{\theta_2} P(\theta|\hat{x})d\theta = \alpha$

$P(\hat{x}|\theta)$  the know likelihood to observe  $\hat{x}$  given  $\theta$

$P(\hat{x})$  a normalisation factor  $\Rightarrow \int_{-\infty}^{+\infty} P(\theta|\hat{x})d\theta = 1$

$P(\theta)$  the priory PDF or prior that  $\theta$  is the true value.

What to use for  $P(\theta)$ ? Degree of believe in  $\theta$  based on ignorance, on knowledge from previous experiments, on subjectivity. The main difficulty with the Bayrsian approach is to define an objective informative prior.



## Consistent and unbiased estimators



### Consistency

$$\lim_{n \rightarrow \infty} \hat{\theta} = \theta_0$$

$$\bar{x} \rightarrow \mu, \quad s^2, S^2 \rightarrow \sigma^2$$

### Unbiasedness

$$E[\hat{\theta}] = \theta_0$$

$$E[\bar{x}] = \mu, \quad E[s^2, S^2] = \sigma^2$$

$\tau = \tau(\theta)$  univocal and reciprocal :  $\hat{\tau} = \tau(\hat{\theta})$

$$E[\tau(\hat{\theta})] \neq \tau(E[\hat{\theta}])$$

$\Rightarrow \hat{\theta}$  and  $\hat{\tau}$  are not simultaneously unbiased

## Minimal variance – Efficient estimator

Given the PDF – the narrowest, the best - and the size of the sample – the largest, the best - the minimal variance on the estimation is given by the Cramer-Rao inequality:



$$V(t) = \sigma_{\hat{\theta}}^2 = E[(t - \theta)^2] \geq \frac{1}{A(\underline{x}, \theta)}$$

$$A(\underline{x}, \theta) = E\left[\left(\frac{\partial \log \mathcal{L}}{\partial \theta}\right)^2\right] = E\left[\left(\frac{1}{\mathcal{L}} \frac{\partial \mathcal{L}}{\partial \theta}\right)^2\right] = -E\left[\frac{\partial^2 \log \mathcal{L}}{\partial \theta^2}\right]$$

Efficient estimator: variance = minimal variance

$$\frac{\partial \log \mathcal{L}}{\partial \theta} = A(\theta) \times (t - \theta)$$

↑ independent of  $\underline{x}$

$$-\frac{\partial^2 \log \mathcal{L}}{\partial \theta^2} = -\frac{\partial A}{\partial \theta}(t - \theta) + A(\theta)$$

$$E\left[-\frac{\partial^2 \log \mathcal{L}}{\partial \theta^2}\right] = -\frac{\partial A}{\partial \theta} E[t - \theta] + A(\theta) = A(\theta)$$

↑ =0 if unbiased estimator

$$V(t) = \sigma_{\hat{\theta}}^2 = \frac{1}{A(\theta)}$$

# Sufficiency



The whole information about  $\theta$  is contained in the estimator.

$$\text{Condition : } \mathcal{L}(\underline{x} | \theta) = \prod_{i=1}^n f(x_i | \theta) = g(\underline{x}) \cdot h(t(\underline{x}) | \theta)$$

no information on  $\theta$   $\uparrow$

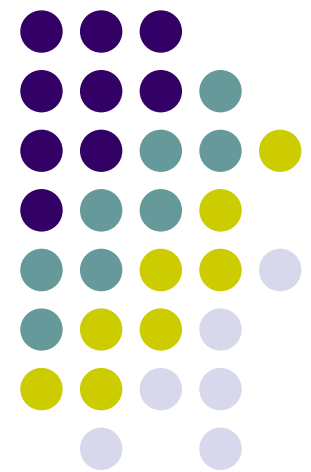
$\uparrow$  depends on  $\underline{x}$  through estimator  $t$

$$\text{Sufficiency condition } \frac{\partial \log \mathcal{L}}{\partial \theta} = \frac{\partial h(t(\underline{x}) | \theta)}{\partial \theta} \text{ contained in}$$

$$\text{Efficiency condition } \frac{\partial \log \mathcal{L}}{\partial \theta} = A(\theta) \times (t - \theta)$$

# VII - Maximum Likelihood

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# Principle of the maximum likelihood method



Random set of  $n$  measurements  $\underline{x} = (x_1, x_2, \dots, x_n)$  extracted from a population defined by  $f(x | \underline{\theta}_0)$

with  $k$  unknown true parameters  $\underline{\theta}_0 = (\theta_{0,1} \dots \theta_{0,k})$  to be estimated from the sample.

Likelihood function  $\mathcal{L}(\underline{x} | \underline{\theta}) = \prod_{i=1}^n f(x_i | \underline{\theta})$  calculable for any set of values  $\underline{\theta}$

Estimation  $\hat{\underline{\theta}}$  of  $\underline{\theta}$  maximises  $\mathcal{L}(\underline{x} | \underline{\theta})$  and thus  $\log \mathcal{L}(\underline{x} | \underline{\theta})$ , given  $\underline{x}$

$$\left. \begin{aligned} \frac{\partial \log \mathcal{L}(\underline{\theta})}{\partial \theta_j} \Big|_{\underline{\theta}=\hat{\underline{\theta}}} &= \sum_{i=1}^n \frac{\partial \log f(x_i | \underline{\theta})}{\partial \theta_j} \Big|_{\underline{\theta}=\hat{\underline{\theta}}} = 0 \\ \frac{\partial^2 \log \mathcal{L}(\underline{\theta})}{\partial \theta_j^2} \Big|_{\underline{\theta}=\hat{\underline{\theta}}} &= \sum_{i=1}^n \frac{\partial^2 \log f(x_i | \underline{\theta})}{\partial \theta_j^2} \Big|_{\underline{\theta}=\hat{\underline{\theta}}} < 0 \end{aligned} \right\} j = 1, k$$

## Invariance of the solution



Conservation of probability  $\mathcal{L}(\underline{x} | \theta) = \mathcal{L}(\underline{x} | \tau(\theta))$

Call  $\tau^* = \tau(\hat{\theta})$

$$\mathcal{L}(\tau^*) = \mathcal{L}(\tau(\hat{\theta})) = \mathcal{L}(\hat{\theta}) \geq \mathcal{L}(\theta) = \mathcal{L}(\tau(\theta))$$

$$\mathcal{L}(\tau^*) \geq \mathcal{L}(\tau) \quad \forall \tau \quad \Rightarrow \tau^* = \hat{\tau}$$

**If  $\tau = \tau(\theta)$  univocal and reciprocal  $\Rightarrow \hat{\tau} = \tau(\hat{\theta})$**

## Example of analytic solution: mean and variance of a gaussian



$$\underline{x} = (x_1, x_2, \dots, x_n) \text{ sample from } f(x | \mu, \sigma^2) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{1}{2} \frac{(x-\mu)^2}{\sigma^2}}$$

$$\mathcal{L}(\underline{x} | \mu, \sigma^2) = \left( \frac{1}{\sqrt{2\pi\sigma^2}} \right)^n \prod_{i=1}^n e^{-\frac{1}{2} \frac{(x_i - \mu)^2}{\sigma^2}}$$

$$\log \mathcal{L}(\mu, \sigma^2) = -\frac{n}{2} \left( \log 2\pi + \log \sigma^2 + \frac{1}{n} \sum_{i=1}^n \frac{(x_i - \mu)^2}{\sigma^2} \right)$$

$$\frac{\partial \log \mathcal{L}}{\partial \mu} = \frac{\sum_{i=1}^n x_i - n\mu}{\sigma^2} = 0 \Rightarrow \hat{\mu} = \bar{x} = \frac{1}{n} \sum_{i=1}^n x_i$$

$$\frac{\partial \log \mathcal{L}}{\partial \sigma^2} = -\frac{n}{2\sigma^2} + \frac{\sum_{i=1}^n (x_i - \mu)^2}{2\sigma^4} = 0$$

$$\text{replace } \mu \text{ by } \bar{x} : -\frac{n}{2\sigma^2} + \frac{\sum_{i=1}^n (x_i - \bar{x})^2}{2\sigma^4} = 0 \Rightarrow \hat{\sigma}^2 = s'^2 = \frac{1}{n} \sum_{i=1}^n (x_i - \bar{x})^2$$

$$s'^2 \text{ biased: } E[s'^2] = \frac{n-1}{n} \sigma^2$$

## Example of analytic solution: weighted mean and standard error



$\hat{\theta}_1, \dots, \hat{\theta}_n$   $n$  estimations of  $\theta$  with standard errors  $\sigma_1, \dots, \sigma_n$

How to combine the measurements into  $\hat{\theta} \pm \sigma_{\hat{\theta}}$ ?

Each  $\hat{\theta}_i$  is extracted from PDF  $N(\theta_0, \sigma_i^2)$

$$\mathcal{L}(\underline{\hat{\theta}} | \theta) = \prod_{i=1}^n \frac{1}{\sqrt{2\pi\sigma_i^2}} e^{-\frac{1}{2} \frac{(\hat{\theta}_i - \theta)^2}{\sigma_i^2}}$$

$$\log \mathcal{L} = -\frac{1}{2} \sum_{i=1}^n \frac{(\hat{\theta}_i - \theta)^2}{\sigma_i^2} + \text{Cste}$$

$$\frac{\partial \log \mathcal{L}}{\partial \theta} = \sum_{i=1}^n \frac{\hat{\theta}_i - \theta}{\sigma_i^2} = 0$$

$$\hat{\theta} = \frac{\sum_{i=1}^n \frac{\hat{\theta}_i}{\sigma_i^2}}{\sum_{i=1}^n \frac{1}{\sigma_i^2}} \quad \text{weighted means with weights } \frac{1}{\sigma_i^2}$$

$$\frac{\partial \log \mathcal{L}}{\partial \theta} = \sum_{i=1}^n \frac{1}{\sigma_i^2} (\hat{\theta} - \theta) \Rightarrow A(\theta) = \sum_{i=1}^n \frac{1}{\sigma_i^2} \Rightarrow$$

$$\sigma_{\hat{\theta}}^2 = \frac{1}{\sum_{i=1}^n \frac{1}{\sigma_i^2}} \Rightarrow \sigma_{\hat{\theta}} = \sqrt{\frac{1}{\sum_{i=1}^n \frac{1}{\sigma_i^2}}}$$



# Asymptotic Consistency, Efficiency, Sufficiency, Normality of $\mathcal{L}$



For  $n \rightarrow \infty$  :

**consistency:**  $\lim_{n \rightarrow \infty} \hat{\theta} = \theta_0$

**efficiency :**  $\frac{\partial \log \mathcal{L}}{\partial \theta} = A(\theta) \times (t - \theta)$  and  $V(t) = \sigma_\theta^2 = \frac{1}{A(\theta)}$

**sufficiency :** from efficiency

**normality :**  $\mathcal{L}(\theta | \underline{x}) = \prod_{i=1}^n f(\theta | x_i)$  takes the shape  $\mathcal{L}(\theta) = N(\hat{\theta}, \sigma_\theta^2) = \frac{1}{\sqrt{2\pi\sigma_\theta^2}} e^{-\frac{1}{2} \frac{(\hat{\theta} - \theta)^2}{\sigma_\theta^2}}$

$$\log \mathcal{L}(\theta) = -\frac{1}{2} \frac{(\hat{\theta} - \theta)^2}{\sigma_\theta^2} - \kappa$$

$$\frac{\partial \log \mathcal{L}(\theta)}{\partial \theta} = \frac{\hat{\theta} - \theta}{\sigma_\theta^2} \quad \sigma_\theta^2 = - \left( \frac{\partial^2 \log \mathcal{L}(\theta)}{\partial \theta^2} \right)^{-1}$$

**Analytical resolution possible only if  $\frac{\partial \log \mathcal{L}(\theta)}{\partial \theta}$  and  $\frac{\partial^2 \log \mathcal{L}(\theta)}{\partial \theta^2}$  are analytical**

# Asymptotic Consistency, Efficiency, Sufficiency, Normality of $\mathcal{L}$



If  $k$  parameters  $\underline{\theta} = (\theta_1, \dots, \theta_k)$

$$\left. \begin{aligned} \frac{\partial \log \mathcal{L}(\underline{\theta})}{\partial \theta_i} &= \frac{\hat{\theta}_i - \theta_i}{\sigma_{\theta_i}^2} \\ \sigma_{\theta_j}^2 &= - \left( \frac{\partial^2 \log \mathcal{L}(\underline{\theta})}{\partial \theta_j^2} \right)^{-1} \\ \sigma_{\theta_i \theta_j} &= - \left( \frac{\partial^2 \log \mathcal{L}(\underline{\theta})}{\partial \theta_i \partial \theta_j} \right)^{-1} \end{aligned} \right\} i, j = 1, k$$

## Asymptotic normality : numerical estimation of the confidence interval

If  $\partial_{\theta} \log \mathcal{L}(\theta)$  and  $\partial_{\theta^2} \log \mathcal{L}(\theta)$  cannot be calculated analytically



$$\log \mathcal{L}^*(\theta) = \log \mathcal{L}(\theta) + \kappa = -\frac{1}{2} \frac{(\hat{\theta} - \theta)^2}{\sigma_{\theta}^2} \quad \text{is a parabol}$$

**Point estimation:**

$$\hat{\theta} \Leftrightarrow \log \mathcal{L}^*(\hat{\theta}) = 0$$

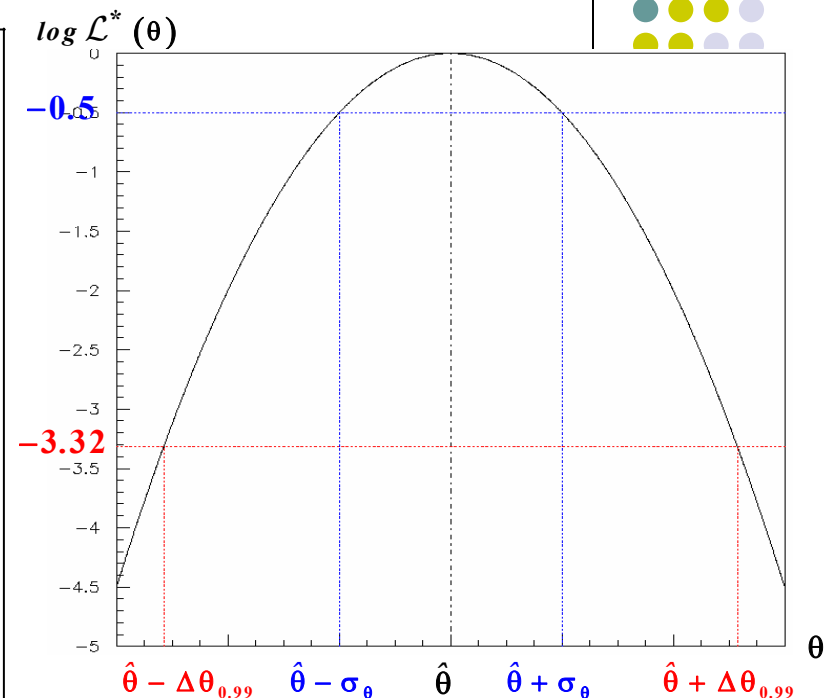
**Standard error = Confidence interval at C.L. = 0.683**

$$\log \mathcal{L}^*(\theta^{\pm}) = -\frac{1}{2} \Rightarrow \sigma_{\theta} = |\theta^{\pm} - \hat{\theta}|$$

**Confidence interval at C.L. =  $\alpha$**

$$r_{\alpha} \rightarrow \alpha = \int_{-r_{\alpha}}^{r_{\alpha}} N(0,1) dx \quad \text{or equivalently} \quad \int_0^{r_{\alpha}^2} f(\chi_1^2) d\chi_1^2$$

$$\log \mathcal{L}^*(\theta^{\pm}) = -\frac{r_{\alpha}^2}{2} \Rightarrow \Delta\theta_{\alpha} = |\theta^{\pm} - \hat{\theta}| \quad \text{at C.L.} = \alpha$$



$\alpha$	$r_{\alpha}$	$r_{\alpha}^2/2$
0.683	1	0.5
0.900	1.65	1.35
0.950	1.96	1.92
0.990	2.58	3.32
0.999	3.29	5.41

$$\text{Scaling relation : } \Delta\theta_{\alpha} = r_{\alpha} \sigma_{\theta} = \frac{r_{\alpha}}{r_{\alpha'}} \Delta\theta_{\alpha'}$$

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## Small samples : numerical estimation of the confidence interval



$n$  small  $\Rightarrow \log \mathcal{L}^*(\theta) \neq$  parabol

Assume  $\tau = \tau(\theta)$  univocal and reciprocal such that  $\log \mathcal{L}^*(\tau) = -\frac{1}{2} \frac{(\hat{\tau} - \tau)^2}{\sigma_\tau^2}$

$$\hat{\tau} \Leftrightarrow \log \mathcal{L}^*(\hat{\tau}) = 0$$

$$\log \mathcal{L}^*(\tau^\pm) = -\frac{1}{2} \Rightarrow \sigma_\tau = |\tau^\pm - \hat{\tau}| \sigma_\tau$$

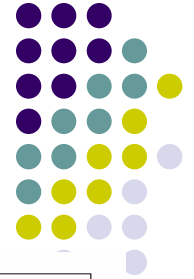
**Standard error results** from probability conservation:

$\log \mathcal{L}^*(\tau^+) = \log \mathcal{L}^*(\tau^{-1}(\tau^+) = \theta^+) = -\frac{1}{2}, \quad \sigma_\theta^+ = \theta^+ - \hat{\theta}$	$P(\theta_0 \in [\theta^-, \theta^+]) = 0.683$ $\theta = \hat{\theta}_{-\sigma_\theta^-}^{+\sigma_\theta^+}$
$\log \mathcal{L}^*(\tau^-) = \log \mathcal{L}^*(\tau^{-1}(\tau^-) = \theta^-) = -\frac{1}{2}, \quad \sigma_\theta^- = \theta^- - \hat{\theta}$	

**Confidence interval at C.L. =  $\alpha$**  : get  $r_\alpha \rightarrow \alpha = \int_{-r_\alpha}^{r_\alpha} N(0,1) dx$  or equivalently  $\int_0^{r_\alpha^2} f(\chi_1^2) d\chi_1^2$

$$\left. \begin{aligned} \log \mathcal{L}^*(\theta_\alpha^+) &= -\frac{r_\alpha^2}{2} \Rightarrow \Delta\theta_\alpha^+ = |\theta_\alpha^+ - \hat{\theta}| \\ \log \mathcal{L}^*(\theta_\alpha^-) &= -\frac{r_\alpha^2}{2} \Rightarrow \Delta\theta_\alpha^- = |\theta_\alpha^- - \hat{\theta}| \end{aligned} \right\} \text{at C.L.} = \alpha \Rightarrow P(\theta_0 \in [\theta_\alpha^-, \theta_\alpha^+]) = \alpha$$

## Example of small sample : confidence interval on the variance of a normal PDF

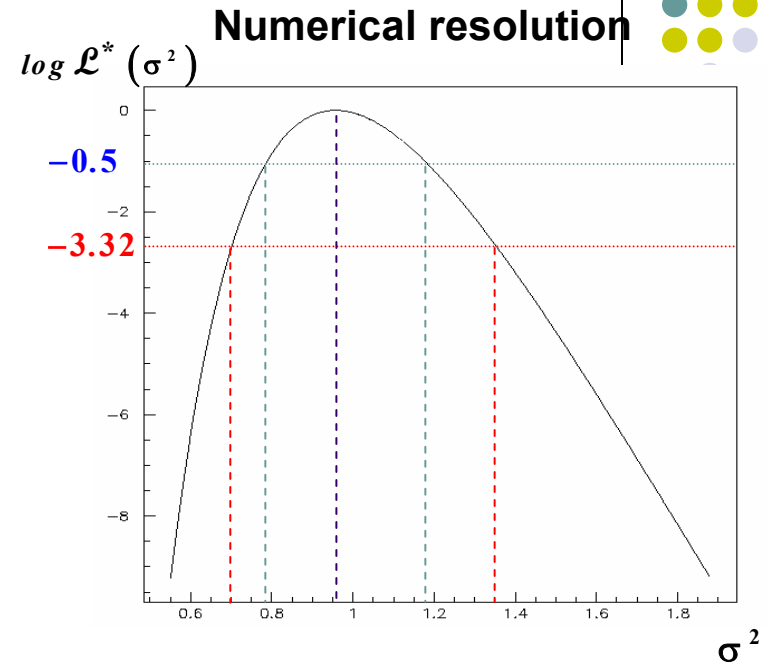


Random sample of  $n = 100$  extracted from  $N(0,1)$

Analytical resolution

$$\sigma^2 = 0.96 \pm 0.14$$

but  $P(\sigma_0^2 \in [0.96 - 0.14, 0.96 + 0.14]) \neq 0.683$



but

$$\Delta\theta_{0.99}^+ = 0.46 > \sigma^+ \times r_{0.99} = 0.15 \times 2.58 = 0.39$$

$$\Delta\theta_{0.99}^- = 0.28 < \sigma^- \times r_{0.99} = 0.12 \times 2.58 = 0.31$$

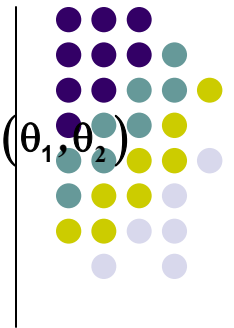
Confidence interval at  $C.L. = 0.683$  :  $0.96_{-0.12}^{+0.15}$

Confidence interval at  $C.L. = 0.99$  :  $0.96_{-0.28}^{+0.46}$

**No scaling relation between the size of the confidence interval and the  $C.L.$**

$$\Delta\theta_{\alpha}^+ \neq r_{\alpha} \sigma_{\theta}^+ \quad \Delta\theta_{\alpha}^- \neq r_{\alpha} \sigma_{\theta}^- \quad \frac{\Delta\theta_{\alpha}^+}{\sigma_{\theta}^+} \neq \frac{\Delta\theta_{\alpha}^-}{\sigma_{\theta}^-}$$

## Asymptotic normality : extension to two independent variables



Asymptotic likelihood function for large samples and two independent variables  $\theta = (\theta_1, \theta_2)$

$$\mathcal{L}(\theta_1, \theta_2 \mid \hat{\theta}_1, \hat{\theta}_2) = \frac{1}{2\pi\sqrt{\sigma_1^2\sigma_2^2}} e^{-\frac{1}{2}\left(\frac{(\theta_1 - \hat{\theta}_1)^2}{\sigma_1^2} + \frac{(\theta_2 - \hat{\theta}_2)^2}{\sigma_2^2}\right)}$$

$$\log L^*(\theta_1, \theta_2) = \log L(\theta_1, \theta_2) + \kappa = -\frac{1}{2} \sum_{i=1,2} \frac{(\theta_i - \hat{\theta}_i)^2}{\sigma_i^2} \text{ is a paraboloid}$$

**Point estimation:**  $\hat{\theta} \Rightarrow \log \mathcal{L}^*(\hat{\theta}) = 0$

**Confidence interval at C.L. =  $\alpha$**

$$-2 \log \mathcal{L}^*(\theta_1, \theta_2) = \sum_{i=1,2} \frac{(\theta_i - \hat{\theta}_i)^2}{\sigma_i^2} \text{ follows a } \chi_2^2 \text{ PDF}$$

$$r_\alpha^2 \Rightarrow \int_0^{r_\alpha^2} f(\chi_2^2) d\chi_2^2 = \alpha$$

**confidence interval: area contained in the ellipse defined by**

intersection of  $\begin{cases} \text{paraboloid } \log \mathcal{L}^*(\theta_1, \theta_2) \\ \text{plane } \log \mathcal{L}^*(\theta_1, \theta_2) = -\frac{r_\alpha^2}{2} \end{cases}$

$\alpha$	$r_\alpha$	$r_\alpha^2 r_\alpha / 2$
0.393	1.00	0.50
0.632	1.41	1.00
0.683	1.51	1.14
0.865	2.00	2.00
0.900	2.14	2.30
0.950	2.45	3.00
0.990	3.03	4.60

# Example : confidence interval for mean and variance of a $N(0,1)$

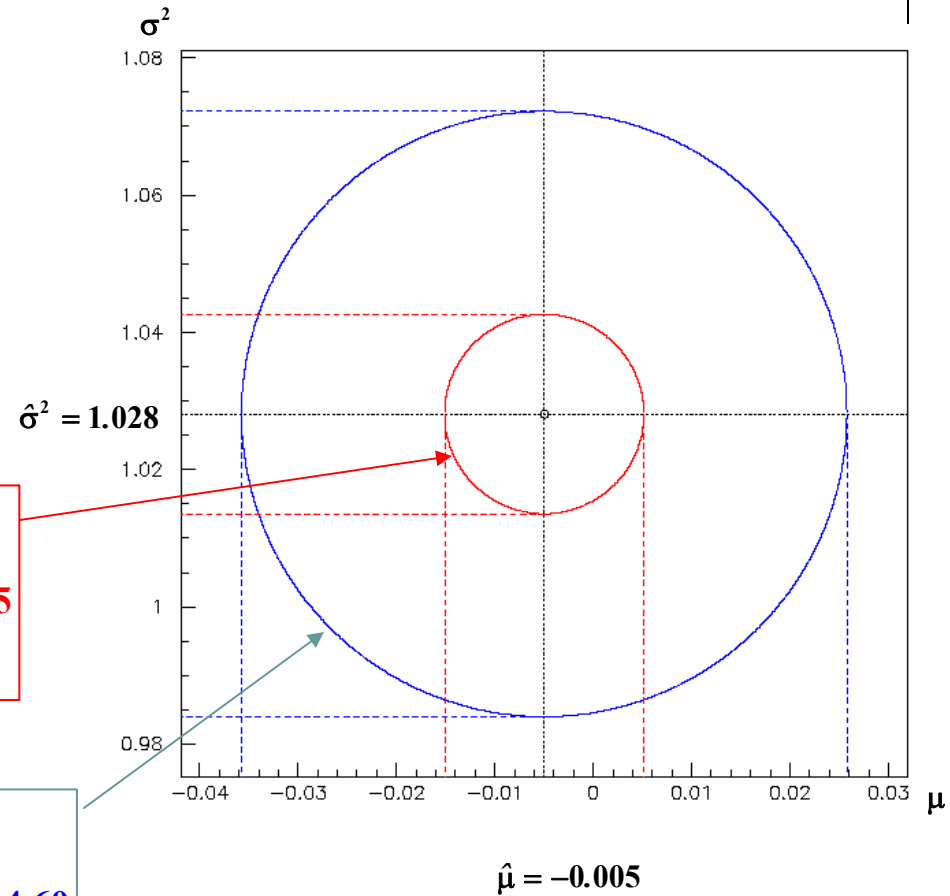


## Analytic method

$$\hat{\mu} = \bar{x} = 0.005 \pm 0.010$$

$$\hat{\sigma}^2 = s'^2 = 1.028 \pm 0.015$$

## Numeric method



$$r_{\alpha} = 1$$

$$\log \mathcal{L}^*(\theta) = -\frac{r_{\alpha}^2}{2} = -0.5$$

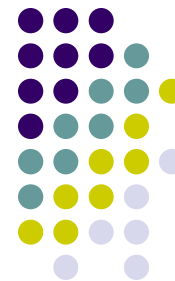
$$\alpha = 0.393$$

$$r_{\alpha} = 3.03$$

$$\log \mathcal{L}^*(\theta) = -\frac{r_{\alpha}^2}{2} = -4.60$$

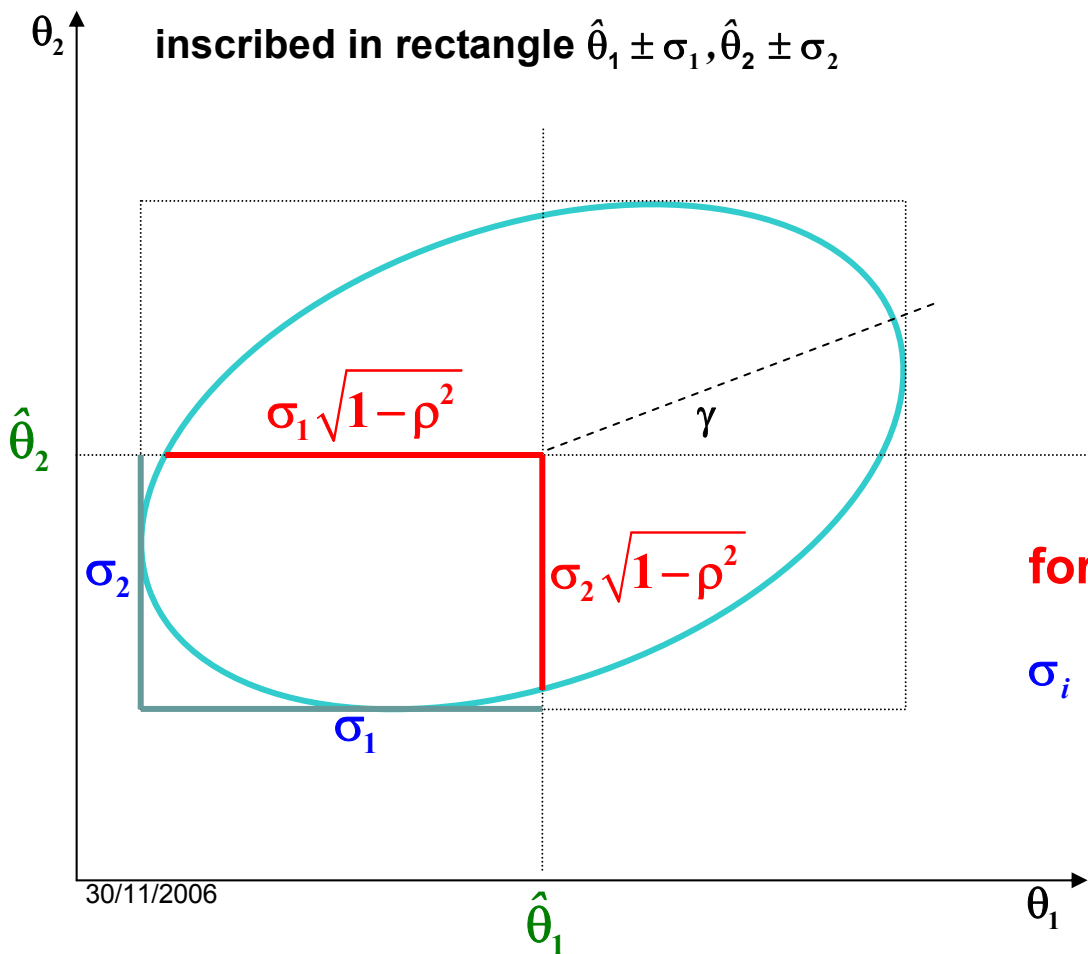
$$\alpha = 0.99$$

## Asymptotic normality : extension to two correlated variables



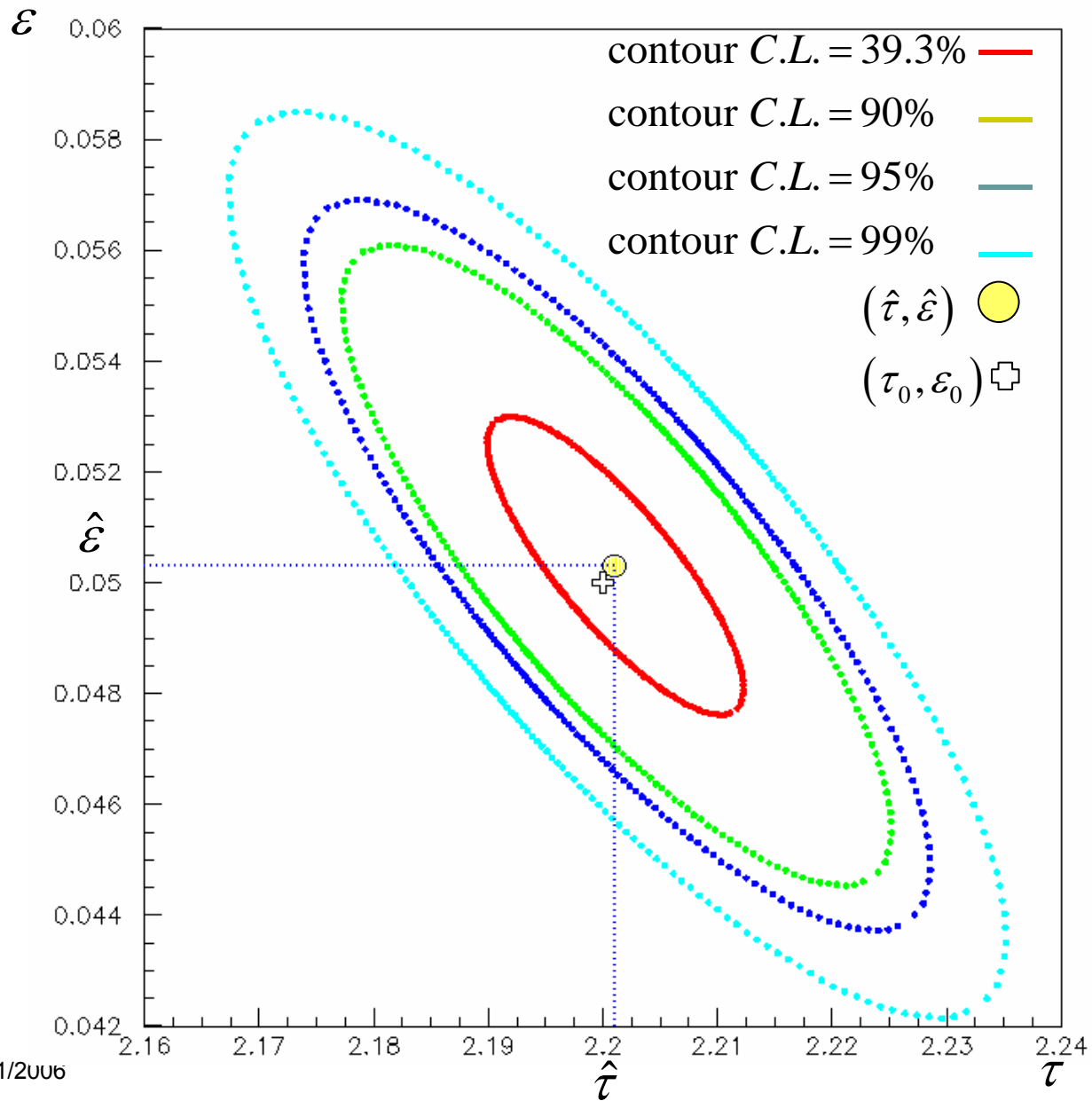
Contour  $\log \mathcal{L}^*(\theta_1, \theta_2) = -\frac{1}{2(1-\rho^2)} \left( \frac{(\theta_1 - \hat{\theta}_1)^2}{\sigma_1^2} + \frac{(\theta_2 - \hat{\theta}_2)^2}{\sigma_2^2} - 2\rho \frac{(\theta_1 - \hat{\theta}_1)(\theta_2 - \hat{\theta}_2)}{\sigma_1 \sigma_2} \right) = -\frac{1}{2}$

ellipse centred on  $(\hat{\theta}_1, \hat{\theta}_2)$  with  $\tan(2\gamma) = \frac{2\rho\sigma_1\sigma_2}{\sigma_1^2 - \sigma_2^2}$





# Asymptotic normality : extension to two correlated variables

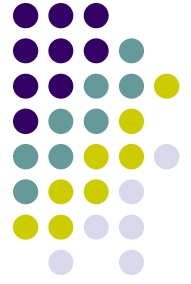


## Extension to small samples and $N$ correlated variables

Method stays formally correct :  $\chi_2^2 \rightarrow \chi_N^2$

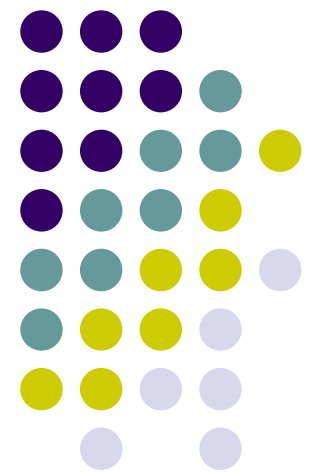
$$r_\alpha \Rightarrow \int_0^{r_\alpha^2} f(\chi_N^2) d\chi_N^2 = \alpha$$

Difficult in practice if  $n$  small,  $N$  large et correlations



# VIII – Least Squares Method

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# Principle of the least squares method



- $y = f(x | \underline{\theta}_0)$  functional relation between variables  $y$  and  $x$
- $k$  unknown parameters  $\underline{\theta} = (\theta_1, \theta_2, \dots, \theta_k)$  of true values  $\underline{\theta}_0$
- $\underline{y} = (y_1, \dots, y_n)$  the  $n > k$  measured values of  $f(x | \underline{\theta})$  at points  $\underline{x} = (x_1, \dots, x_n)$  with standard errors  $\underline{\sigma} = (\sigma_1, \dots, \sigma_n)$
- PDF of  $y_i : N(f(x_i | \underline{\theta}_0), \sigma_i^2)$

Estimations  $\hat{\underline{\theta}}$  of  $\underline{\theta}_0$  minimise

$$X^2(\underline{\theta}) = \sum_{i=1}^n \frac{(y_i - f(x_i | \underline{\theta}))^2}{\sigma_i^2} \quad \text{given } \underline{y} \pm \underline{\sigma}$$

## Example : histogram

$$X^2(\underline{\theta}) = \sum_{i=1}^N \frac{(n_i - np_{0i}(\underline{\theta}))^2}{np_i(\underline{\theta})}$$

$n_i =$  number of events in class  $[X_i \leq x \leq X_{i+1}]$

$$n = \sum_{i=1}^N n_i$$

$$p_{0i}(\underline{\theta}) = \int_{X_i}^{X_{i+1}} f(x | \underline{\theta}) dx$$

## Equivalence between least squares and maximum likelihood for large samples

Large samples  $\Rightarrow$  gaussian approximation of  $\mathcal{L}$

$$\mathcal{L}(\underline{\theta}) = \prod_{i=1}^n \frac{1}{\sqrt{2\pi\sigma_i^2}} e^{-\frac{1}{2} \frac{(y_i - f(x_i|\underline{\theta}))^2}{\sigma_i^2}}$$

$$\log \mathcal{L}^*(\underline{\theta}) = -\frac{1}{2} \sum_{i=1}^n \frac{(y_i - f(x_i|\underline{\theta}))^2}{\sigma_i^2}$$

$$X^2(\underline{\theta}) = \sum_{i=1}^n \frac{(y_i - f(x_i|\underline{\theta}))^2}{\sigma_i^2}$$

$$\boxed{-2 \log \mathcal{L}^*(\underline{\theta}) = X^2(\underline{\theta})}$$

The least squares method is asymptotically coherent, efficient and sufficient

### Maximum likelihood

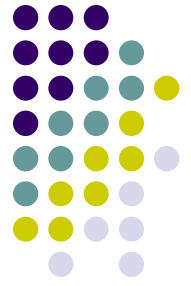
intersection of  $\log \mathcal{L}^*(\underline{\theta})$  with hyperplan parallel to  $(\underline{\theta})$  at  $\log \mathcal{L}^*(\underline{\theta}) = -r_\alpha^2/2$

### Least squares

intersection of  $X^2(\underline{\theta})$  with hyperplan parallel to  $(\underline{\theta})$  at  $X^2(\underline{\theta}) = \text{Min}(X^2(\underline{\theta})) + r_\alpha^2$

$$r_\alpha^2 \Rightarrow \int_0^{r_\alpha^2} f(\chi_k^2) d\chi_k^2 = \alpha$$

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## Analytical resolution of the linear model



- $y = f(x) = \sum_{l=1}^L a_l(x) \theta_l$

$$X^2(\underline{\theta}) = \sum_{n=1}^N \frac{\left( y_n - \sum_{l=1}^L a_{nl} \theta_l \right)^2}{\sigma_n^2} \quad \text{with } a_{nl} = a_l(x_n)$$

$$= (\underline{y} - A\underline{\theta})^T V^{-1} (\underline{y} - A\underline{\theta}) \quad \text{Matrix notation also valid for correlated parameters}$$

$$A = \begin{pmatrix} a_{11} & \cdots & a_{1L} \\ \vdots & \ddots & \vdots \\ a_{N1} & \cdots & a_{NL} \end{pmatrix}$$

and

$$V = \begin{pmatrix} \sigma_1^2 & \cdots & \sigma_{1N} \\ \vdots & \ddots & \vdots \\ \sigma_{N1} & \cdots & \sigma_N^2 \end{pmatrix}$$

### Point estimations

$$\frac{\partial X^2(\underline{\theta})}{\partial \underline{\theta}} = -2A^T V^{-1} \underline{y} + 2A^T V^{-1} A \underline{\theta} = \mathbf{0} \quad \Rightarrow \quad \underline{\hat{\theta}} = (A^T V^{-1} A)^{-1} A^T V^{-1} \underline{y}$$

### Variances

$$\underline{\hat{\theta}} = f(\underline{y})$$

$$V(\underline{\hat{\theta}}) = \left( \frac{\partial \underline{\hat{\theta}}}{\partial \underline{y}} \right) V \left( \frac{\partial \underline{\hat{\theta}}}{\partial \underline{y}} \right)^T = \left( (A^T V^{-1} A)^{-1} A^T V^{-1} \right) V \left( (A^T V^{-1} A)^{-1} A^T V^{-1} \right)^T$$

$$V(\underline{\hat{\theta}}) = (A^T V^{-1} A)^{-1}$$

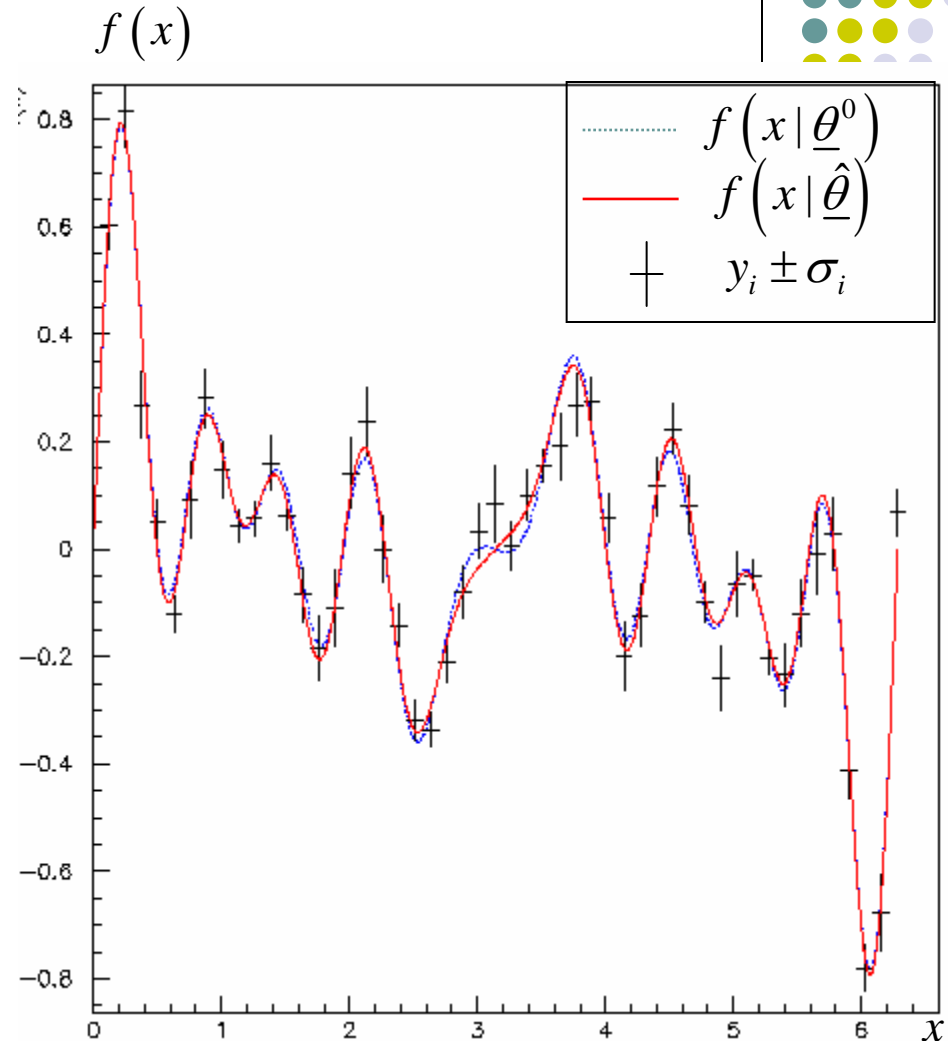
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## Example: superposition de 10 sinusoids of known frequencies



- $f(x | \underline{\theta}^0) = \sum_{l=1}^{10} \sin(\omega_l x) \theta_l^0$        $L = 10$
- $y_i \pm \sigma_i, i = 1, N = 50$

$\omega$	$\theta^0$	$\hat{\theta}$	$\sigma(\hat{\theta})$
1.0	0.040	0.034	0.010
2.0	0.182	0.175	0.010
3.0	0.026	0.028	0.010
4.0	0.123	0.126	0.009
5.0	0.041	0.028	0.010
6.0	0.116	0.130	0.010
7.0	0.174	0.178	0.009
8.0	0.032	0.037	0.010
9.0	0.158	0.149	0.009
10.0	0.107	0.116	0.010



## The non-linear model with constraints



### System of $M = N + L$ parameters

- $N$  measurable parameters  
estimations  
covariance matrix  
 $\underline{\eta} = (\eta_1, \eta_2, \dots, \eta_N)$   
 $\hat{\underline{\eta}} = (\hat{\eta}_1, \hat{\eta}_2, \dots, \hat{\eta}_N)$   
 $V_{\hat{\eta}}$
- $L$  non-measurable parameters  
 $\underline{\theta} = (\theta_1, \theta_2, \dots, \theta_L)$
- $K > L$  constraints between the  $M$  parameters  $\underline{f}(\underline{\eta}, \underline{\theta}) = \mathbf{0}$

### Purpose :

- improved estimation of the  $N$  measurable parameters  $\hat{\underline{\eta}}$
- estimation of the  $L$  non-measurable parameters  $\hat{\underline{\theta}}$
- calculation of the covariance matrix between the  $M = N + L$  parameters



## The non-linear model with constraints : Example



Kinematical analysis of 2-body  $\rightarrow F$ -body

$$M = 2 + F \text{ bodies}$$

Number of variables :  $4 \times M$

$$(p_m, \theta_m, \phi_m, E_m), m = 1, M$$

$K = 4$  constraints : energy-momentum conservation

$$\sum_{i=1}^2 p_i \sin \theta_i \cos \phi_i - \sum_{f=1}^F p_f \sin \theta_f \cos \phi_f = 0$$

$$\sum_{i=1}^2 p_i \sin \theta_i \sin \phi_i - \sum_{f=1}^F p_f \sin \theta_f \sin \phi_f = 0$$

$$\sum_{i=1}^2 p_i \cos \theta_i - \sum_{f=1}^F p_f \cos \theta_f = 0$$

$$\sum_{i=1}^2 E_i - \sum_{f=1}^F E_f = 0$$

$L$  unmeasurable variables

$L > 4$  : undefined system

$L = 4$  : solvable system

$L < 4$  : adjustable system with least squares method

If the particles are identified, there masses are known and the number of variables is

reduced to  $3 \times M$  or equivalently, there  $M$  additional constraints  $E_m^2 = p_m^2 + m_m^2, m = 1, M$ .

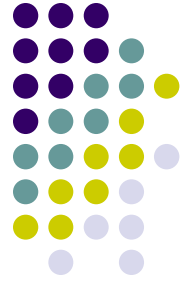
## Lagrange parameters method

$$\left. \begin{array}{l}
 K \text{ constraints } \underline{f}(\underline{\eta}, \underline{\theta}) = \mathbf{0} \\
 \text{minimisation of } X^2 = (\underline{\hat{\eta}} - \underline{\eta})^T V_{\hat{\eta}}^{-1} (\underline{\hat{\eta}} - \underline{\eta}) \\
 \text{minimisation of } X'^2 = (\underline{\hat{\eta}} - \underline{\eta})^T V_{\hat{\eta}}^{-1} (\underline{\hat{\eta}} - \underline{\eta}) + 2\underline{\lambda}^T \underline{f}(\underline{\eta}, \underline{\theta}) \\
 K \text{ additional unknown parameters of Lagrange } \underline{\lambda}
 \end{array} \right\} \Rightarrow$$

Minimisation of  $X'^2$ :

$$\left. \begin{array}{l}
 \frac{\partial X'^2}{\partial \underline{\eta}} = -2V_{\hat{\eta}}^{-1} (\underline{\hat{\eta}} - \underline{\eta}) + 2\underline{f}_{\eta}^T \underline{\lambda} = \mathbf{0} \\
 \frac{\partial X'^2}{\partial \underline{\theta}} = 2\underline{f}_{\theta}^T \underline{\lambda} = \mathbf{0} \\
 \frac{\partial X'^2}{\partial \underline{\lambda}} = 2\underline{f} = \mathbf{0}
 \end{array} \right\} \begin{array}{l}
 N + K + L \text{ normal equations} \\
 N + K + L \text{ unknowns} \\
 \underline{\eta}, \underline{\theta}, \underline{\lambda}
 \end{array}$$

$$\text{with } \left\{ \begin{array}{l}
 (\underline{f}_{\eta})_{kn} = \frac{\partial f_k}{\partial \eta_n} \quad K \times N \text{ matrix} \\
 (\underline{f}_{\theta})_{kl} = \frac{\partial f_k}{\partial \theta_l} \quad K \times L \text{ matrix}
 \end{array} \right.$$



## Lagrange parameters method : iterative procedure

$\underline{f}^{(v)} \equiv \underline{f}(\underline{\eta}^{(v)}, \underline{\theta}^{(v)})$  at iteration  $v$

$$\left. \begin{aligned} V_{\hat{\eta}}^{-1} (\underline{\eta}^{(v+1)} - \hat{\underline{\eta}}) + \underline{f}_{\eta}^{(v)T} \underline{\lambda}^{(v+1)} &= \mathbf{0} \\ \underline{f}_{\theta}^{(v)T} \underline{\lambda}^{(v+1)} &= \mathbf{0} \\ \underline{f}^{(v+1)} &= \underline{f}^{(v)} + \underline{f}_{\eta}^{(v)} (\underline{\eta}^{(v+1)} - \underline{\eta}^{(v)}) + \underline{f}_{\theta}^{(v)} (\underline{\theta}^{(v+1)} - \underline{\theta}^{(v)}) \end{aligned} \right\} \begin{array}{l} N + K + L \text{ normal equations} \\ N + K + L \text{ unknowns} \\ \underline{\eta}^{(v+1)}, \underline{\theta}^{(v+1)}, \underline{\lambda}^{(v+1)} \end{array}$$

### Iteration 0

$$\underline{\eta}^{(0)} = \hat{\underline{\eta}}$$

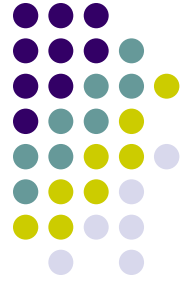
$\underline{\theta}^{(0)}$  : solution of a subset of  $L$  among  $K$  constraints

$$\underline{\lambda}^{(0)} = \underline{I}_K \text{ arbitrarily}$$

### Conditions to stop the iterative process at iteration $v+1$

$$\left\{ \begin{array}{l} \left| \theta_l^{(v+1)} - \theta_l^{(v)} \right| \text{ or } \frac{\left| \theta_l^{(v+1)} - \theta_l^{(v)} \right|}{\theta_l^{(v)}} \leq \varepsilon_l \quad \forall l = 1, L \\ \left| \eta_n^{(v+1)} - \eta_n^{(v)} \right| \text{ or } \frac{\left| \eta_n^{(v+1)} - \eta_n^{(v)} \right|}{\eta_n^{(v)}} \leq \varepsilon'_n \quad \forall n = 1, N \\ \underline{f}_k(\underline{\eta}^{(v+1)}, \underline{\theta}^{(v+1)}) \leq \varepsilon''_k \quad \forall k = 1, K \end{array} \right\} \Rightarrow \begin{array}{l} \hat{\underline{\theta}} = \underline{\theta}^{(v+1)} \\ \hat{\underline{\eta}} = \underline{\eta}^{(v+1)} \end{array}$$

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## Lagrange parameters method : solution



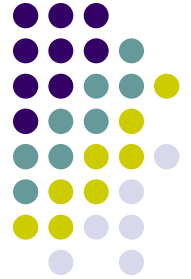
### Point solutions

$$\left. \begin{aligned} \underline{\theta}^{(v+1)} &= \underline{\theta}^{(v)} - \mathbf{H}^{-1} \mathbf{f}_{\theta}^{(v)T} \mathbf{S}^{-1} \underline{r} \\ \underline{\lambda}^{(v+1)} &= \mathbf{S}^{-1} \left( \underline{r} - \mathbf{f}_{\theta}^{(v)} \left( \underline{\theta}^{(v+1)} - \underline{\theta}^{(v)} \right) \right) \\ \underline{\eta}^{(v+1)} &= \underline{\hat{\eta}} - \mathbf{V}_{\hat{\eta}}^{-1} \mathbf{f}_{\eta}^{(v)T} \underline{\lambda}^{(v+1)} \end{aligned} \right\} \text{ with } \begin{aligned} \mathbf{S} &= \left( \mathbf{f}_{\eta}^{(v)} \mathbf{V}_{\hat{\eta}}^{-1} \mathbf{f}_{\eta}^{(v)T} \right) \\ \mathbf{H} &= \left( \mathbf{f}_{\theta}^{(v)T} \mathbf{S}^{-1} \mathbf{f}_{\theta}^{(v)} \right) \\ \underline{r} &= \underline{f}^{(v)} + \mathbf{f}_{\eta}^{(v)} \left( \underline{\hat{\eta}} - \underline{\eta}^{(v)} \right) \end{aligned}$$

### Covariance matrix

$$\left. \begin{aligned} \underline{\hat{\eta}} &= \underline{g}(\underline{\hat{\eta}}) \\ \underline{\hat{\theta}} &= \underline{h}(\underline{\hat{\eta}}) \\ \mathbf{V}_{\hat{\eta}} &= \left( \frac{\partial \underline{g}}{\partial \underline{\hat{\eta}}} \right) \mathbf{V}_{\hat{\eta}} \left( \frac{\partial \underline{g}}{\partial \underline{\hat{\eta}}} \right)^T = \mathbf{V}_{\hat{\eta}} \left( \mathbf{I}_N - (\mathbf{G} - \mathbf{F}\mathbf{H}^{-1}\mathbf{F}^T) \mathbf{V}_{\hat{\eta}} \right) \\ \mathbf{V}_{\hat{\theta}} &= \left( \frac{\partial \underline{h}}{\partial \underline{\hat{\eta}}} \right) \mathbf{V}_{\hat{\eta}} \left( \frac{\partial \underline{h}}{\partial \underline{\hat{\eta}}} \right)^T = \mathbf{H}^{-1} \\ \text{Cov}_{\hat{\eta}\hat{\theta}} &= \left( \frac{\partial \underline{g}}{\partial \underline{\hat{\eta}}} \right) \mathbf{V}_{\hat{\eta}} \left( \frac{\partial \underline{h}}{\partial \underline{\hat{\eta}}} \right)^T = \mathbf{V}_{\hat{\eta}} \mathbf{F}\mathbf{H}^{-1} \end{aligned} \right\} \text{ with } \begin{cases} \mathbf{G} = \mathbf{f}_{\eta}^T \mathbf{S}^{-1} \mathbf{f}_{\eta} \\ \mathbf{H} = \mathbf{f}_{\theta}^T \mathbf{S}^{-1} \mathbf{f}_{\theta} \\ \mathbf{F} = \mathbf{f}_{\eta}^T \mathbf{S}^{-1} \mathbf{f}_{\theta} \end{cases}$$

## Quality of the fit of the data to the model



Estimation methods provide values for model parameters that fit best to the experimental data. The best fit, however, may be a very poor fit. The quality of the fit requires an hypothesis test.

The only combination of an estimation method followed by an hypothesis test that is formally, but asymptotically, correct for large sample is:

1. The least square method to estimate the  $L$  parameters of the model.
2. The Pearson  $\chi^2$  test to estimate the quality of the fit.

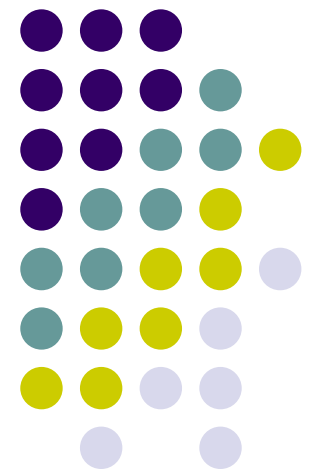
The PDF of statistic  $X^2$  follows a  $\chi^2$  with number of degrees of freedom =  $\nu - L$ .

If the maximum likelihood is used instead, the number of degrees of freedom is undefined in the range  $[\nu, \nu - L]$ .

# IX – Confidence intervals for pathological cases

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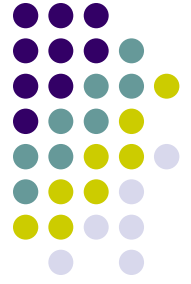
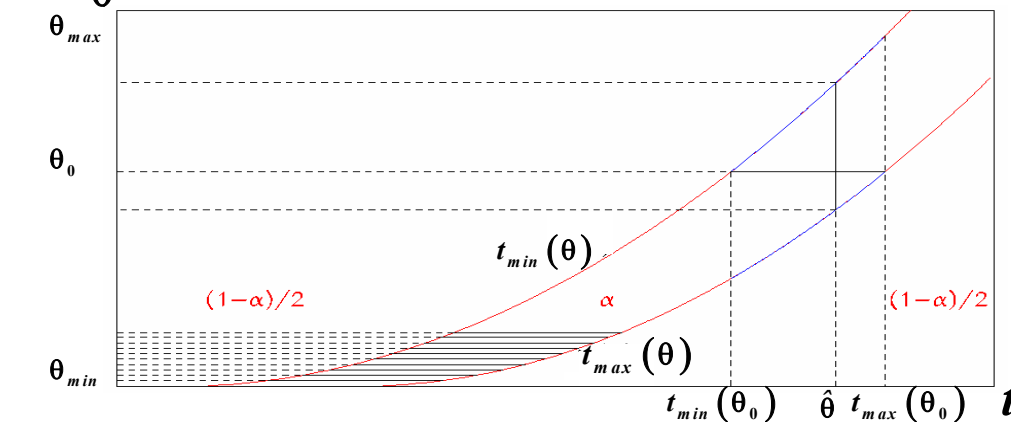
- Small signals above small background.
- Measurements with standard errors extending over a physical limit.



## Neyman prescription : belts

The Neyman centred belts are constructed with a particular prescription:

$$\int_{t_{min}}^{t_{max}} g(t | \theta) dt = \alpha \quad \text{and} \quad \int_{-\infty}^{t_{min}} g(t | \theta) dt = \int_{t_{max}}^{\infty} g(t | \theta) dt = \frac{1-\alpha}{2}$$



There is an infinite number of prescriptions to construct belts with correct coverage corresponding to *C.L.*  $\alpha$  that lead to different confidence intervals but are all equally correct from the statistical point of view.!

The Neyman upper and lower belts are constructed with the particular prescriptions:

$$\int_{t_{max}}^{+\infty} g(t | \theta) dt = \alpha \quad \int_{-\infty}^{t_{min}} g(t | \theta) dt = \alpha$$

## Gaussian error near physical limit:



Exemples :

- sine of an angle compatible with being  $>1$  within error,
- mass of a particle compatible with being  $<0$  within error.

Appropriate change of variable:

Positive variable near physical bound 0 with standard error  $\sigma = 1$

Two sensible prescriptions to build confidence intervals with exact coverage for a *C.L.*  $\alpha$  :

- The centred Neyman belts defining lower and upper limits.
- Upper limit Neyman belt, the lower limit being the physical bound 0.



# Gaussian error near physical limit: Neyman belts

$\theta$

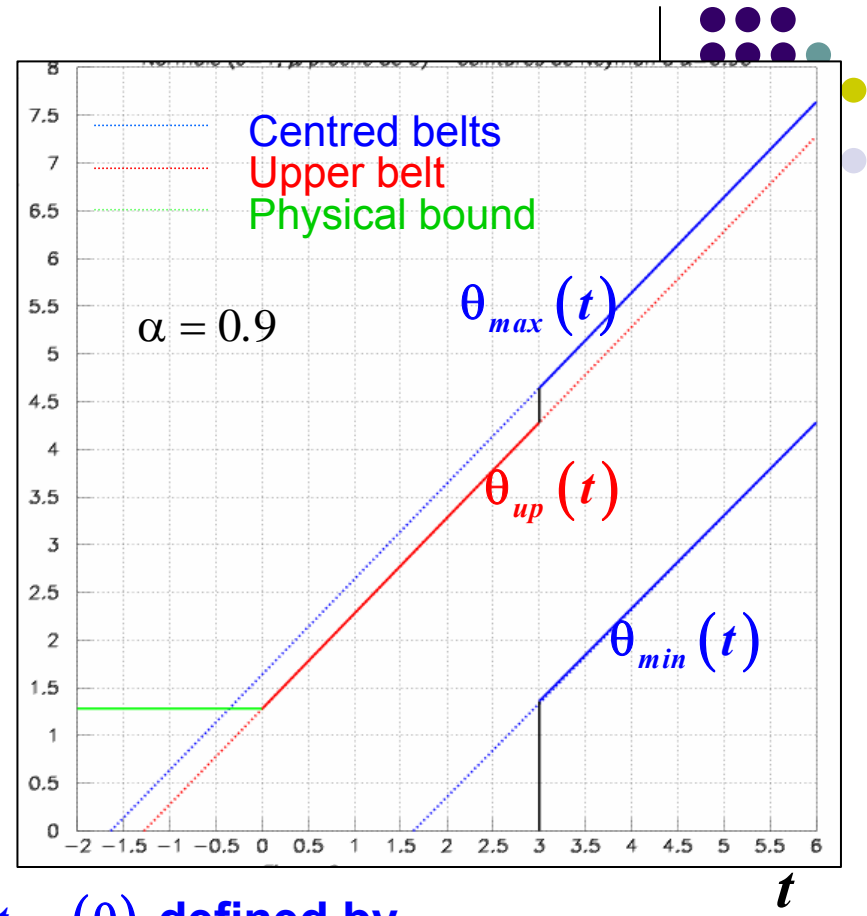
Lower limit  $\theta_{up}(t) \equiv t_{low}(\theta)$  defined by

$$\int_{t_{up}(\theta)}^{+\infty} N(t | \theta, 1) dt = \alpha$$

Centred limits  $\theta_{max}(t) \equiv t_{min}(\theta)$  et  $\theta_{min}(t) \equiv t_{max}(\theta)$  defined by

$$\int_{t_{min}(\theta)}^{t_{max}(\theta)} N(t | \theta, 1) dt = \alpha \text{ et } \int_{-\infty}^{t_{min}(\theta)} N(t | \theta, 1) dt = \int_{t_{max}(\theta)}^{\infty} N(t | \theta, 1) dt = \frac{1-\alpha}{2}$$

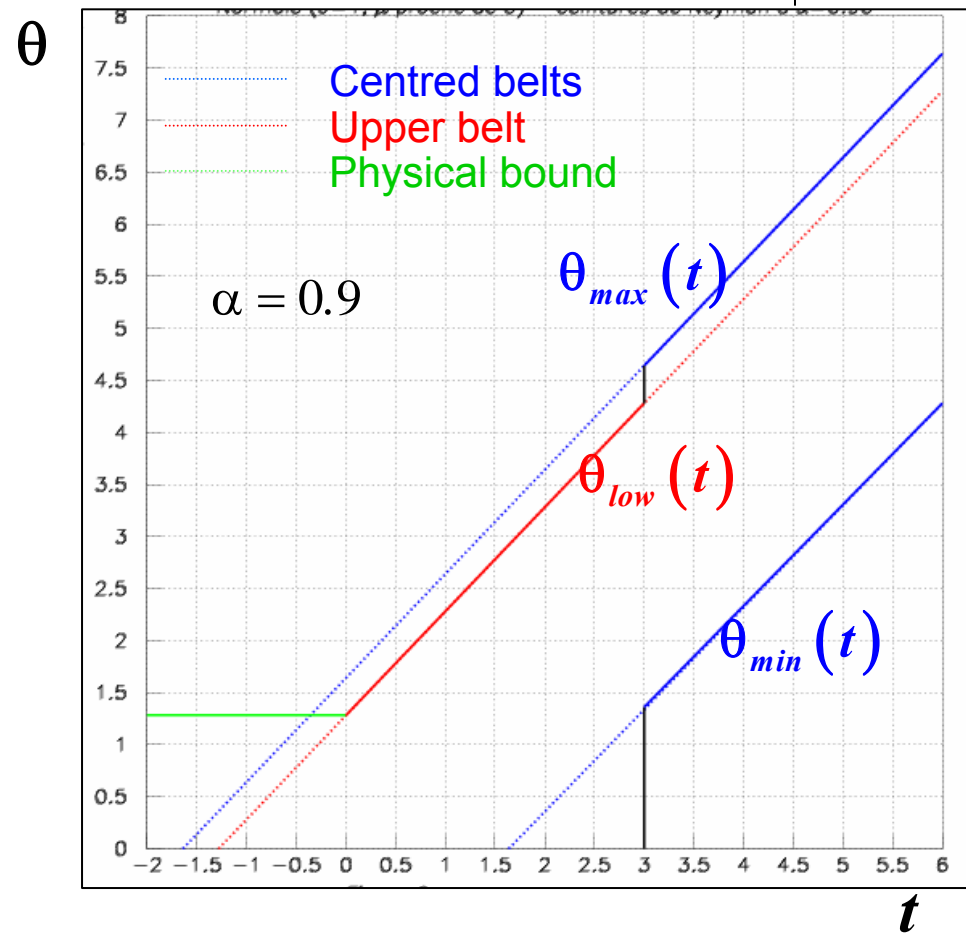
Belts are straight lines of slope  $\pi/4$



## Gaussian error near physical limit: Neyman hybrid belts



- If  $\hat{\theta} > 3\sigma = 3$  :  
 $\theta > 0$  is sensible  $\Rightarrow$   
 use centred belts  $\theta_a(t), \theta_b(t)$   
 $P(\theta_0 \in [\theta_a(\hat{\theta}), \theta_b(\hat{\theta})]) = \alpha = 0.9$   
 if  $\hat{\theta} = 4$  :  $P(\theta_0 \in [2.3, 5.6]) = \alpha = 0.9$
- If  $\hat{\theta} < 3\sigma$  :  
 $\theta$  compatible with 0 is sensible  $\Rightarrow$   
 use upper belt  $\theta_l(t)$   
 $P(\theta_0 \leq \theta_l(\hat{\theta})) = \alpha$   
 if  $\hat{\theta} = 1$  :  $P(\theta_0 < 2.2) = 0.9$
- If  $\hat{\theta} < 0$   
 $\theta = 0$   
 $P(\theta_0 \leq \theta_s(0) = 1.3) = 0.9$



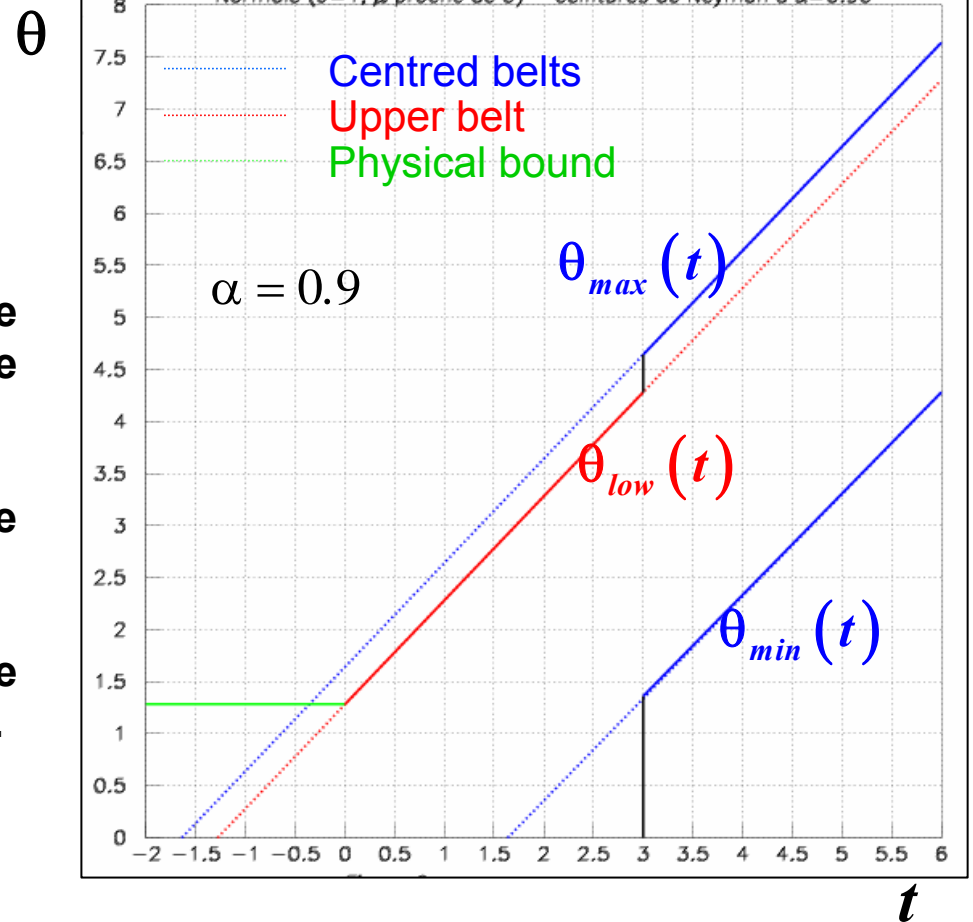
## Gaussian error near physical limit:

what is wrong with Neyman hybrid belts?

- If  $\hat{\theta} > 3$  :  $\theta_0 \in [\theta_{min}(\hat{\theta}), \theta_{max}(\hat{\theta})]$  — blue line
- If  $0 < \hat{\theta} < 3$  :  $\theta_0 \leq \theta_{low}(\hat{\theta})$  — red line
- If  $\hat{\theta} < 0$  :  $\theta_0 < \theta_s(0)$  — green line

Choosing belts a priori is correct from the statistical point of view but the choice may be meaningless:

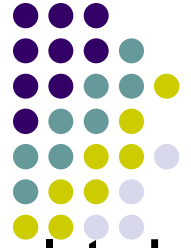
- compute an upper limit when the measurement is clearly positive
- compute a pair of limits when the measurement is clearly compatible with 0.



To make the choice a posteriori is statistically incorrect.

The coverage does not correspond  $\alpha = 0.9$

# Small event count with background



$r_S$  : unknown number of signal events - confidence interval to be calculated

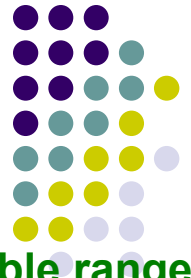
$r_B$  : expected number of background events

$n$  : estimator of the total number of events (signal + background)

$\hat{n}$  : estimation, particular value taken by  $n$

$$P(n | r_S) = \frac{(r_S + r_B)^n}{n!} e^{-(r_S + r_B)}$$

## Small event count with background : Neyman prescription



**Centred belts:**

**Compute contours  $n_{min}(r_S)$  et  $n_{max}(r_S)$  for a discrete set of values of  $r_S$  in a sensible range:**

$$\sum_{k=0}^{n_{min}(r_S)} P(k | r_S) > \frac{1-\alpha}{2} \text{ and } \sum_{k=0}^{n_{min}(r_S)-1} P(k | r_S) \leq \frac{1-\alpha}{2} \Rightarrow \sum_{k=n_{min}(r_S)}^{n_{max}(r_S)} P(k | r_S) > \alpha$$

$$\sum_{k=n_{max}(r_S)}^{\infty} P(k | r_S) > \frac{1-\alpha}{2} \text{ and } \sum_{k=n_{max}(r_S)+1}^{\infty} P(k | r_S) \leq \frac{1-\alpha}{2}$$

**$n_{min}, n_{max}$  are discrete  $\Rightarrow$  exact coverage for  $C.L. = \alpha$  not possible**

$$P(r_{S0} \in [r_{Smin}(\hat{n}), r_{Smax}(\hat{n})]) \geq \alpha \text{ with } r_{Smin}(n) = n_{max}^{-1}(n_{max}(r_S)), \quad r_{Smax}(n) = n_{min}^{-1}(n_{min}(r_S))$$

**Upper belt:**

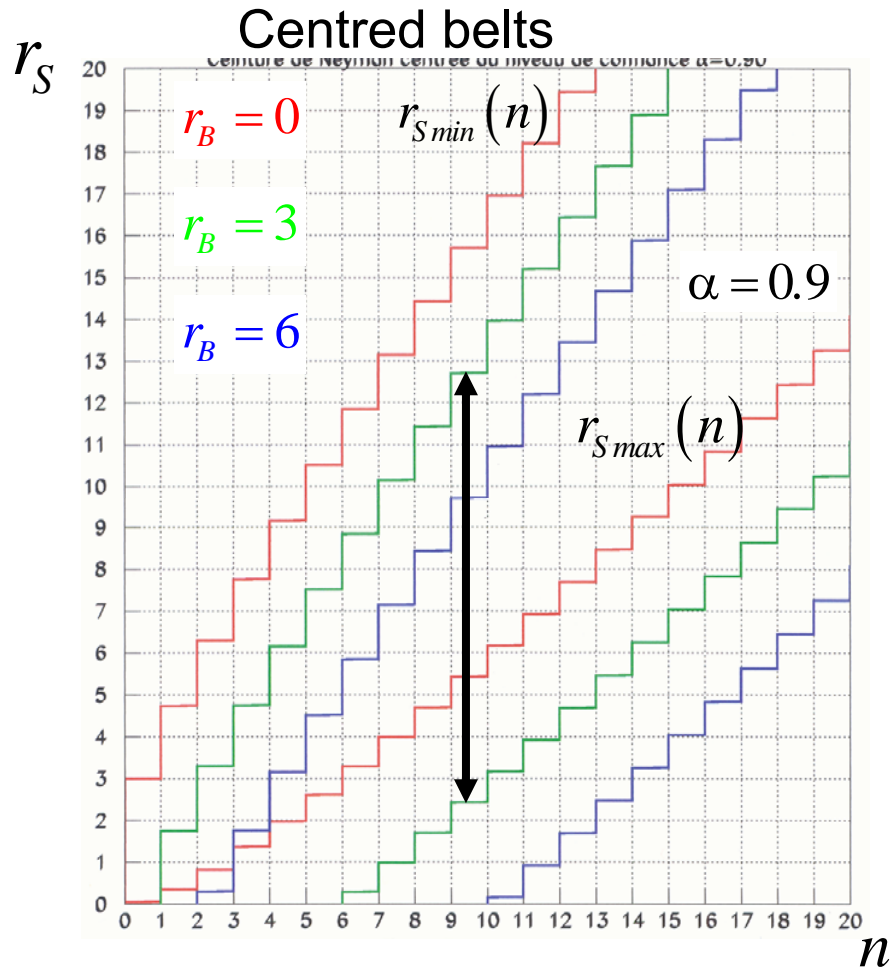
**Compute contour  $n_{up}(r_S)$  for a discrete set of values of  $r_S$  in a sensible range:**

$$\sum_{k=n_{up}(r_S)}^{\infty} P(k | r_S) > 1-\alpha \text{ and } \sum_{k=n_{up}(r_S)+1}^{\infty} P(k | r_S) \leq 1-\alpha \Rightarrow \sum_{k=0}^{n_{up}(r_S)} P(k | r_S) > \alpha$$

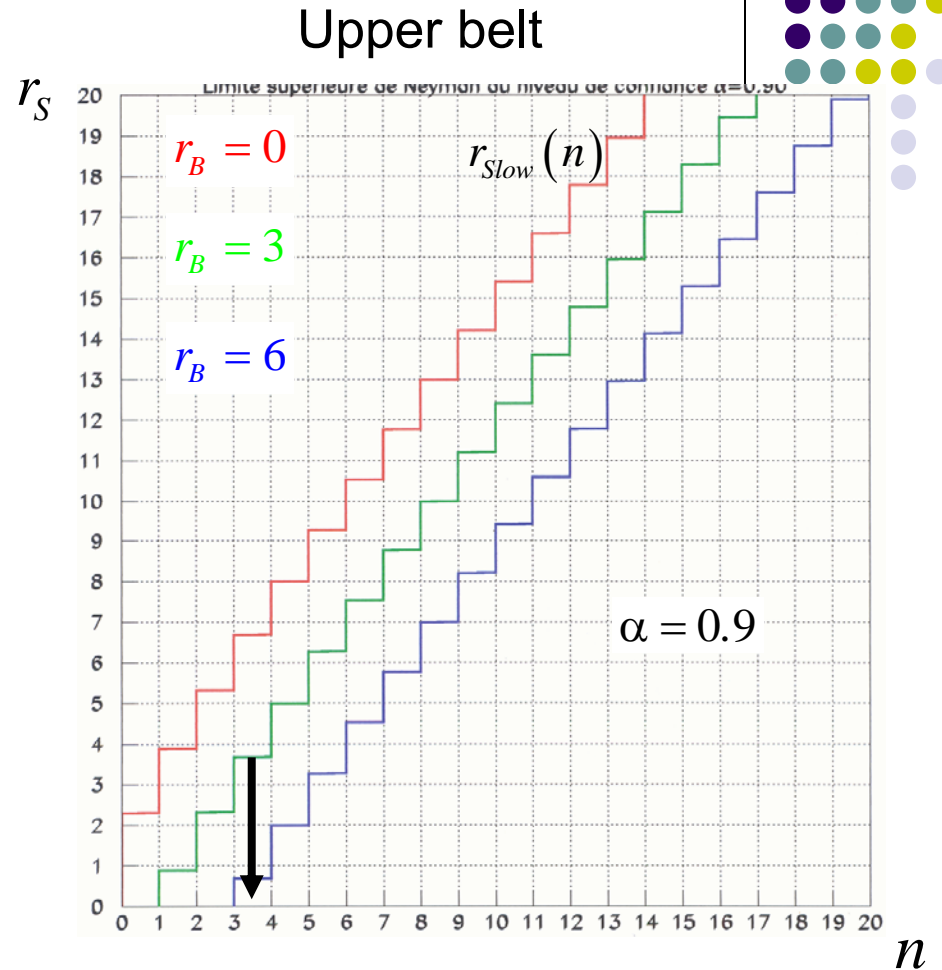
**$n_{up}$  is discrete  $\Rightarrow$  exact coverage for  $C.L. = \alpha$  not possible**

$$P(r_{S0} < r_{Slow}(\hat{n})) \geq \alpha \text{ with } r_{Slow}(n) = n_{up}^{-1}(n_{up}(r_S))$$

# Small event count with background : Neyman belts



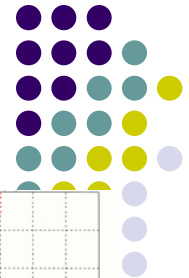
If  $r_B = 3$  and  $n = 9 \Rightarrow P(r_s \in [2.4, 12.8]) = 0.9$



If  $r_B = 3$  and  $n = 3 \Rightarrow P(r_s < 3.7) = 0.9$

If  $n \ll r_B$  - large negative fluctuation on  $r_B$  :  
 $r_{SI}(n) = 0 \Leftrightarrow$  the confidence interval is void

## Small event count with background : Neyman hybrid belts



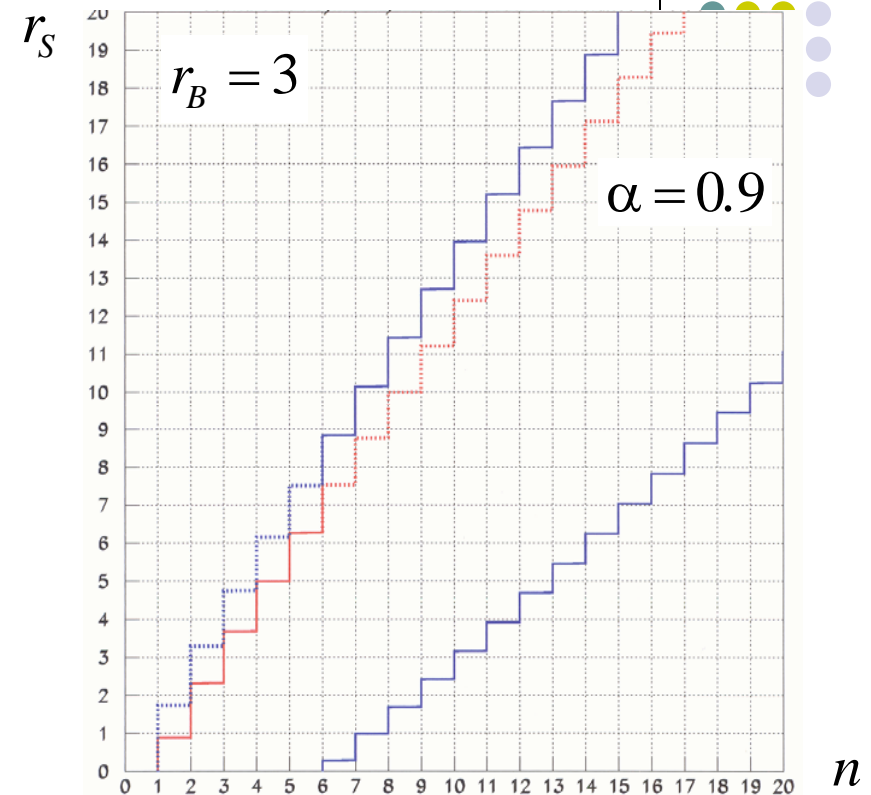
Choosing belts a priori is correct from the statistical point of view but the choice may be meaningless:

- compute a pair of limits on the signal when the measurement is clearly compatible with the expected background.
- compute an upper limit on the signal when the measurement is clearly larger than the expected background.

Why not make the choice a posteriori ?  
Statistically incorrect: the coverage is incorrect.

To make the choice a posteriori is statistically incorrect.

The coverage does not correspond  $\alpha = 0.9$



# The Feldman – Cousins prescription



*Unified approach to the classical analysis of small signals.*

G. Feldman and R. Cousins

Phys. Rev. D57 (1998) 3873

**Purpose : define an a priori unique set of belts with proper coverage.**

This paper is a first of a long series that treat the questions of small signals above small background and measurements with standard errors extending over a physical limit from the frequentist point of view with prescriptions that insure correct coverage.

Other prescriptions are used

Some improvements to i.e.

- take the systematic errors into account,
- take the error on the background into account,
- 

Th. Junk

NIM A434 (1999) 435

C. Junti

arXiv:hep-ex/9901015

B. Roe and M. Woodroffe

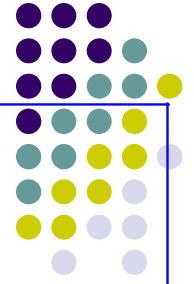
arXiv:physics/9812036v3

G. Punzi

arXiv:hep-ex/9912048



# Gaussian error near physical limit: Feldman–Cousins prescription



## Ordering prescriptions

1 • By definition :  $P(t \in [t_{min}(\theta), t_{max}(\theta)]) = \int_{t_{min}(\theta)}^{t_{max}(\theta)} f(t|\theta) dt = \alpha$

2 • The likelihood ratio  $R(t) = \frac{P(t|\theta)}{P(t|\theta^*(t))}$  is maximum

$\theta^*(t)$  is the physically allowed value of  $\theta$  that maximises  $P(t|\theta)$  given  $t$

Applying to prescription to measurements with standard errors extending over a physical limit.

$$\text{If } \hat{\theta} \geq 0 : \theta^* = \hat{\theta} \Rightarrow N(t|t,1) = \frac{1}{\sqrt{2\pi}} \Rightarrow R(t) = \frac{\frac{1}{\sqrt{2\pi}} e^{-\frac{1}{2}(t-\theta)^2}}{\frac{1}{\sqrt{2\pi}}} = e^{-\frac{1}{2}(t-\theta)^2}$$

$$\text{If } \hat{\theta} \leq 0 : \theta^* = 0 \Rightarrow N(t|0,1) = \frac{1}{\sqrt{2\pi}} e^{-\frac{t^2}{2}} \Rightarrow R(t) = \frac{\frac{1}{\sqrt{2\pi}} e^{-\frac{1}{2}(t-\theta)^2}}{\frac{1}{\sqrt{2\pi}} e^{-\frac{t^2}{2}}} = e^{-\frac{1}{2}(\theta^2 - 2t\theta)}$$

# Gaussian error near physical limit: Feldman–Cousins belts



For a finite values of  $\theta$  : solve numerically the system

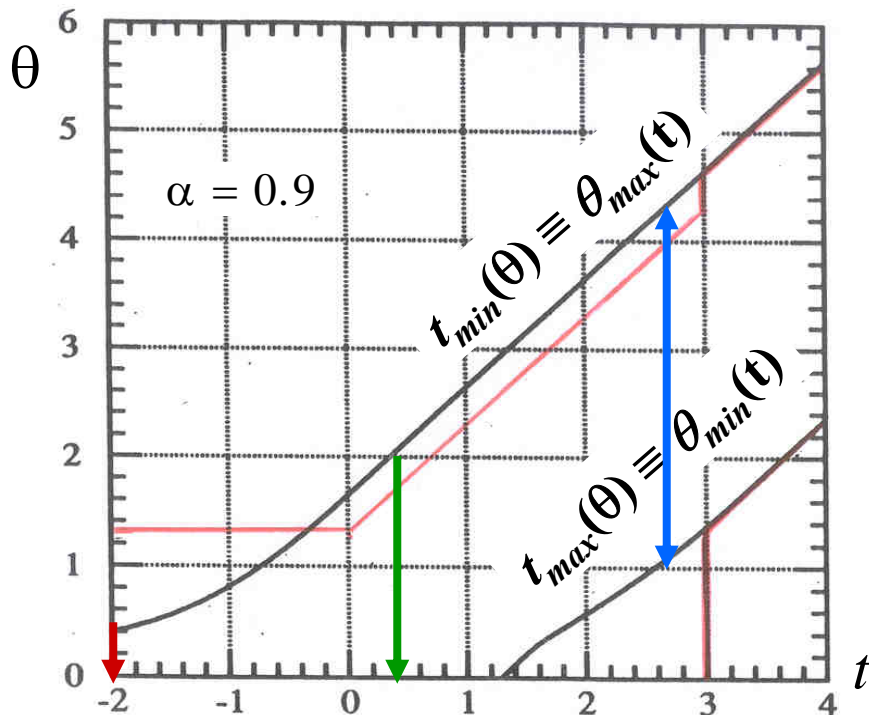
$$\int_{t_{\min}(\theta)}^{t_{\max}(\theta)} N(t | \theta, 1) = \alpha$$

$$R(t_{\min}(\theta) | \theta) = R(t_{\max}(\theta) | \theta)$$

with

$$R(t) = e^{-\frac{1}{2}(t-\theta)^2} \quad \text{if } t \geq 0$$

$$R(t) = \frac{e^{-\frac{1}{2}(t-\theta)^2}}{e^{-\frac{t^2}{2}}} = e^{-\frac{1}{2}(\theta^2 - 2t\theta)} \quad \text{if } t \leq 0$$



30/11/2006

— Feldman – Cousins belt

— Neyman hybrid belt

If  $\hat{\theta} = 2.6, P(\theta_0 \in [1.0, 4.4]) = 0.9$

If  $\hat{\theta} = 0.4, P(\theta_0 < 2.0) = 0.9$

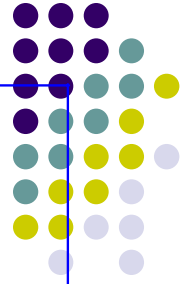
For large values of  $t$  : identical belts

$\lim_{t \rightarrow -\infty} \theta_b(t) = 0$

but the confidence interval is never null

If  $\hat{\theta} = -2, P(\theta_0 < .0) = 0.9$

## Small event count with background : Feldman–Cousins prescription



### Ordering prescriptions

1 • By definition :  $P\left(n \in \left[n_{\min}(r_S), n_{\max}(r_S)\right]\right) = \sum_{k=n_{\min}(n_S)}^{n_{\max}(n_S)} P(k | r_S) \approx \alpha$

2 • The likelihood ratio  $R(n) = \frac{P(n | r_S)}{P(n | r_S^*(n))}$  is maximum

$r_S^*(n)$  is the value of  $r_S$  that maximises  $P(n | r_S)$  given  $n$  and  $r_S^* \geq 0$

### Applying to prescription to search for a small signals above small background

$$r_S^*(n) = \text{Max}(0, n - r_B)$$

$$P(n | r_S, r_B) = \frac{(r_S + r_B)^n}{n!} e^{-(r_S + r_B)}$$

$$P(n | r_S^*(n), r_B) = \frac{(r_S^*(n) + r_B)^n}{n!} e^{-(r_S^*(n) + r_B)},$$

$$R(n) = \frac{P(n | r_S, r_B)}{P(n | r_S^*(n), r_B)}$$

## Small event count with background : Feldman–Cousins belts (1)



For a finite values of  $r_S$  in the sensible range:

Select the values of  $n$  in decreasing values of  $R(n)$  until  $\sum P(n | r_S) \geq \alpha$

Use the two extreme values of  $n$  as limits

**Example: Compute limits at  $r_S = 1$  for  $r_B = 3$  and  $\alpha = 0.9$**

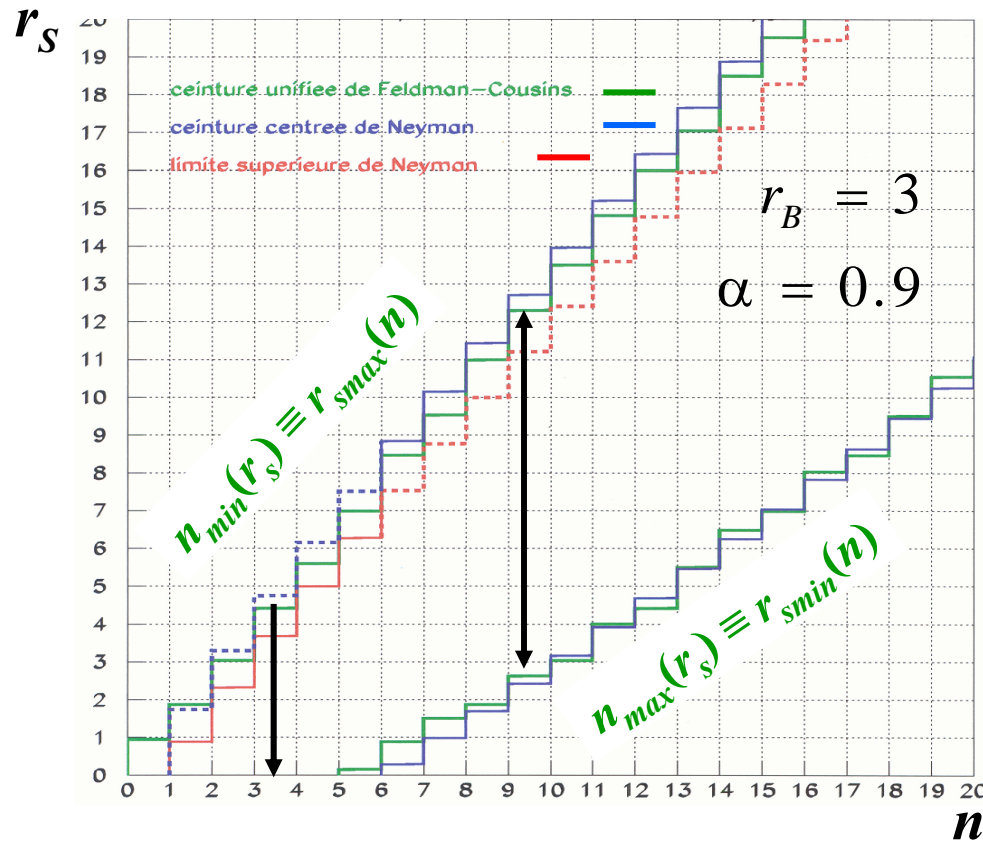
$n$	$P(n   r_S)$	$r_S^*(n)$	$P(n   r_S^*(n))$	$R(n)$	rank
0	0.030	0.0	0.050	0.607	6
1	0.106	0.0	0.149	0.708	5
2	0.185	0.0	0.224	0.826	3
3	0.216	0.0	0.224	0.963	2
4	0.189	1.0	0.195	0.966	1
5	0.132	2.0	0.175	0.753	4
6	0.077	3.0	0.161	0.480	7
7	0.039	4.0	0.149	0.259	
8	0.017	5.0	0.140	0.121	
9	0.007	6.0	0.132	0.050	
10	0.002	7.0	0.125	0.018	
11	0.001	8.0	0.119	0.006	

$$\sum_{k=1,}^6 P_k(n | r_S = 1) = 0.858 < 0.9 < \sum_{k=1,}^7 P_k(n | r_S = 1) = 0.935$$

$$\Rightarrow n_{\min}(r_S = 1 | n_B = 3, \alpha = 0.9) = 0$$

$$\Rightarrow n_{\max}(r_S = 1 | n_B = 3, \alpha = 0.9) = 6$$

# Small event count with background : Feldman–Cousins belts (2)



If  $r_B = 3$  and  $n = 9$  :

$$P(r_{S0} \in [2.6, 12.3]) \geq 0.9$$

If  $r_B = 3$  and  $n = 3$  :

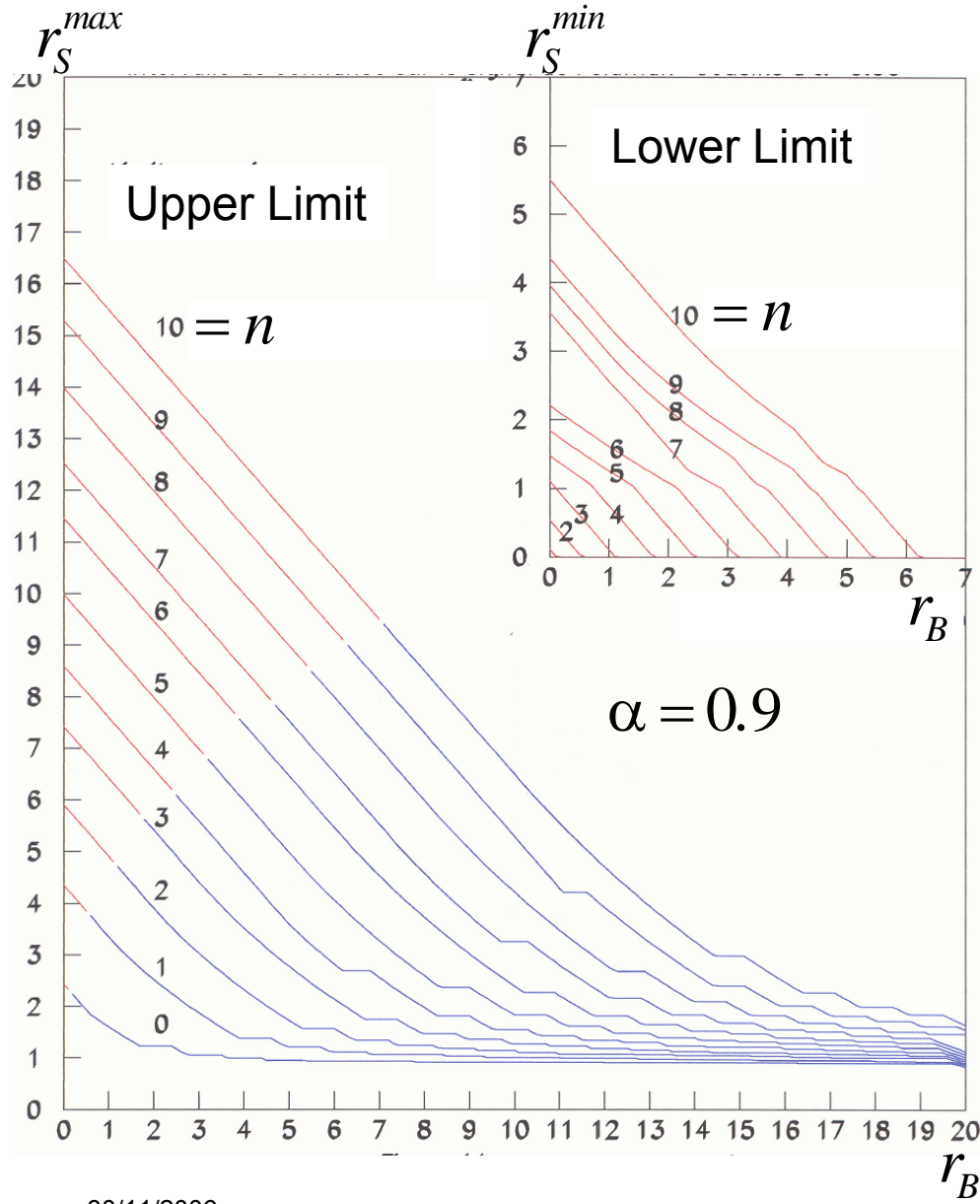
$$P(r_{S0} < 4.5) \geq 0.9$$

Because  $n$  is integer: coverage cannot be strictly exact

Confidence interval never void, though  $\lim_{n \ll r_B} r_{S \max} \rightarrow 0$

if  $n = r_B - 3 = 0$  :  $P(r_s \leq 1) = 0$ .

# Summary of Feldman–Cousins prescription for counting experiment



Examples :

If  $r_B = 4.7$  and  $n = 8$  :  $P(r_{S0} \in [0.7, 9.3]) = 0.9$

If  $r_B = 2.5$  and  $n = 3$  :  $P(r_{S0} < 4.9) = 0.9$

## Application to the search for neutrino oscillation



The confidence interval of parametre  $\theta$  of a model that predicts  $r_S(\theta)$  is:

$$P(\theta_0 \in [\theta_{min}, \theta_{max}]) = \alpha \text{ with}$$

$$\theta_{min} \Rightarrow r_S(\theta_{min}) = r_{Smin}$$

$$\theta_{max} \Rightarrow r_S(\theta_{max}) = r_{Smax}$$

Alternatively,  $\theta$  may replace  $r_S$  as ordinate of all plots and the physical bounds on  $\theta$  used.

The procedure may be extended to a set of parametre  $\underline{\theta}$  of a model that predicts  $r_S(\underline{\theta})$

$$\begin{aligned} |v_\ell\rangle &= \cos\theta |v_1\rangle + \sin\theta |v_2\rangle \\ |v_{\ell'}\rangle &= \cos\theta |v_2\rangle - \sin\theta |v_1\rangle \end{aligned} \Rightarrow P(v_\ell \rightarrow v_{\ell' \neq \ell}) = \sin^2(2\theta) \sin^2 \left( 1.27 \frac{\Delta m^2 \left[ \left( \frac{eV}{c^2} \right)^2 \right] L [km]}{E [GeV]} \right)$$

e.g.  $P(v_\mu \rightarrow v_\tau)$  in a  $v_\mu$  beam

Face the two pathological problems:

- if mixing  $\sin^2(2\theta)$  small : small signal
- the combination of the true value  $\Delta m^2$  and values of  $L/E$  accessible to experiment such that small signal even for large mixing
- physical bounds :  $0 \leq \sin^2(2\theta) \leq 1$

+ background :  $v_\mu$  misidentified as  $v_\tau$

## Application to the search for neutrino oscillation : outcome of one experiment



$$P\left(\nu_{\mu} \rightarrow \nu_{\tau}\right) = \sin^2(2\theta) \sin^2\left(1.27 \frac{\Delta m^2 \left[\left(\frac{eV}{c^2}\right)^2\right] L[km]}{E[GeV]}\right)$$

For simplicity, assume that  $L \gg$  fluctuations on  $L$

$P(\nu_{\mu} \rightarrow \nu_{\tau}) = P(E) \Rightarrow$  divide in  $N$  energy bins (the better the energy resolution, the more bins)

In each bin  $i$  :

define a set of  $\nu_{\tau}$  selection criteria  $\Rightarrow \log \lambda = \log \frac{\mathcal{L}(\nu_{\tau})}{\mathcal{L}(\nu_{\mu})}$  is large

compute the expected background :  $r_{Bi}$

compute for a discrete set of pairs of values of  $(\Delta m^2, \sin^2(2\theta))$  the expected signal :

$$r_{Si}(\Delta m^2, \sin^2(2\theta))$$

computation are not analytic and require Monte-Carlo simulation.

Outcome of one experiment :

$$\left. \begin{array}{l} r_{Bi} \\ r_{Si}(\Delta m^2, \sin^2(2\theta)) \\ \text{one particular set } n_i \text{ of observed events} \end{array} \right\} i = 1, N$$



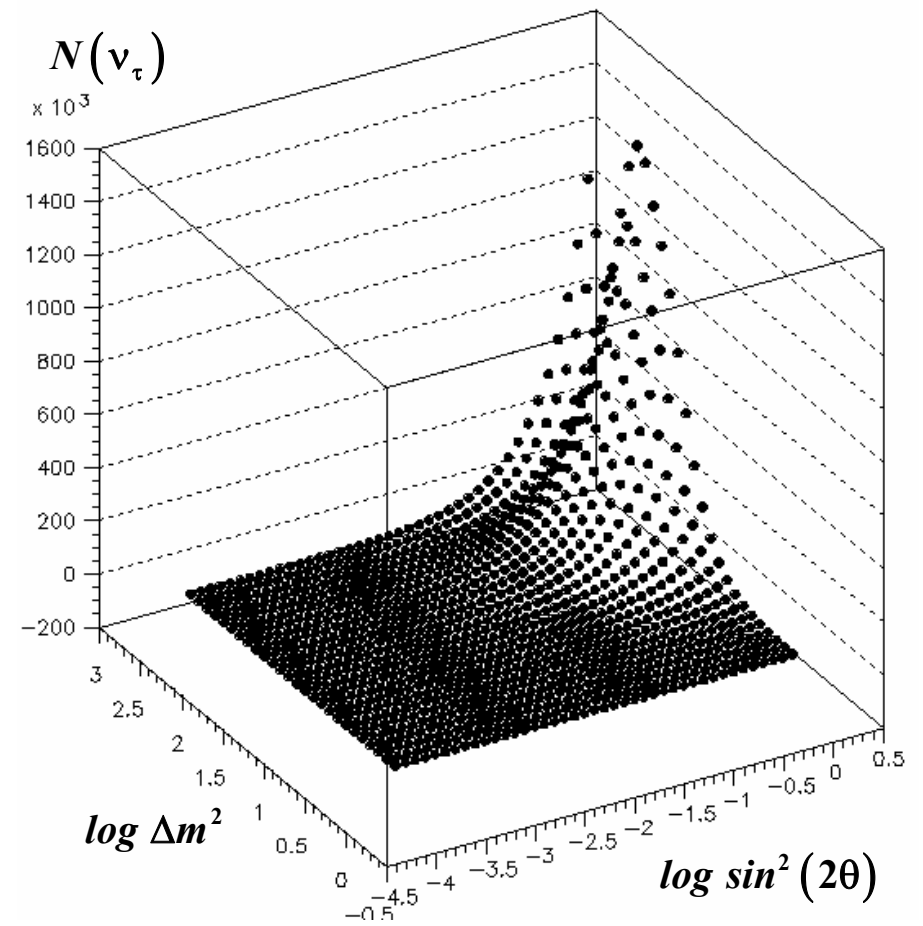
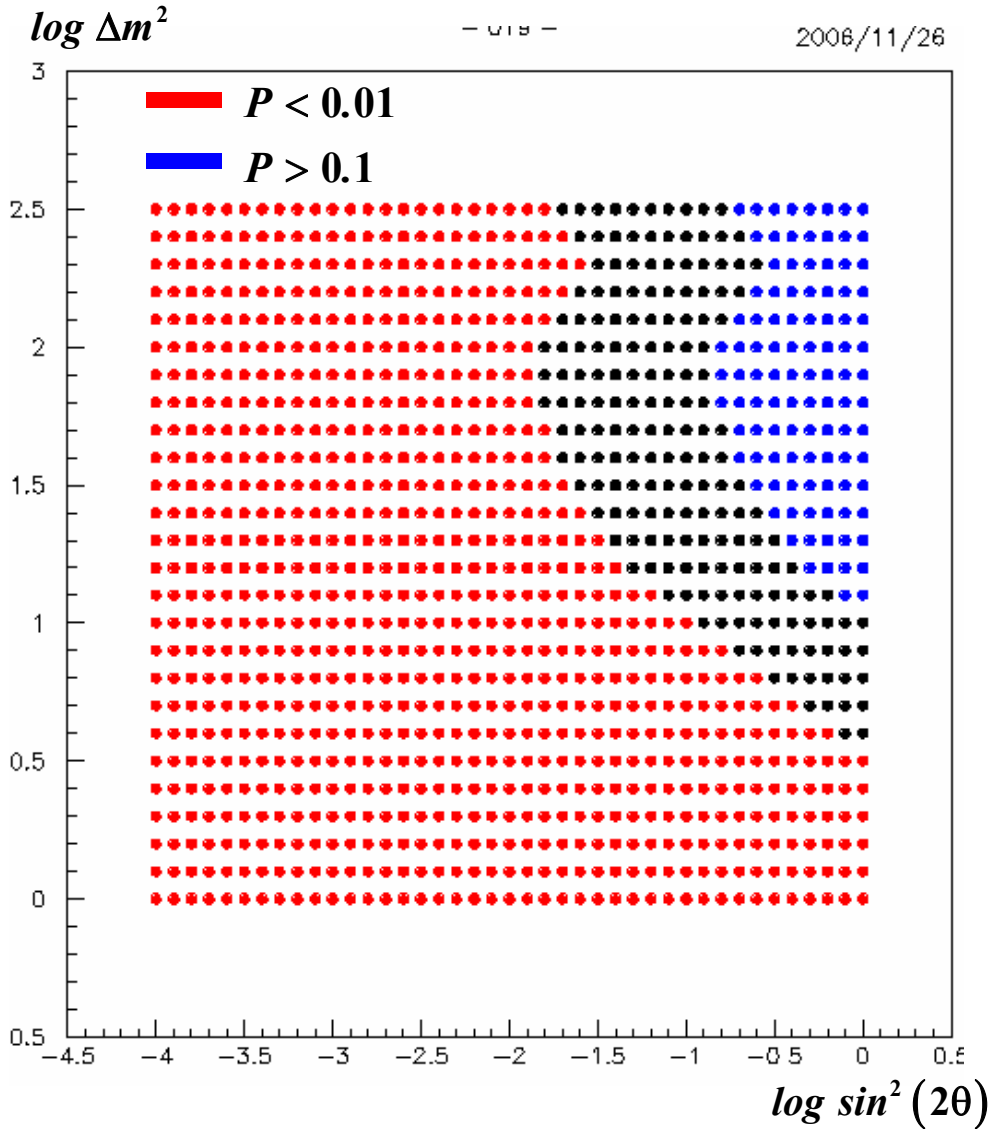
# Application to the search for neutrino oscillation : oscillation probability



$E$  uniform on  $[10.,60.] GeV$

$L = 0.6 km$

$N(\nu_\mu) = 2\,000\,000$



# Application to the search for neutrino oscillation : belts



Definition of the belts at  $C.L. = \alpha$  in the  $(\Delta m^2, \sin^2(2\theta))$  plane

For each discrete pair of values of  $(\Delta m^2, \sin^2(2\theta)) \Rightarrow \underline{r}_S(\Delta m^2, \sin^2(2\theta))$

The possible outcomes from a large number of simulation experiments

is a large number of sets  $\underline{n} = (n_1, \dots, n_N)$

resulting from fluctuations on the expected background ( $\underline{r}_B$ ) and signal  $\underline{r}_S(\Delta m^2, \sin^2(2\theta))$

For each set, compute

$$R(\underline{n} | \Delta m^2, \sin^2(2\theta)) = \frac{P(\underline{n} | \underline{r}_S(\Delta m^2, \sin^2(2\theta)), \underline{r}_B)}{P(\underline{n} | \underline{r}_S^*(\Delta m^2, \sin^2(2\theta)), \underline{r}_B | \underline{n})} = \prod_{i=1}^N \frac{P(n_i | r_{Si}(\Delta m^2, \sin^2(2\theta)), r_{Bi})}{P(n_i | r_{Si}^*(n_i; \Delta m^2, \sin^2(2\theta)), r_{Bi} | \underline{n})}$$

where  $\underline{r}_S^*(\underline{n}; \Delta m^2, \sin^2(2\theta))$  maximizes  $P(\underline{n} | \underline{r}_S(\Delta m^2, \sin^2(2\theta)))$  in the physical domain given  $\underline{n}$ .

In regions where  $P_{oscl}^{true}$  is small,  $\underline{r}_S \ll \underline{r}_B$  : values of  $\underline{n} < \underline{r}_B \Rightarrow P_{osc} < 0$  or  $\sin^2(2\theta) < 0$  may occur.

In regions where  $P_{oscl}^{true} \approx 1$ :  $N(\nu_\tau) > N(\nu_\mu) \Rightarrow P_{osc} > 1$  or  $\sin^2(2\theta) > 1$  may occur.

**Select the value  $R_\alpha(\Delta m^2, \sin^2(2\theta))$  such that a fraction  $\alpha$  of the sets  $(\underline{n})$  have  $R(\underline{n}) < R_\alpha$**

## Application to the search for neutrino oscillation: confidence domain



Confidence domain set by one experiment at  $C.L. = \alpha$  in the  $(\Delta m^2, \sin^2(2\theta))$  plane

One experiment  $\Leftrightarrow$  one particular set  $(\hat{n})$

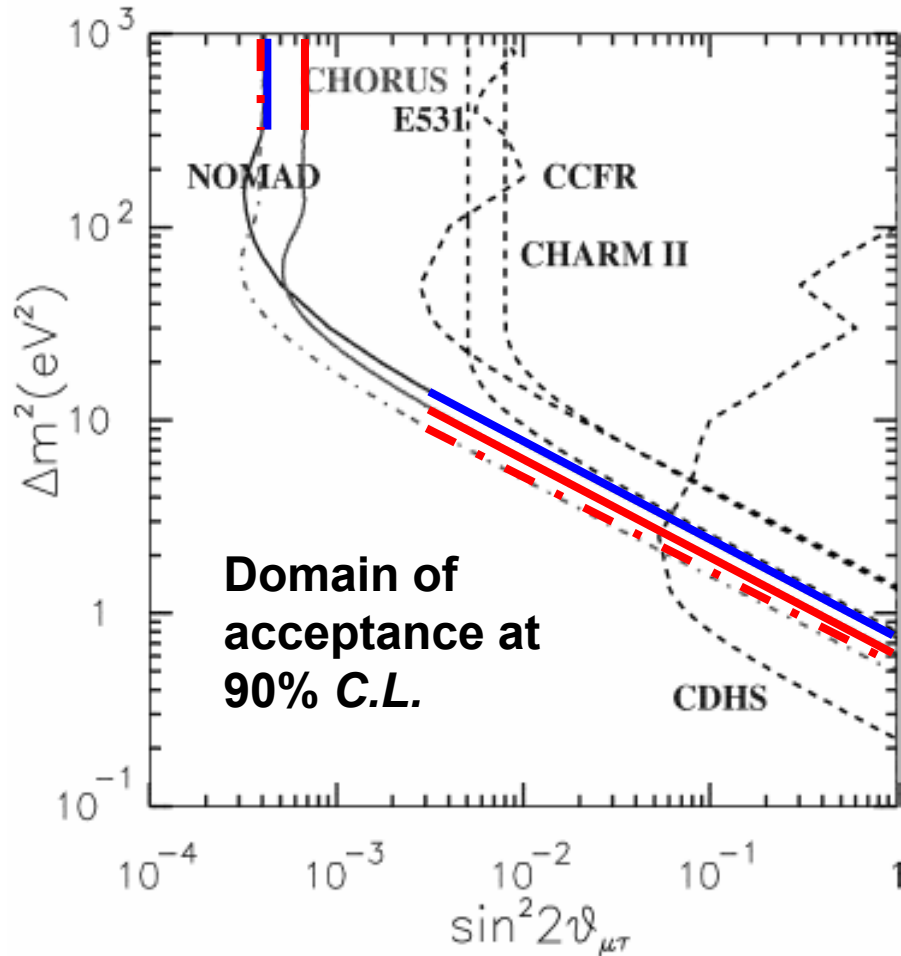
For each discrete pair of values of  $(\Delta m^2, \sin^2(2\theta)) \Rightarrow \underline{r}_S(\Delta m^2, \sin^2(2\theta))$

$$\text{compute } R(\hat{n} | \Delta m^2, \sin^2(2\theta)) = \frac{P(\hat{n} | \underline{r}_S(\Delta m^2, \sin^2(2\theta)), \underline{r}_B)}{P(\hat{n} | \underline{r}_S^*(\underline{n}; \Delta m^2, \sin^2(2\theta)), \underline{r}_B)}$$

**Confidence domain : Pairs of values  $(\Delta m^2, \sin^2(2\theta))$**

**such that  $R(\hat{n} | \Delta m^2, \sin^2(2\theta)) < R_\alpha(\Delta m^2, \sin^2(2\theta))$**

## Application to the search for neutrino oscillation: CHORUS and NOMAD rejection domains and the use of different prescriptions



- CHORUS – Junk prescription
- - - CHORUS – Feldman-Cousin prescription
- NOMAD – Feldman-Cousin prescription

Feldman-Cousins and Junk prescriptions are **different but both statistically correct**. They have exact coverage. The acceptance region would include the true values of the parameters for 90% of similar experiments.

**The confidence domains for one particular experiment are different.**

## Application to the search for neutrino oscillation : gain in binning



Net gain in binning events according to topology/kinematics in bins of low background and high  $S/B$

Bin A :	$S = 3.0$	$S + B = 24.9$
Bin B :	$S = 2.2$	$S + B = 2.5$
A+B :	$S = 5.2$	$S + B = 26.4$

Statistically easier to detect a signal above background in bin B than in the whole sample dominated by bin A.

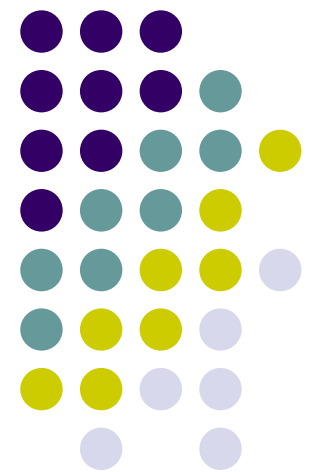
Bin B brings most of the information.

Bin A brings small but not null additional information without altering the information provided by bin B.

Bins A and B are two independent experiments

# X – Monte-Carlo Simulation

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## Uniform pseudo-random numbers $\xi$ generators on $[0, 1]$



**Pseudo-random** : result of an algorithm that produce identical numbers when repeated

**Random** : no way a posteriori to distinguish from genuine random numbers

Good generator:

- Randomness and uniformity.
- Length of the sequence before repetition and disjoint sub-sequences.
- Reproducibility.
- Portability.
- Speed.

### The first generator : von Neumann generator

- $X_0$  made of  $r$  digits,
- $Y_1$ , from the  $r/2$  central digits of  $X_0$
- $X_1 = Y_1 \times Y_1$
- $Y_2$ , from the  $r/2$  central digits of  $X_1$
- ...

If  $X_n = X_{n-1}$ : period fixed to 1

**RANMAR, mix the bits of two generators** (G. Marsaglia, A. Zaman and W.-W Tsang, Stat. Prob. Lett 9 (1990) 35)

1. Differed Fibonacci sequence :  $X_i = (X_{i-p} - X_{i-q} + 1.) \bmod(1.)$  ,  $q < p$

2. Arithmetic sequence :  $0 < c, d < 1$

$$Y_i = Y_{i-1} - c$$

$$\text{if } Y_i < 0. \Rightarrow Y_i = Y_i + d$$

3. Combination of the two sequences

$$Z_i = (X_i \oplus Y_i + 1.) \bmod(1.)$$

Period of  $10^{43}$

Large number of sub-sequences ( $30000 \times 30000$ )  
of mean periodicity  $10^{31}$

## Non-uniform discrete random numbers generators

Random number on  $[a,b]$

$\xi$  on  $[0, 1] \Rightarrow x = a + (b - a) \xi$ .

•  $x$  may take a finite set of  $N$  values  $(x_1, \dots, x_N)$  with probabilities  $(p_1, \dots, p_N)$

**binomial distribution**

Define the distribution function  $P_n = \sum_{i=1}^n p_i, n = 1, N$

$P_N = 1$ ; call  $P_0 = 0$

Accept value  $x_n$  for  $x$  if  $P_{n-1} < \xi \leq P_n$

•  $x$  may take an infinite set of values

**Poisson distribution**

Define the distribution function  $P_n = \sum_{i=1}^n p_i, n = 1, N$

for a finite number of values until  $P_N \simeq 1$ .

If  $\xi > P_{N'}$ : compute  $P_{N+1}, \dots, P_{N'}$  until  $\xi \leq P_{N'}$





## Non-uniform continuous random numbers generators : cumulative method



Generate value of  $x$  following PDF  $f(x)$

$$F(x) = \int_a^x f(x') dx' \quad ; \quad 0 \leq F(x) \leq 1$$

$$dF(x) = f(x) dx$$

$$x = F^{-1}(\xi) \text{ follows } f(x)$$

Demonstration :  $PDF(x) = PDF(\xi) \frac{d\xi}{dx} = 1 \times \frac{dF(x)}{dx} = \frac{f(x) dx}{dx} = f(x)$

Method limited to PDF where  $F(x)$  and  $F^{-1}(\xi)$  are analytical

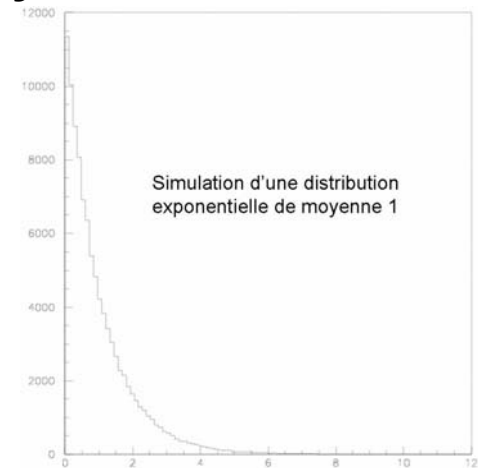
**Exponential PDF :**  $f(x) = \frac{1}{\beta} e^{-\frac{x}{\beta}}$

$$F(x) = 1 - e^{-\frac{x}{\beta}} = \xi$$

$$x = -\beta \log(1 - \xi)$$

**$\chi_v^2$  PDF :** If  $v = 2n$   $x = -2 \log(\xi_1 \xi_2 \dots \xi_n)$

If  $v = 2n + 1$   $x = -2 \log(\xi_1 \xi_2 \dots \xi_n) - 2 \log \xi_{n+1} \cos^2(2\pi \xi_{n+2})$



# Non-uniform continuous random numbers generators : cumulative method



## Isosceles trapezoidal and triangular distributions

$2a < 2b$  the two trapeze bases

$c$  the minimum value of  $x$ :  $x \in [c, c + 2b]$

$$x = c + (b + a) \xi_1 + (b - a) \xi_2$$

If  $a = 0$  : triangular distribution

$$x = c + b(\xi_1 + \xi_2)$$

Left half-trapeze or half-triangle

$$\text{If } x > c + b : x = (c + b) - (x - (c + b))$$

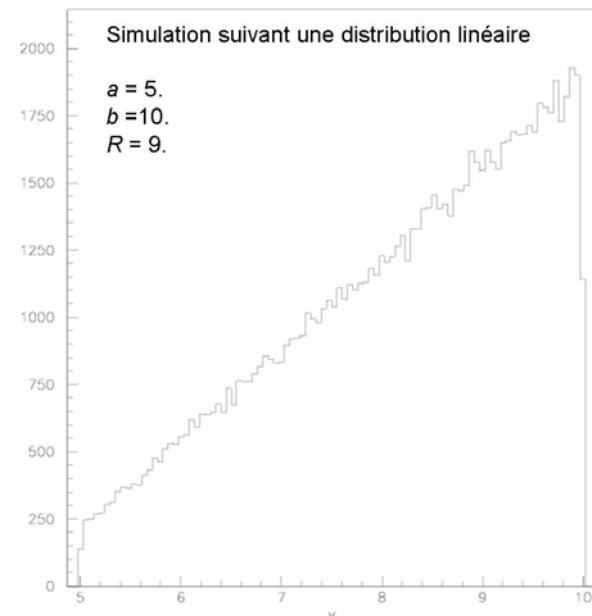
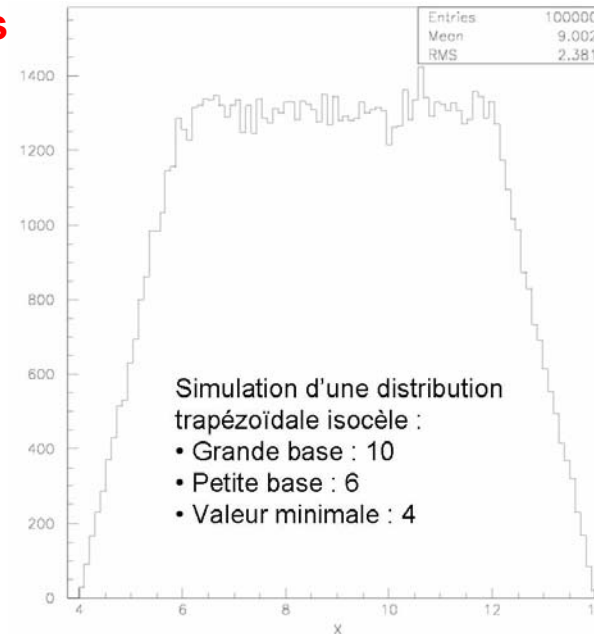
Right half-trapeze or half-triangle

$$\text{If } x < c + b : x = (c + b) + ((c + b) - x)$$

**Linear distribution**  $f(x) = ax + b$  on  $[0, 1]$

$$\text{Define } \alpha, \beta : \left\{ \begin{array}{l} r = \frac{f(1)}{f(0)} = \frac{a+b}{b} \\ \int_0^1 (ax+b) dx = \frac{a}{2} + b = 1 \end{array} \right\} \Rightarrow \left\{ \begin{array}{l} b = \frac{2}{r+1} \\ a = b(r-1) \end{array} \right.$$

$$F(x) = \xi = \frac{a}{2} x^2 + bx \Rightarrow x = \frac{-b + \sqrt{b^2 + 2a\xi}}{a}$$



# Non-uniform continuous random numbers generators : gaussian distribution



## Exact method of Box - Muller

Take

$$x_1 = \sqrt{-2 \log \xi_1} \cos 2\pi \xi_2$$

$$x_2 = \sqrt{-2 \log \xi_1} \sin 2\pi \xi_2$$

or

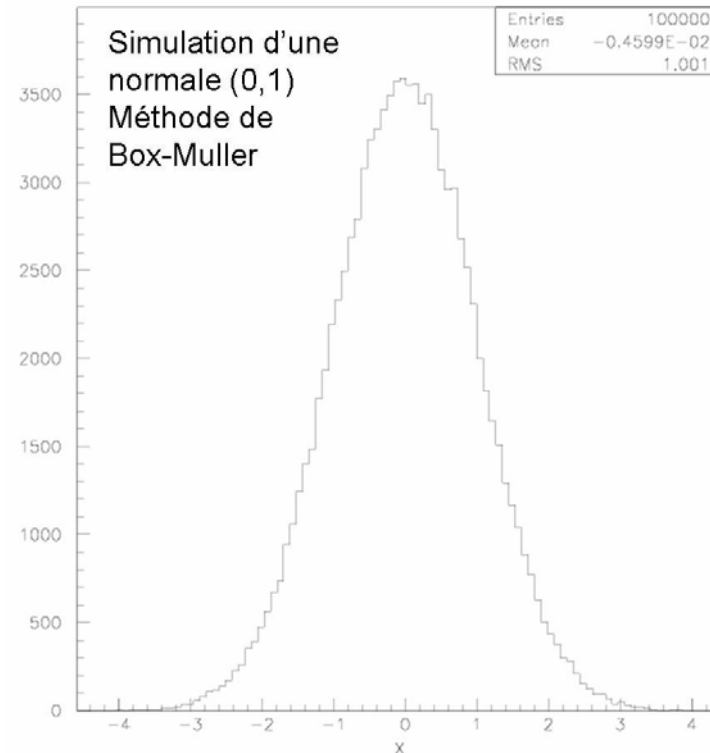
$$\xi_1 = e^{-\frac{(x_1^2 + x_2^2)}{2}}$$

$$\xi_2 = \frac{\arg \operatorname{tg} \left( \frac{x_2}{x_1} \right)}{2\pi}$$

$$f(x_1, x_2) = \begin{vmatrix} \frac{\partial \xi_1}{\partial x_1} & \frac{\partial \xi_1}{\partial x_2} \\ \frac{\partial \xi_2}{\partial x_1} & \frac{\partial \xi_2}{\partial x_2} \end{vmatrix} f(\xi_1, \xi_2) \quad \text{with} \quad f(\xi_1, \xi_2) = f(\xi_1) f(\xi_2) = 1$$

$$f(x_1, x_2) = \frac{1}{2\pi} e^{-\frac{1}{2}(x_1^2 + x_2^2)} = \frac{1}{\sqrt{2\pi}} e^{-\frac{1}{2}x_1^2} \frac{1}{\sqrt{2\pi}} e^{-\frac{1}{2}x_2^2} = f(x_1) f(x_2)$$

$x_1$  and  $x_2$  are independent and distributed following  $N(0,1)$



## Non-uniform continuous random numbers generators : simple acceptance/rejection



Generate  $x$  following  $f(x)$  on  $[a, b]$

$h(x) = 1/(b-a)$  uniform on  $[a, b]$

$\alpha = f_{max} \times (b-a) \Rightarrow \alpha h(x) = f_{max} \geq f(x)$  on  $[a, b]$

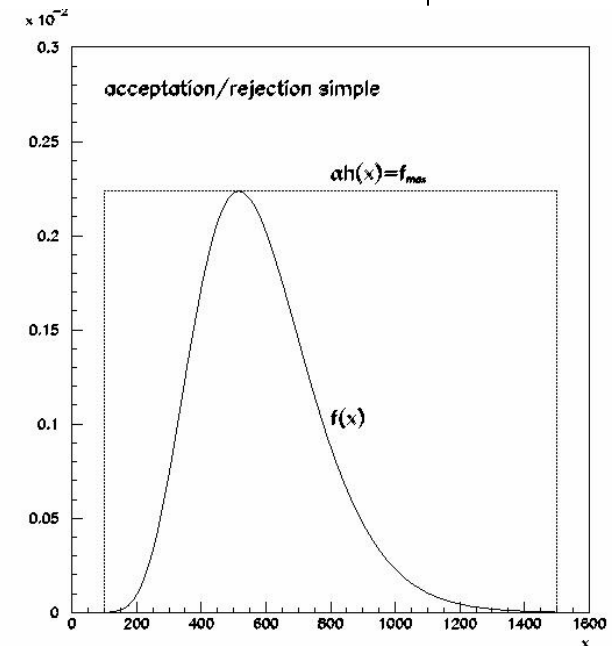
**Algorithm:**

- generate  $\xi_1$  and  $\xi_2$  on  $[0, 1]$
- $x = a + \xi_1 \times (b - a)$
- accept  $x$  if  $\xi_2 < \frac{f(x)}{\alpha h(x)} = \frac{f(x)}{f_{max}}$

Efficiency (number of  $\xi$  to get one  $x$ )  $\varepsilon = 2 \frac{\int_a^b \alpha h(x) dx}{\int_a^b f(x) dx} = 2\alpha$

$\varepsilon$  may become very small if  $f(x)$  has long tails.

If  $a, b = \pm\infty$  : tails must be cut



## Non-uniform continuous random numbers generators : acceptance/rejection adapted to the sample



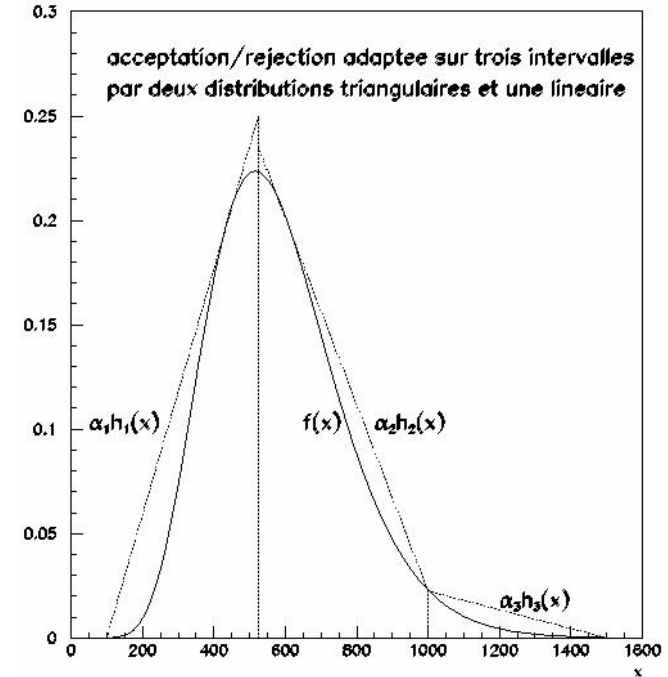
$f(x)$  limited on a series of  $K$  intervals  $[a_{k-1}, a_k]$  by  $\alpha_k h_k(x) \times 10^{-2}$

with  $\alpha_k > 1 \Rightarrow \alpha_k h_k(x) \geq f(x)$  on  $[a_{k-1}, a_k]$

$h_k(x)$  a PDF allowing cumulative method

### Algorithm:

- $p_j = \frac{\alpha_j}{\sum_{i=1}^n \alpha_i}$ ,  $P_j = \frac{\sum_{i=1}^j \alpha_i}{\sum_{i=1}^n \alpha_i} \quad \forall j = 1, n$
- generate  $\xi_1, \xi_2$  on  $[0, 1]$
- select interval  $k = [a_{k-1}, a_k] \Rightarrow P_{k-1} \leq \xi < P_k$
- generate  $x$  sur  $[a_{k-1}, a_k]$  following  $h_k(x)$
- accept  $x$  si  $\xi \leq f(x) / \alpha_k h_k(x)$



### Example: gaussian distribution

$$f(x) = \frac{1}{\sqrt{2\pi}} e^{-\frac{x^2}{2}} \leq \alpha_k h_k(x) \quad k = 1, 2$$

$k$	$[x]$	$\alpha_i$	$h_i(x)$
1	$[0-1]$	$\frac{1}{\sqrt{2\pi}}$	1
2	$[1-\infty]$	$\frac{1}{2\sqrt{2\pi}}$	$2e^{-2(x-1)}$

